



DIAMOND BEAM MONITOR AND LUMINOSITY MEASUREMENTS

October 2018

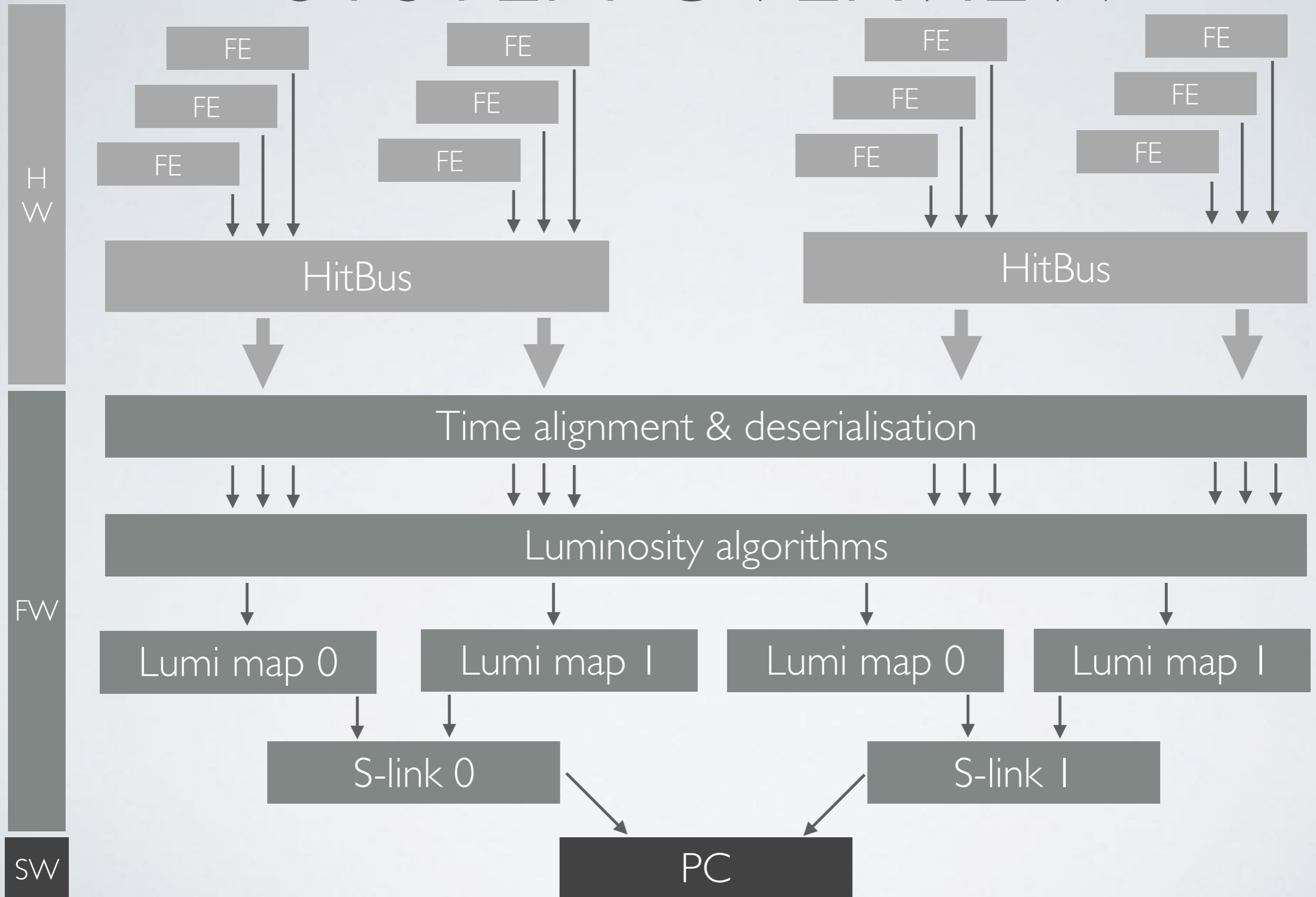
Jožef Stefan Institute
Boštjan Maček

OVERVIEW

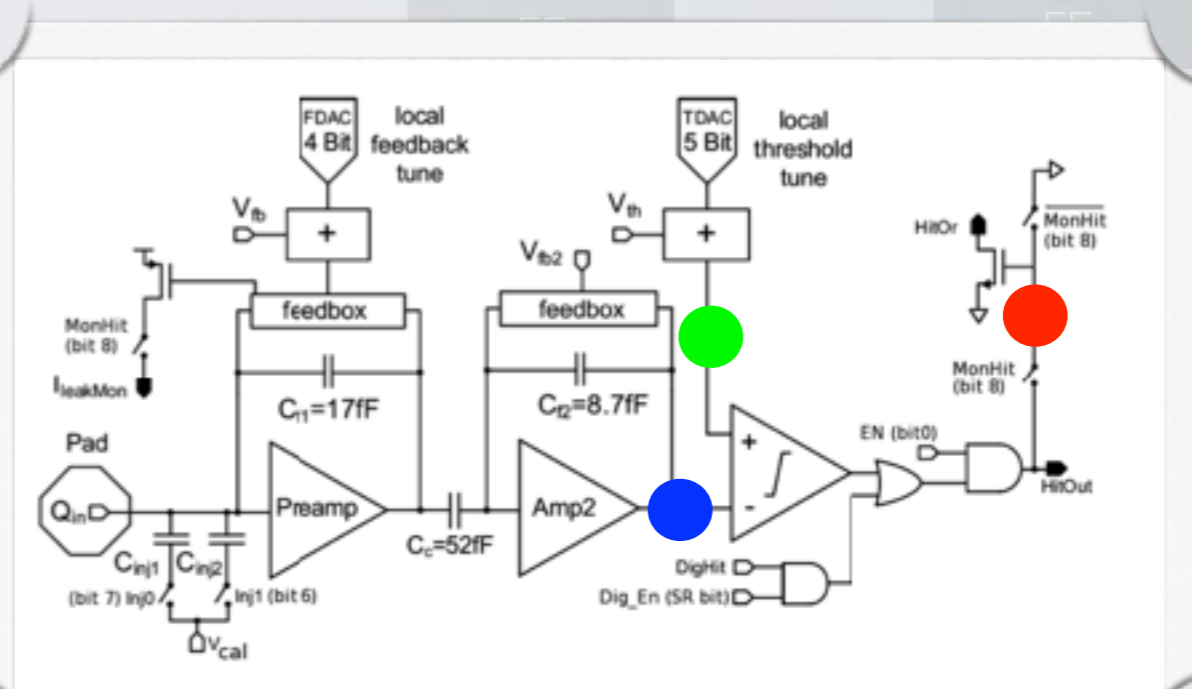
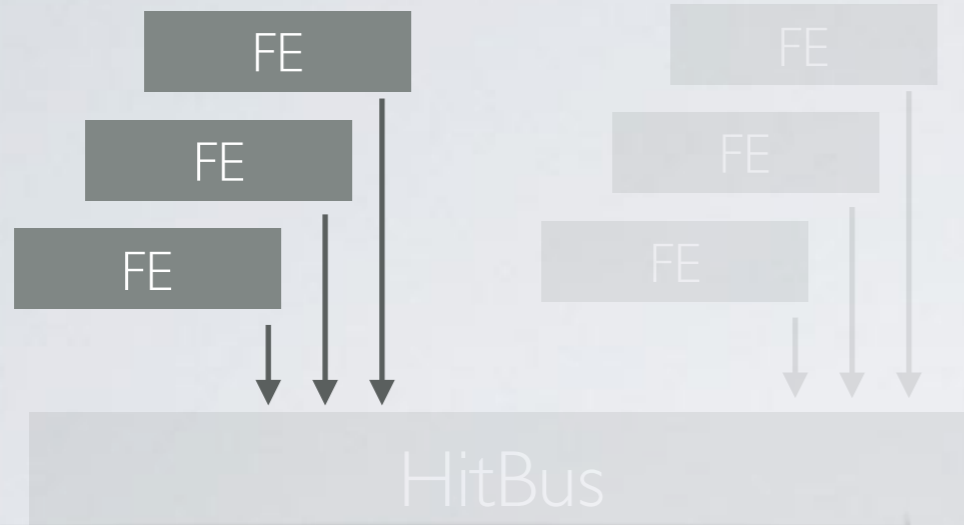
- luminosity readout system
- data format & available information
- system tests
- collected data & analysis
- conclusion

SYSTEM OVERVIEW

SYSTEM OVERVIEW



SIGNAL FORMATION

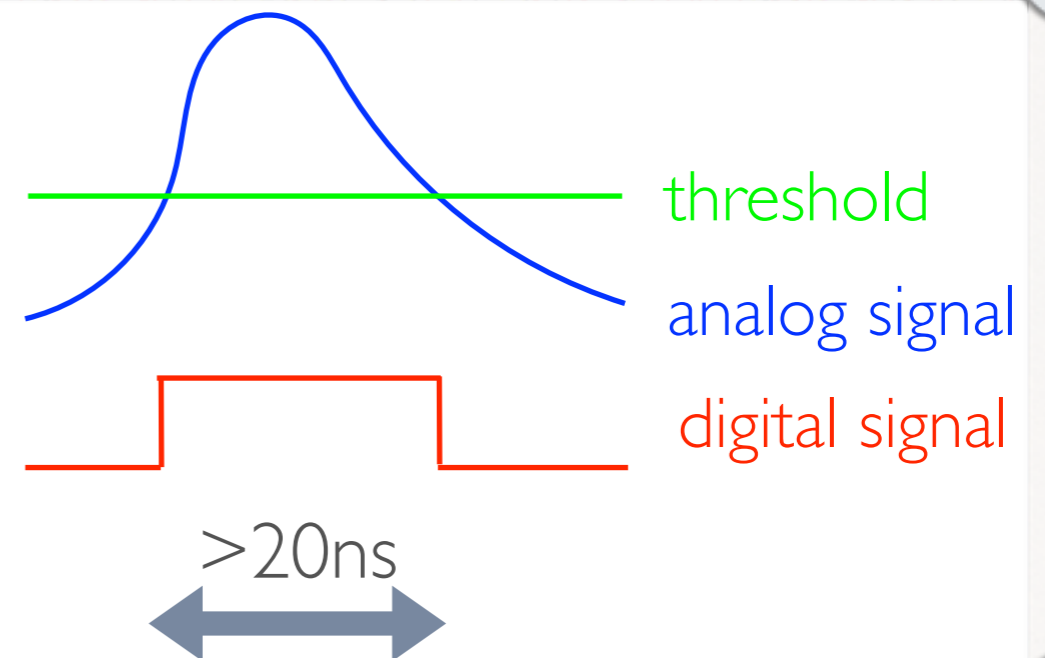


- **analog circuitry:** pixels are completely independent and each has its own time-over-threshold circuit
- two outputs:
 - **HitOr** is common for all pixels in the chip (one output signal per chip), but contribution from each pixel **can be masked**
 - **HitOut** is used for final digitisation

ment & deserialisation

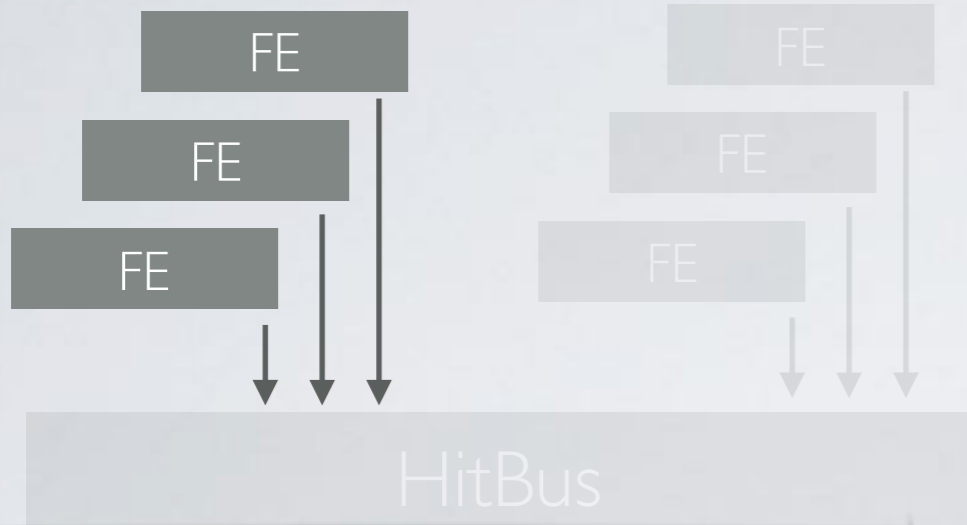
osity alg

p |



PC

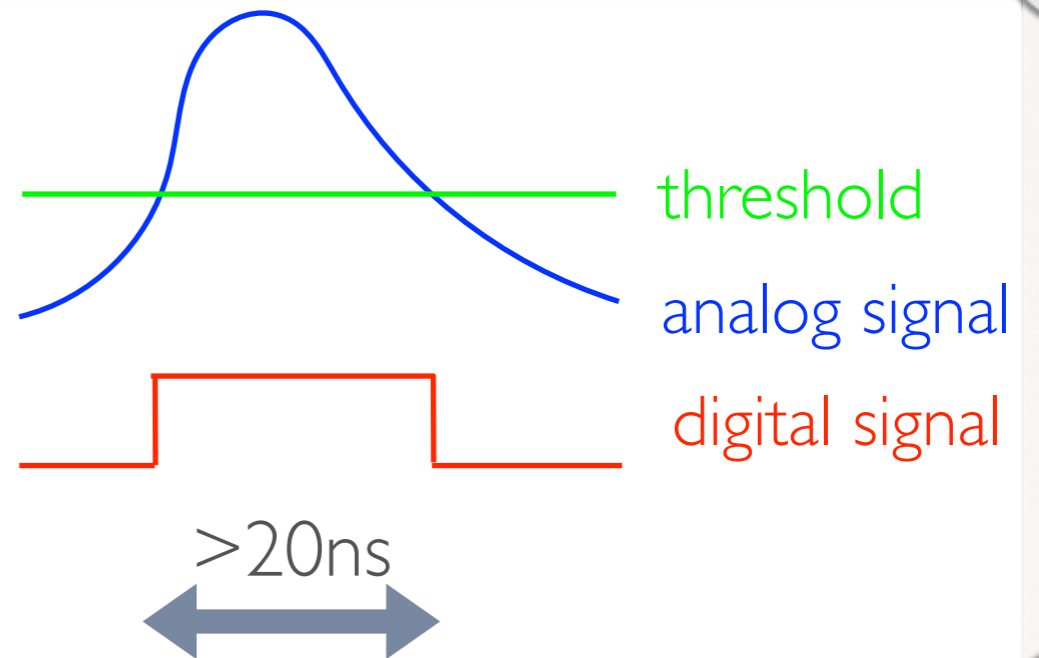
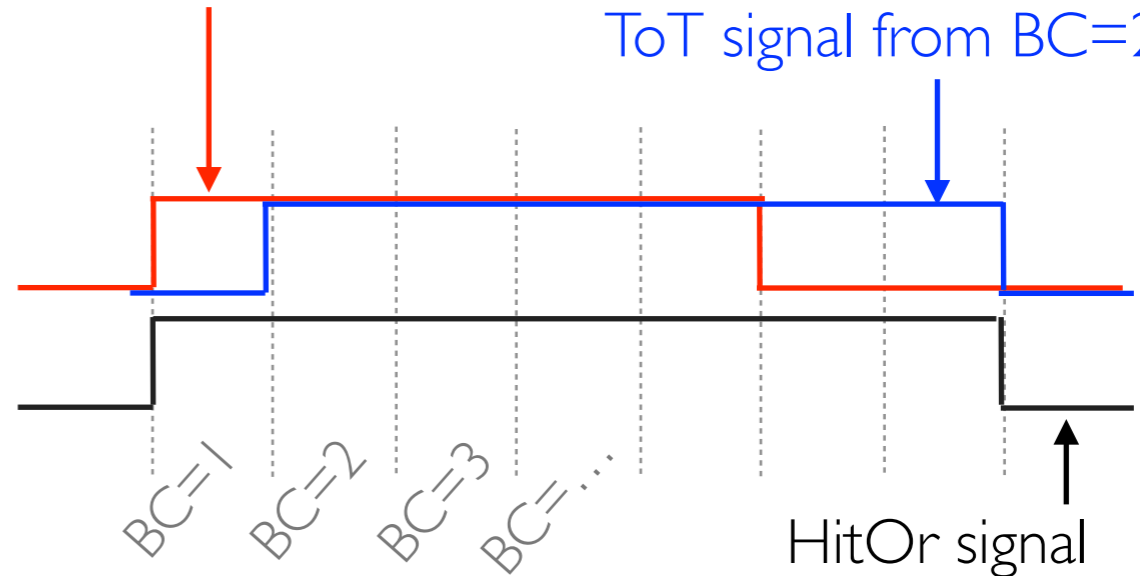
MAIN CHALLENGE



- long ToT signals (1-16 BCs) cause **digital pileup**
- no problem at low luminosity, but with increasing $\langle \mu \rangle$ pile-up dominates over statistical error
- two direct handles possible:
 - different ToT calibration (same charge = shorter pulse)
 - reducing probability for HitOr signal by enabling smaller number of pixels (coupled with noise)

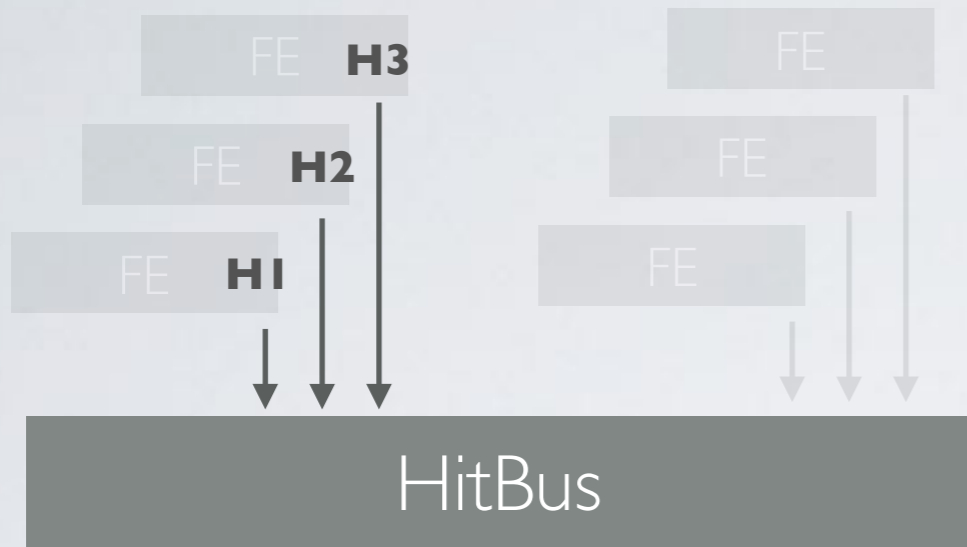
ToT signal from BC=1

ToT signal from BC=2



PC

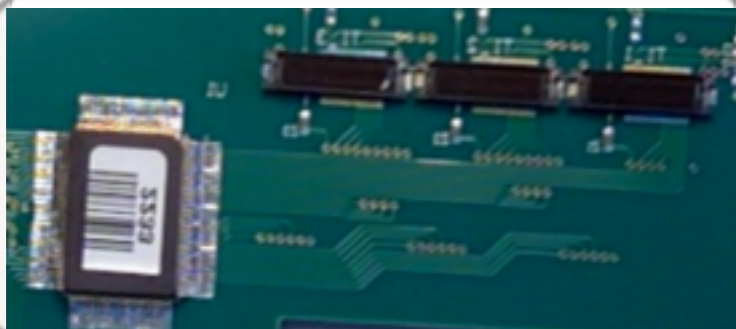
HITBUS



- transparent for luminosity measurement
- simply streams the the HitOr data on 320MHz link
- stream BPM encoded to provide robustness

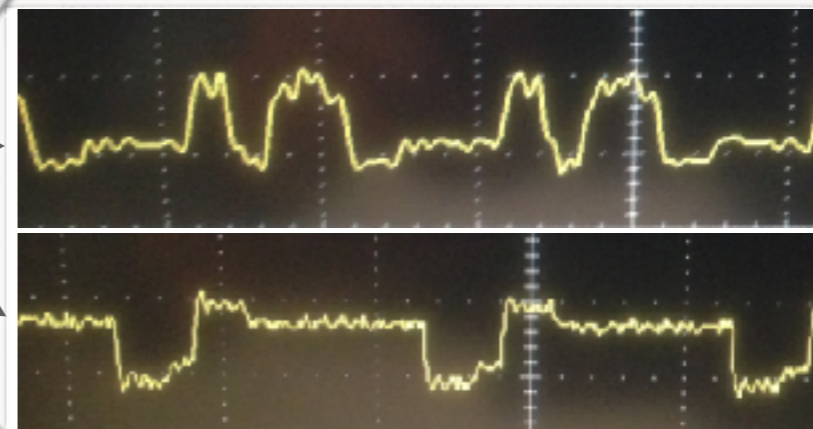


- has two such streams independent stream
- data streamed out of detector to the counting room
- has other modes of operation



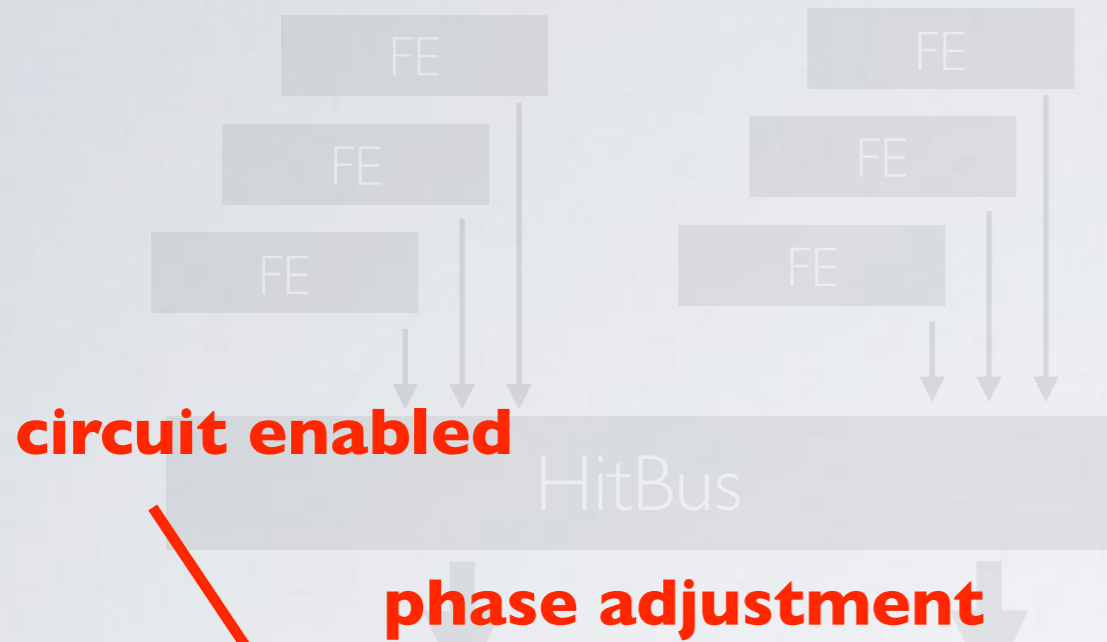
alignme
↓ ↓
Luminos

- one mode is to output fixed data pattern in sync with input clock
- used for time alignment



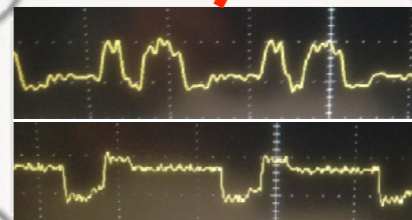
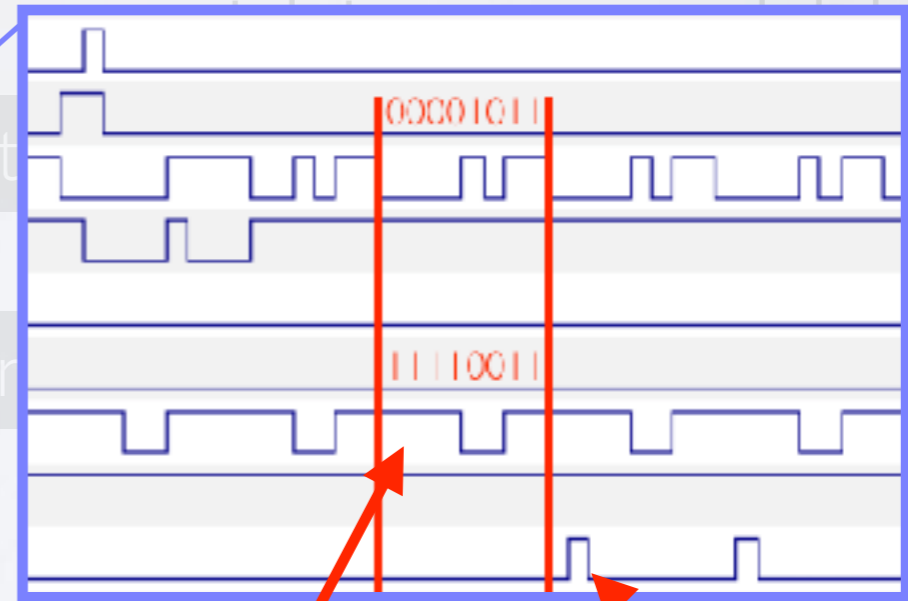
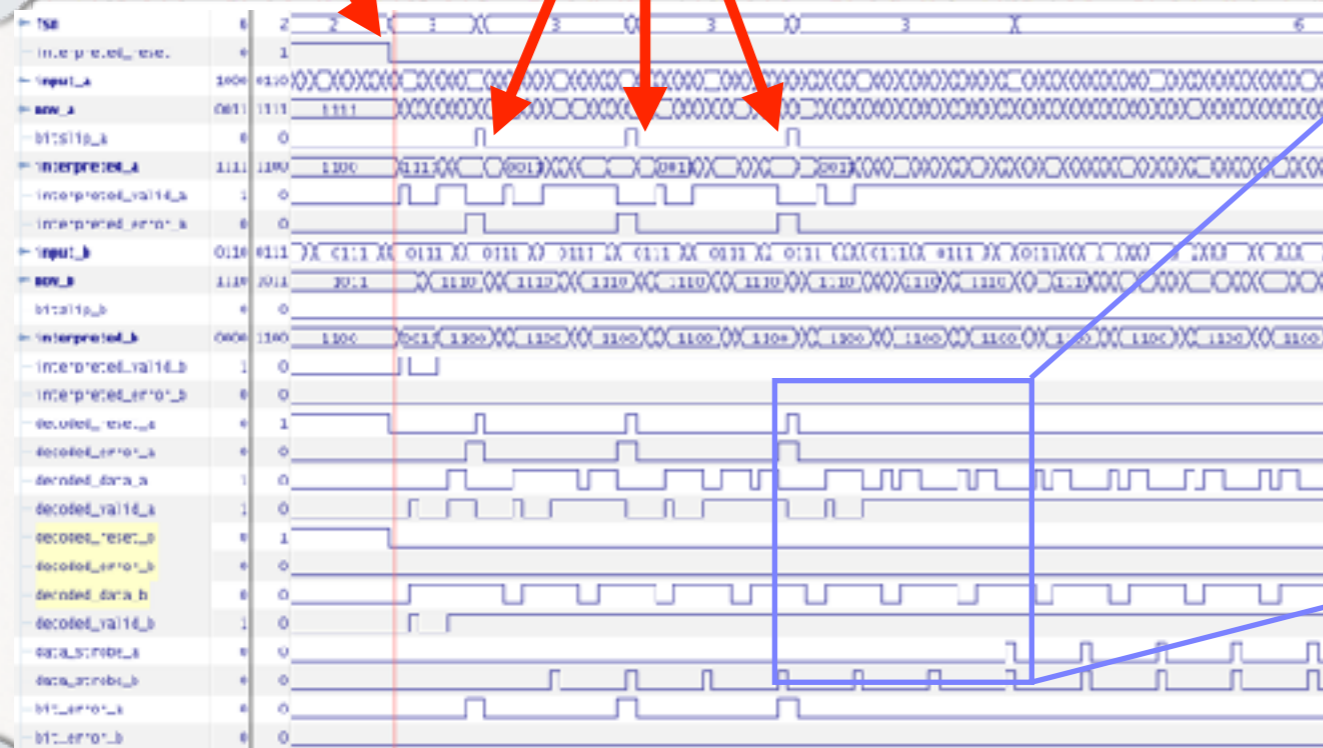
PC

DATA RECEPTION



- main part is deserialisation - providing parallel bus of HitOr bits for each BC
- technical challenges:
 - time align the serial stream
 - error correction on the data line



Time alignment & deserialisation



DEAD-TIME MONITORING

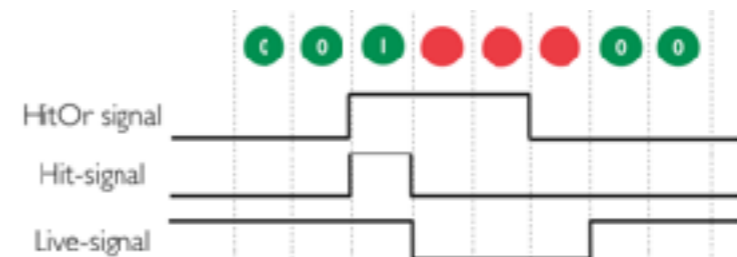
FE

FE

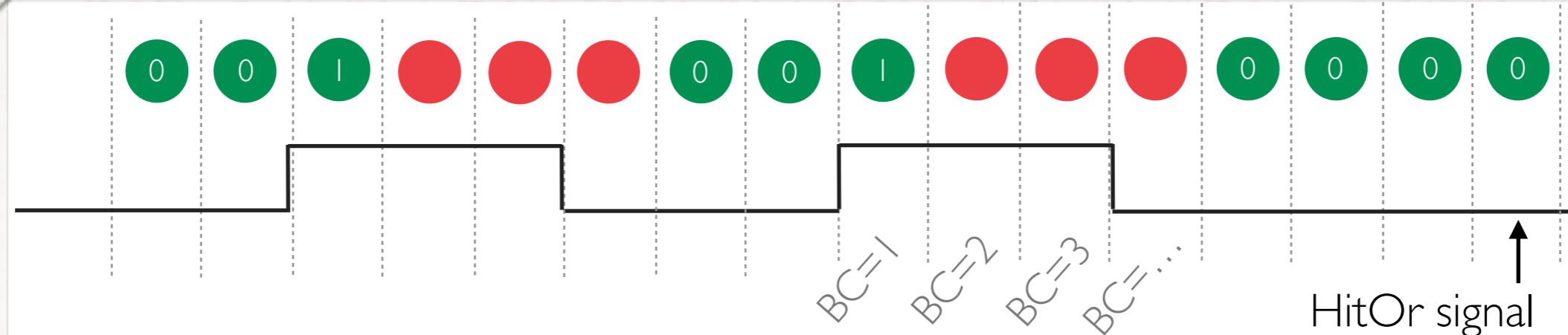
- we have 12 HitOr signals from the modules
- from FE a challenge was inherited - dead-time & pileup
- information is carried by the rising edges 
- need to measure the dead-time 

FE

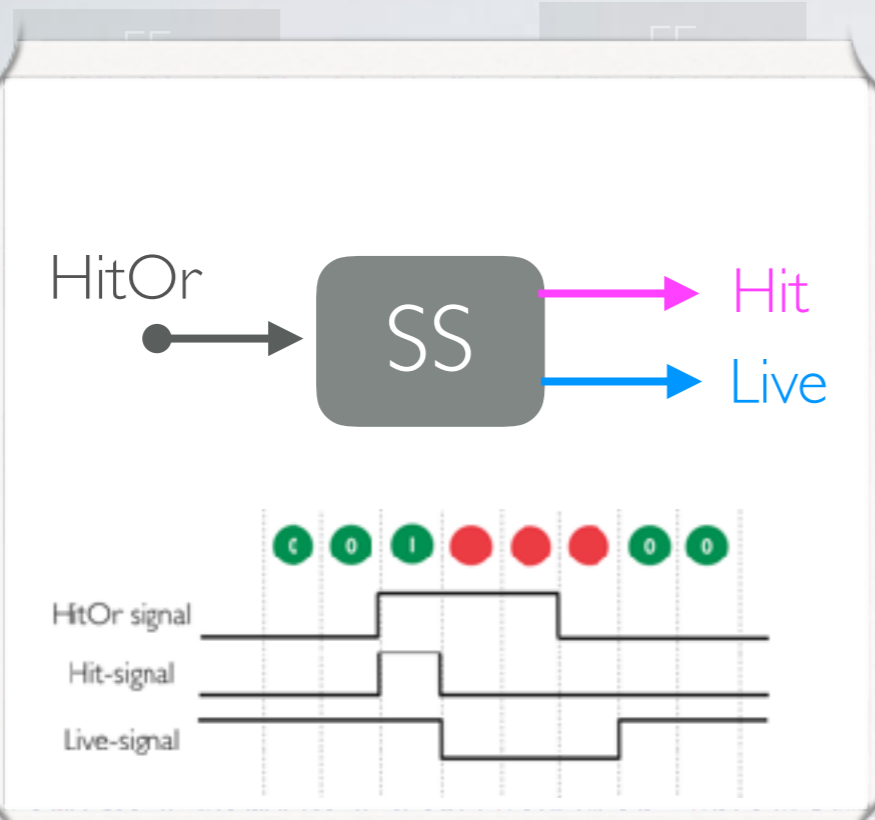
FE



Luminosity algorithms



LUMINOSITY



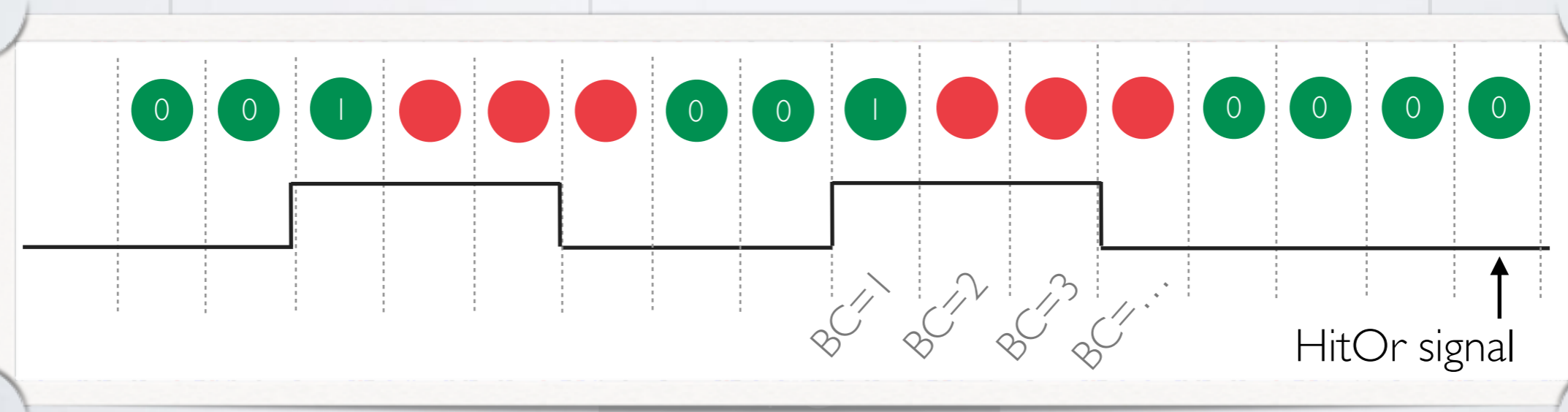
- given 'hit' and 'live' signals for a certain BC one can measure event rate as:

$$r = \frac{1}{(0 + 1)}$$

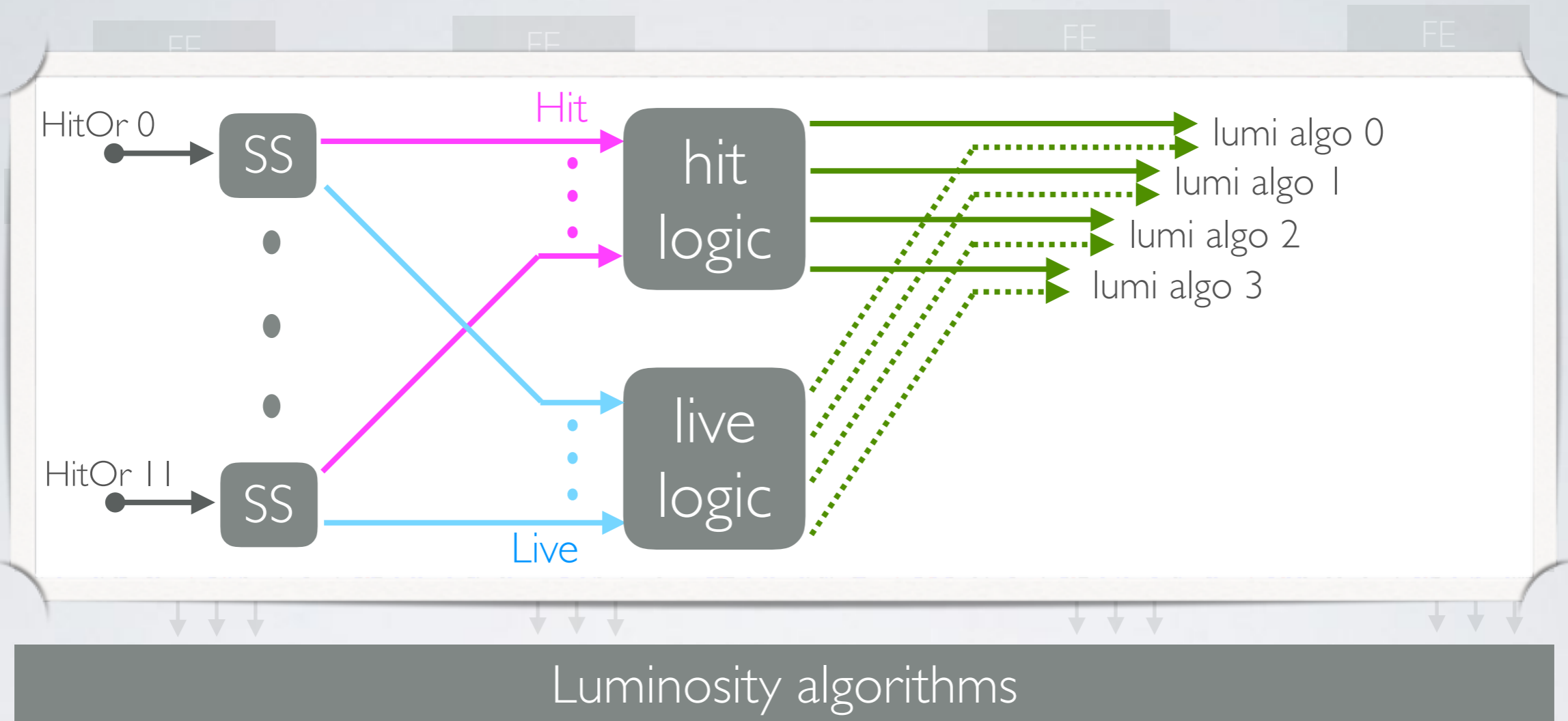
- requires two counters instead of one - doubling the resources required

ent & deserialisation

Luminosity algorithms



COMBINING SENSORS

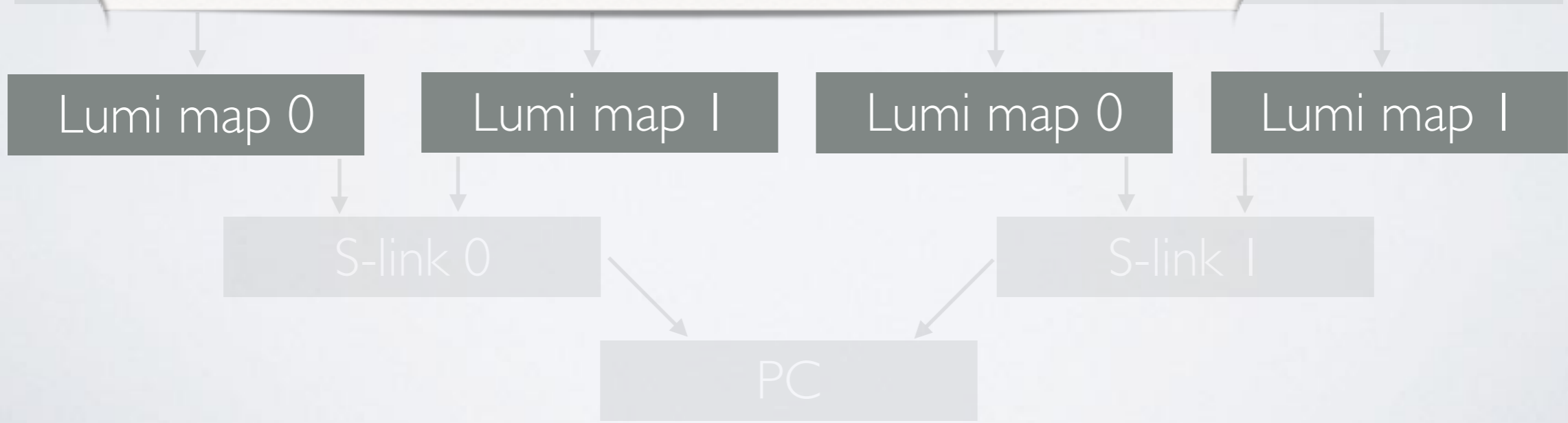
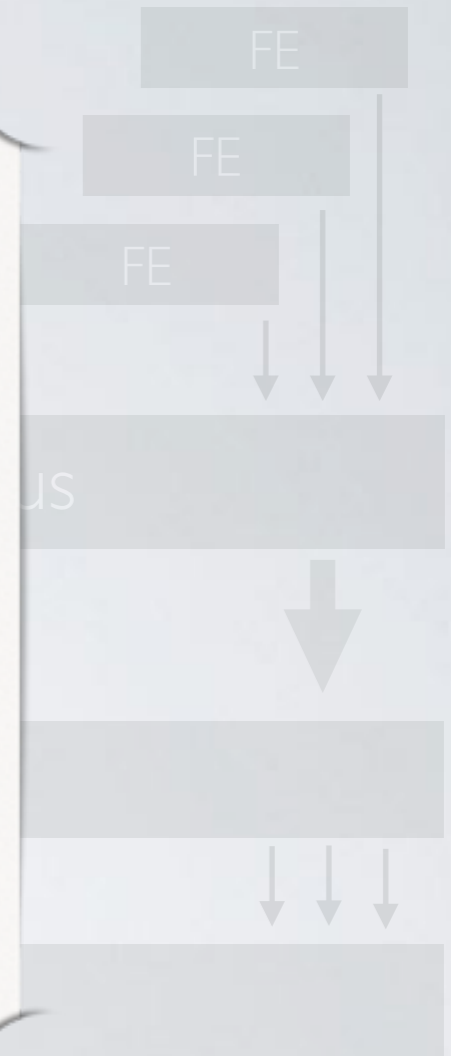


- logic can be uploaded without FW modification
- any combinatorial logic expression with up to 12 inputs possible
- 4 luminosity algorithms available on each FPGA

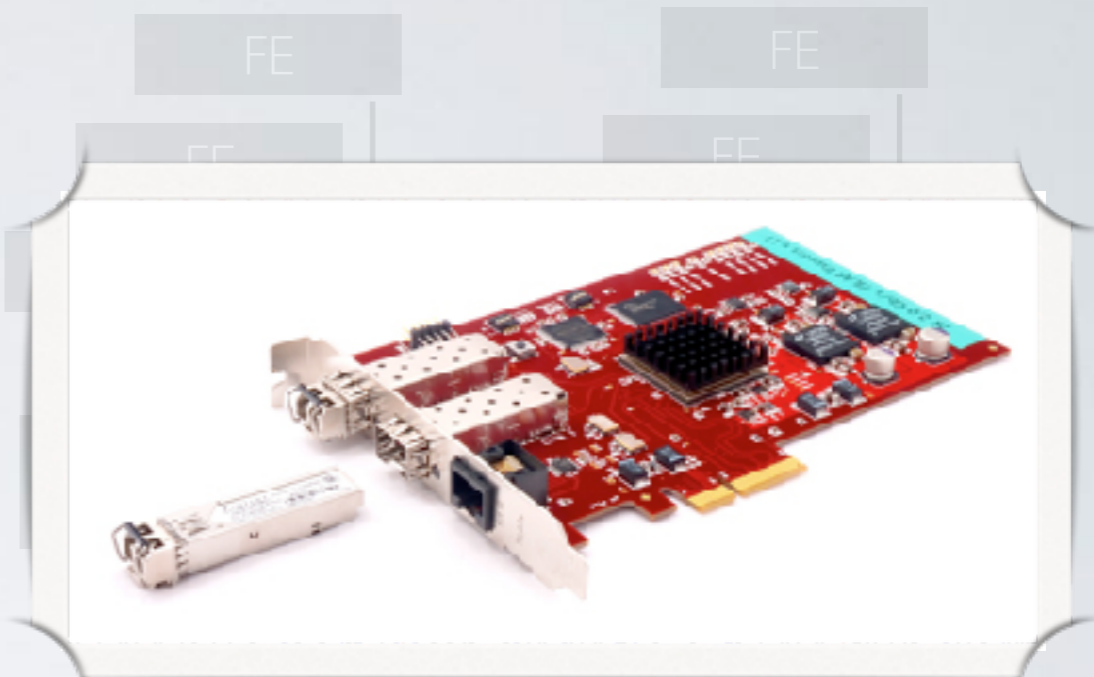
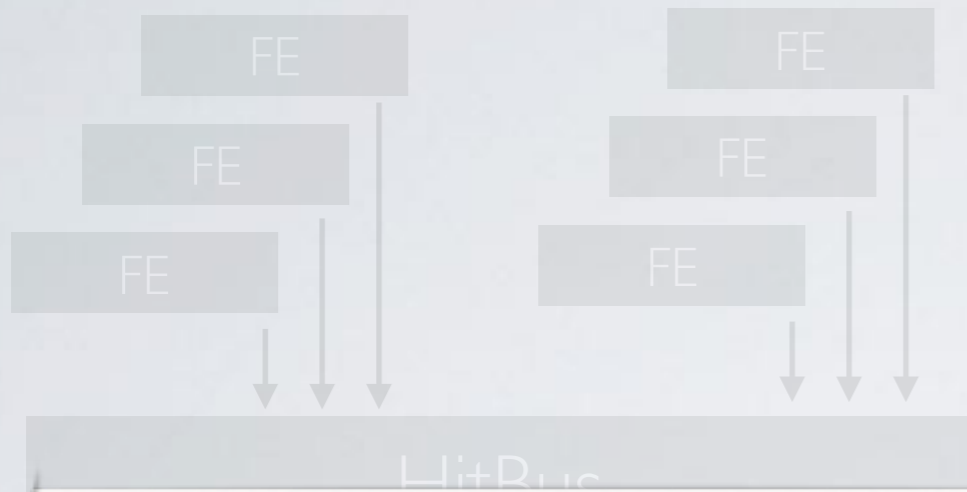


LUMINOSITY MAPS

- 4 luminosity maps - matches the number of algorithms
- histograms both 'live' and 'hit' signals for all BCIDs
- extra info:
 - Orbit counter
 - error checking circuit with the counter
 - unique ID
- no dead-time during the readout
- 16-bit accumulating counters - limits the readout to rates higher than 0.3 Hz



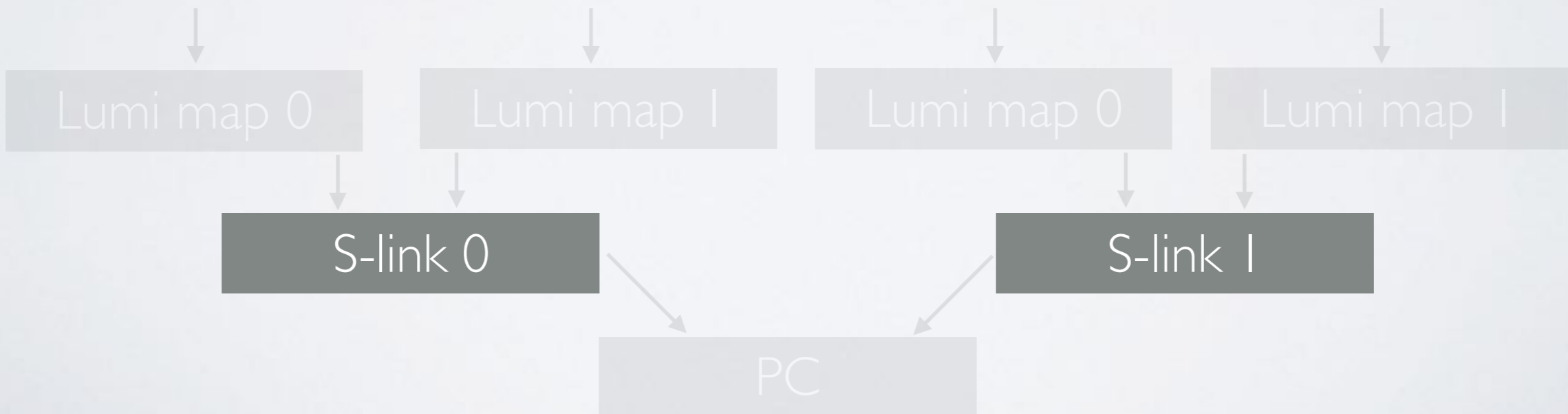
S-LINK



- 2 S-link channels per FPGA
 - #0 hosts lumi maps 0 and 1
 - #1 hosts lumi map 2 and 3
- TILAR card as data receiver on the PC side

deserialisation

Luminosity algorithms



SOFTWARE WORLD

- A dedicate software was developed for readout and processing of the data
- general purpose framework CatShell
 - <https://gitlab.cern.ch/bmacek/CatShell>
- DbmShell for DBM specific infrastructure parts
 - <https://gitlab.cern.ch/bmacek/DbmShell>
 - DBM hardware specifics
- common lumi infrastructure LumiShell
 - <https://gitlab.cern.ch/bmacek/LumiShell>
 - luminosity processing



DATA & TESTS

CLOSE LOOK AT THE DATA

[LumiMap32] Lumi map 32-bit for 3564 BCIDs.

Data source : 1

FPGA source : south

Stream ID : 0

Map : 1

Error count : 0

Start orbit : 999305637

End orbit : 999329638

Start time (UTC) : 2018-09-22 08:24:40.130799

End time (UTC) : 2018-09-22 08:24:42.265081

Counters :

0:	[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],
5:	[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],
10:	[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],
15:	[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],
20:	[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],
25:	[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],
30:	[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],[24001,	0],

....

data for single BC

ID of the luminosity algorithm

$999329638 - 999305638 = 24001$ orbits $\sim 2s$

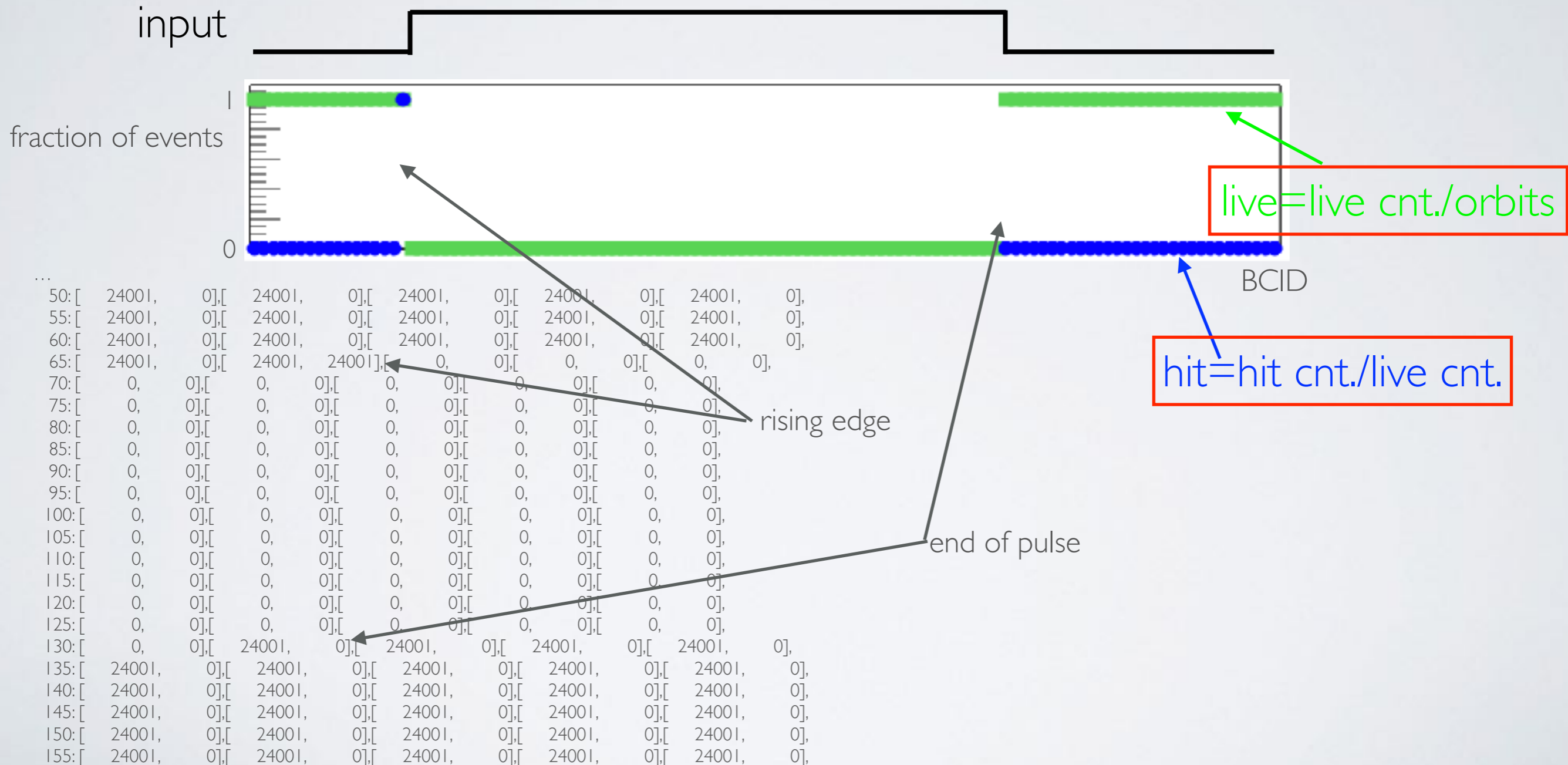
kernel timestamps for book keeping

hit counter

live counter

TESTING THE SYSTEM

- first testing is always with internal number generator, instead of HitOr
- s pattern of repetitive digital pulses is re-played in a same manner on each ORBIT



ANALYSIS

ALGORITHM SETUP-I

- running only side C
- only HB-34 used
- for first data an inclusive set of algorithms was configured



FPGA	Stream	Map	Algorithm	Logic
South	0	0	0	or*(FE6, FE7, FE8, FE9, FE10, FE11) - everything
		1	1	FE10 - single module
	1	0	6	or*(FE6, FE7, FE8) - one telescope (M3)
		1	7	or*(FE9, FE10, FE11) - one telescope (M4)

*special setup: live-algorithms modified
(pinpointing data, no measurement)

normally: live if all live (and)  *special: live if either live (or)*

RUN WITHOUT FE

- first collision run: DBM was un-configured (data tag: 2018_09_23_12_43_01)
- expected to see nothing - hits observed

Algorithms	
0	everything
1	single module
6	M3
7	M4

```
1730: [ 24001, 0],[ 24001, 0],[ 24001, 0],[ 24001, 0],[ 24001, 0],
1735: [ 24001, 0],[ 24001, 0],[ 24001, 0],[ 24001, 0],[ 24001, 0],
1740: [ 24001, 0],[ 24001, 0],[ 24001, 0],[ 24001, 0],[ 24001, 0],
1745: [ 24001, 0],[ 24001, 0],[ 24001, 0],[ 24001, 0],[ 24001, 0],
1750: [ 24001, 1],[ 24000, 0],[ 24000, 0],[ 24000, 0],[ 24001, 0],
1755: [ 24001, 0],[ 24001, 0],[ 24001, 0],[ 24001, 0],[ 24001, 0],
1760: [ 24001, 0],[ 24001, 0],[ 24001, 0],[ 24001, 0],[ 24001, 0],
1765: [ 24001, 0],[ 24001, 0],[ 24001, 0],[ 24001, 0],[ 24001, 0],
1770: [ 24001, 0],[ 24001, 0],[ 24001, 0],[ 24001, 0],[ 24001, 0],
```

hit - 3 BC long

RUN WITHOUT FE

- first collision run: DBM was un-configured (data tag: 2018_09_23_12_43_01)
- expected to see nothing - hits observed

Algorithms	
0	everything
1	single module
6	M3
7	M4

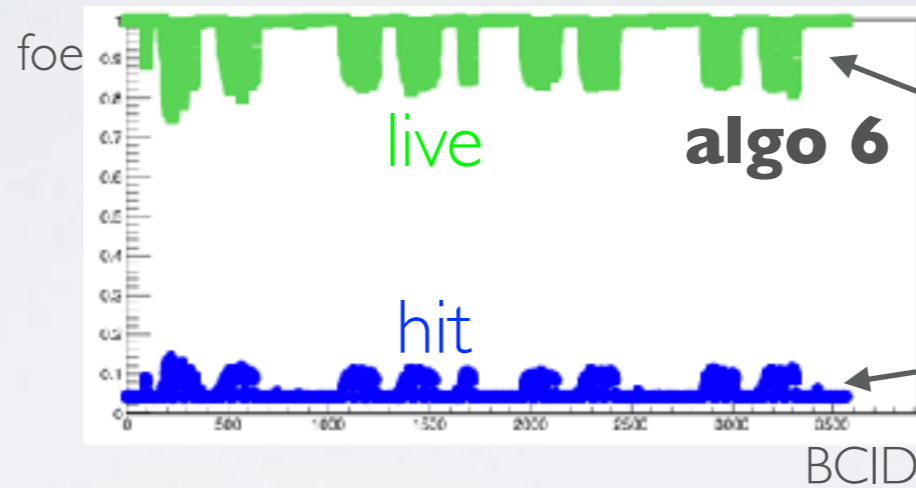
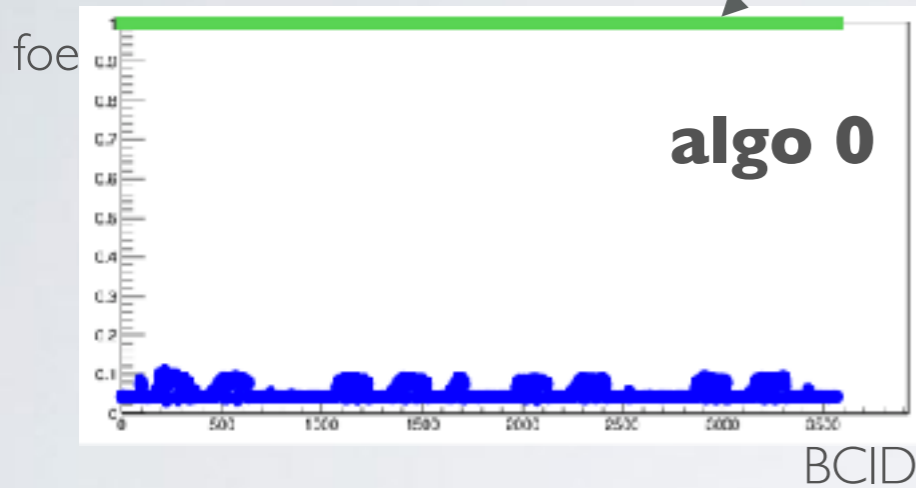
Orbit number	Algorithms	BCID	Length
2089983080	0,1,7	861	1
2091495143	0,6	863	?
2094879284	0,6	398	?
2101023540	0,6	2188	?
2104119669	0,6	2188	? BCIDs repeat !!
2105583730	0,6	863	? -
2107047791	0,6	339	? some systematics
2109831907	0,6	2188	?
2111991997	0,1,7	1750	3

RUN WITH FE

Algorithms	
0	everything
1	single module
6	M3
7	M4

- first collision run with FEs configured (data tag: 2018_09_23_18_33_15)

inherits from map 7

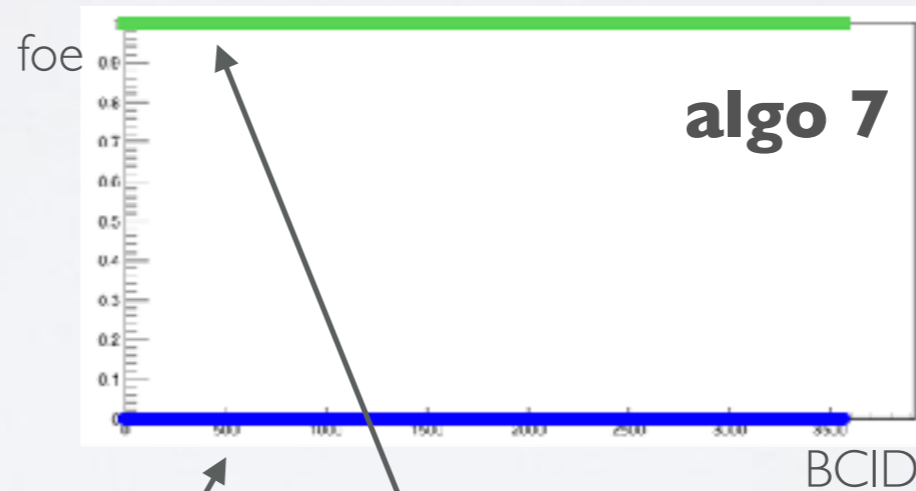


some coincidences of 3 HitOr signals being 0

hits in M3



can only be explained, by the HitOr signal being constantly high



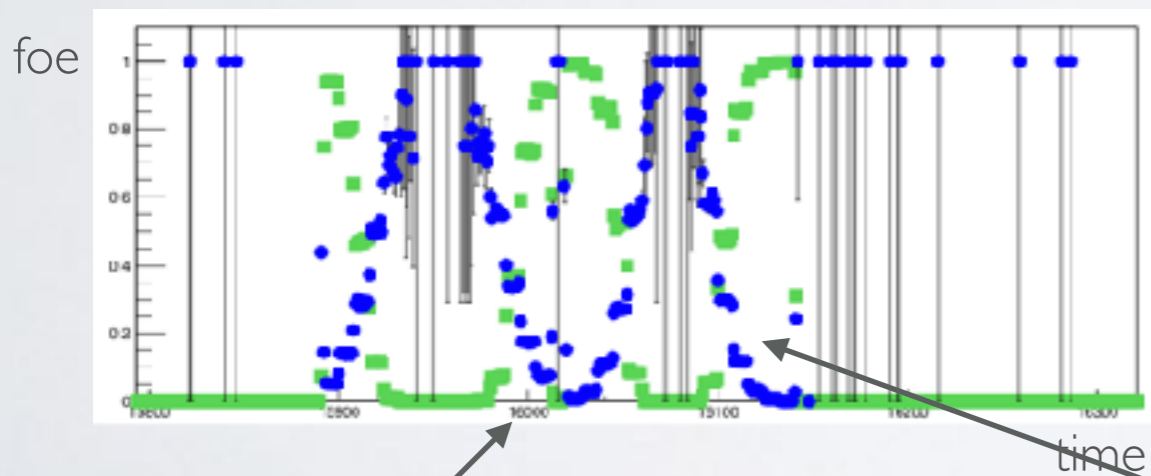
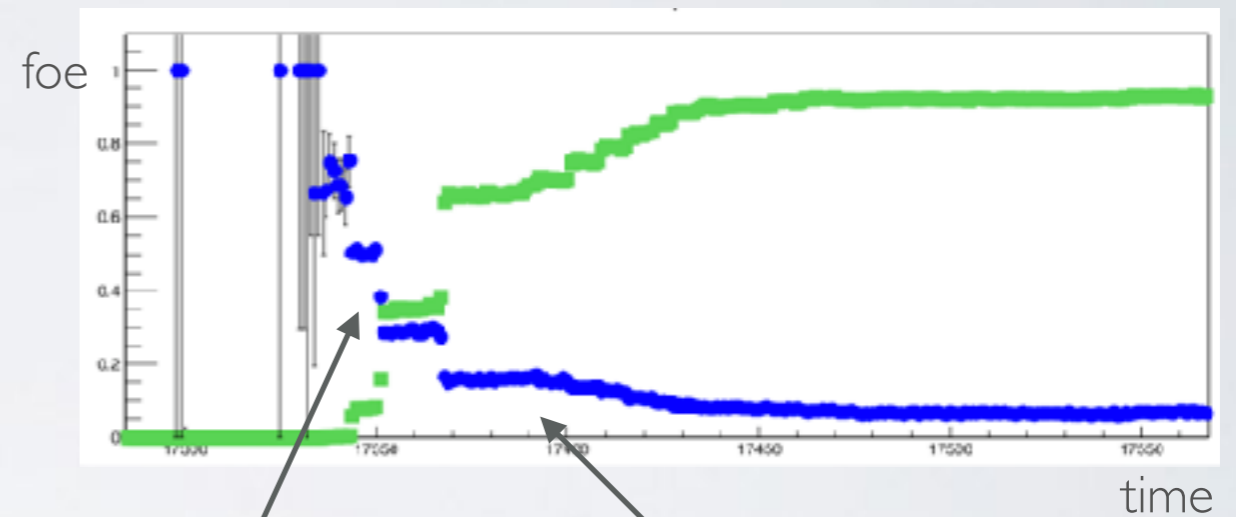
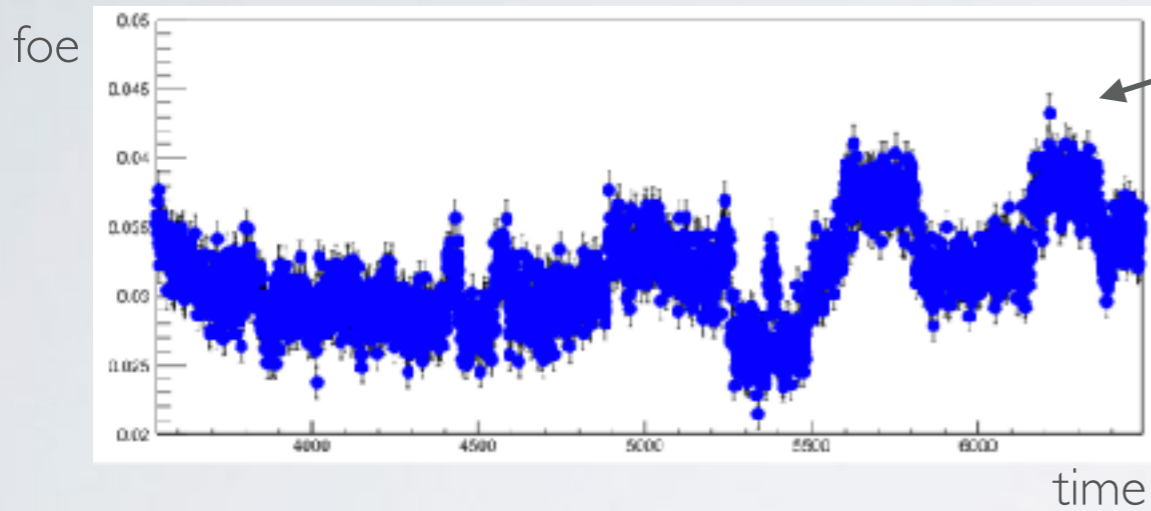
obviously HitOr signal for FE9 or FE10 const. = 0

no hits in M4

RUN WITH FE

- a single BCID=2400 chosen, algorithm 6 = M3 telescope
- two runs in this lumi recordings

IBL included us in timing scan



second run/fill

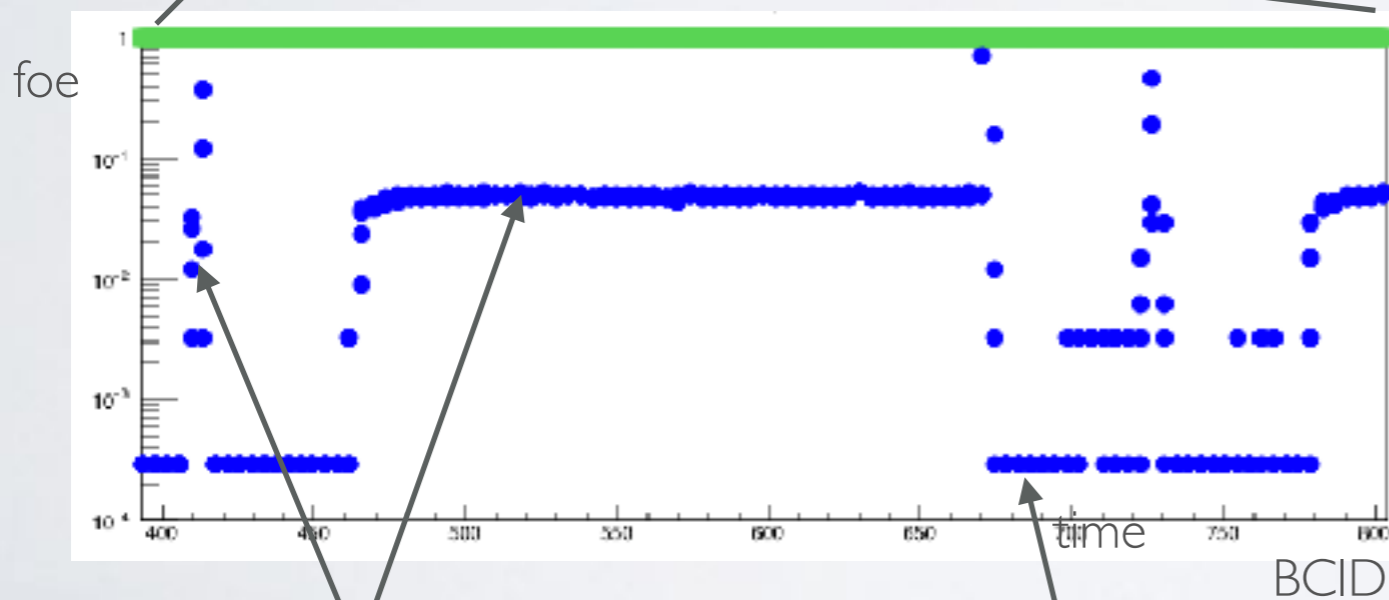
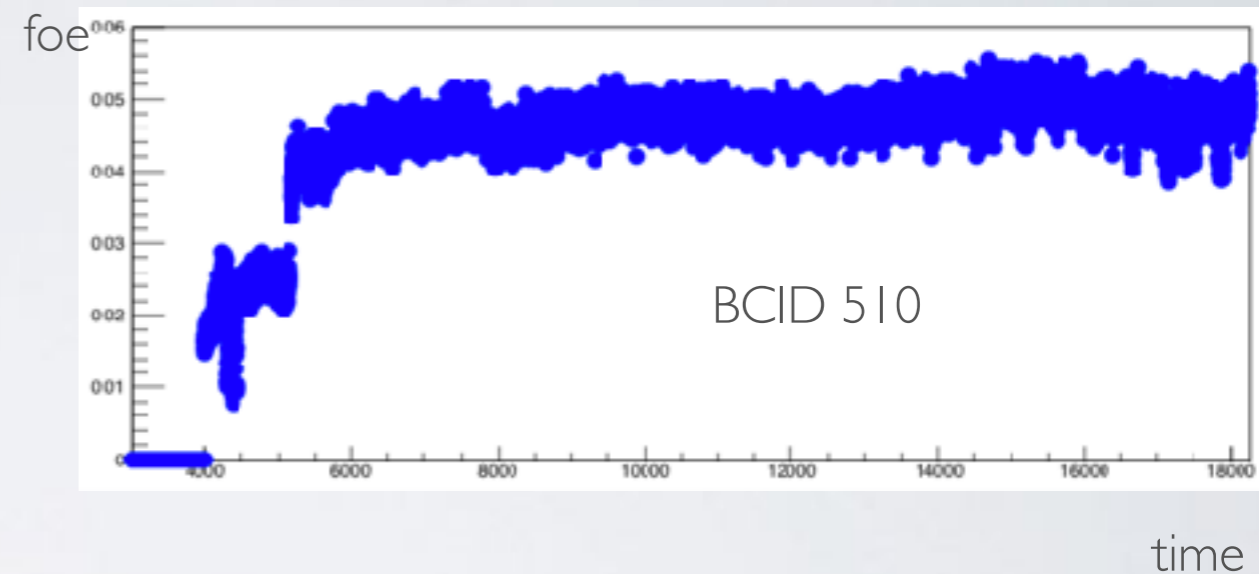
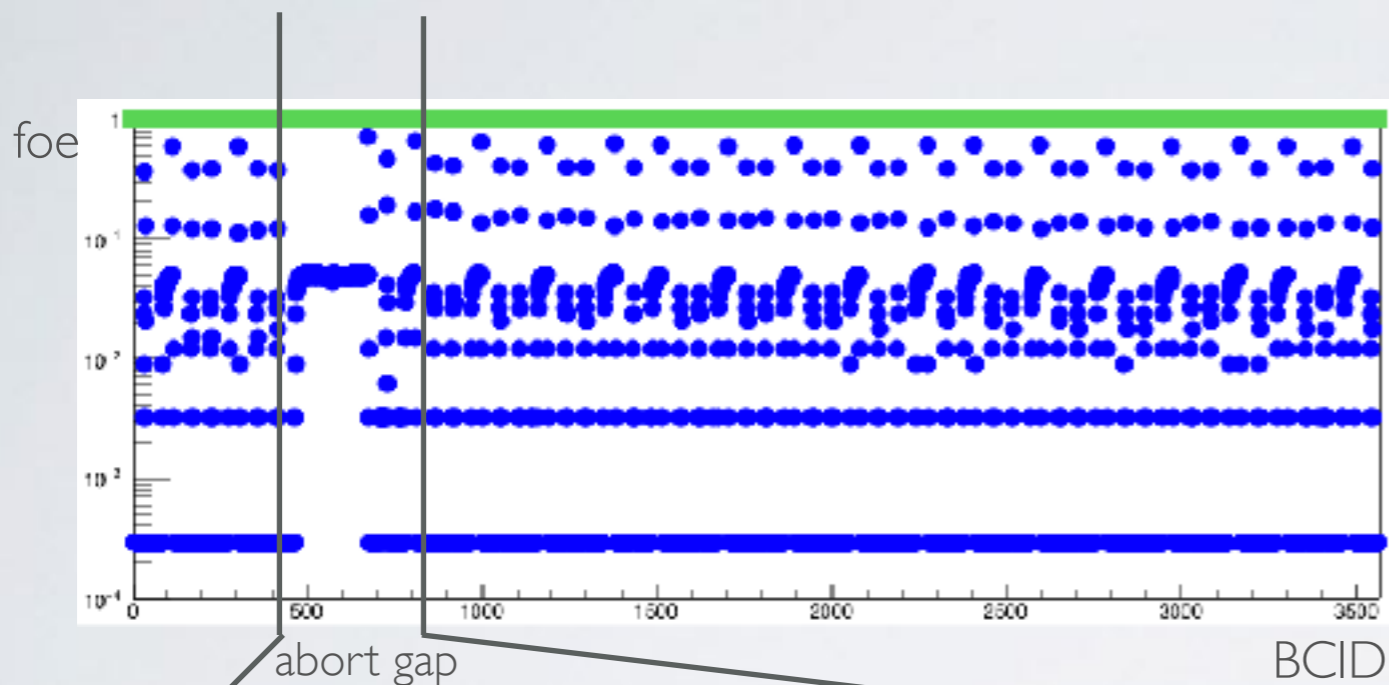
X,Y scans before the run

- counter quantisation seen
- error bars only for statistical error
- detector responding to pp collisions
- response sensible only when beams are not centred

saturation

RECORDING 2.

- recording containing two runs (data tag: 2018_09_24_13_24_51)



with pp collision

-

obvious saturation

signal only in between trains

single hit if any

ALGORITHM SETUP-2

- running only side C - only HB-34 used
- so far: M3 give some signal, M4 no signal
- trying to reduce acceptance - less inclusive algorithms



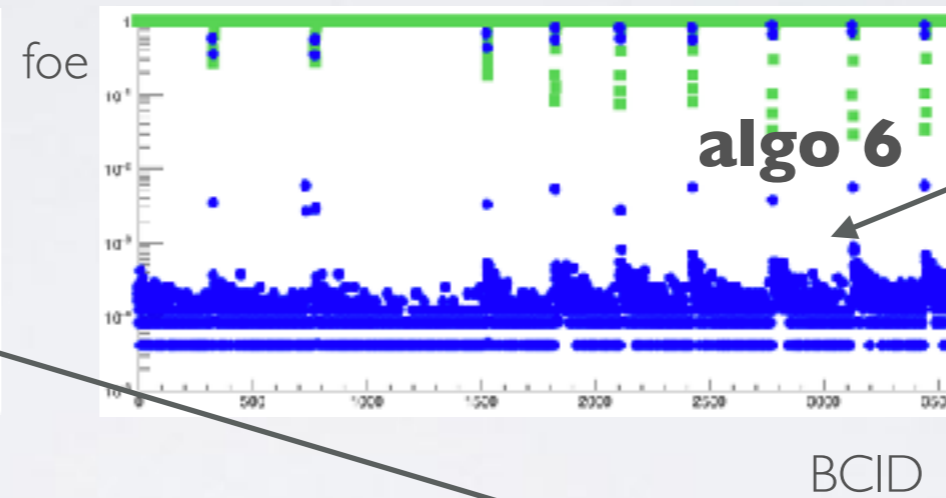
FPGA	Stream	Map	Algorithm	Logic
South	0	0	0	or*(FE6, FE7, FE8) - one telescope (M3)
		1	1	FE6 - single module
	1	0	6	FE7 - single module
		1	7	FE8 - single module

*no special setup: first measurements

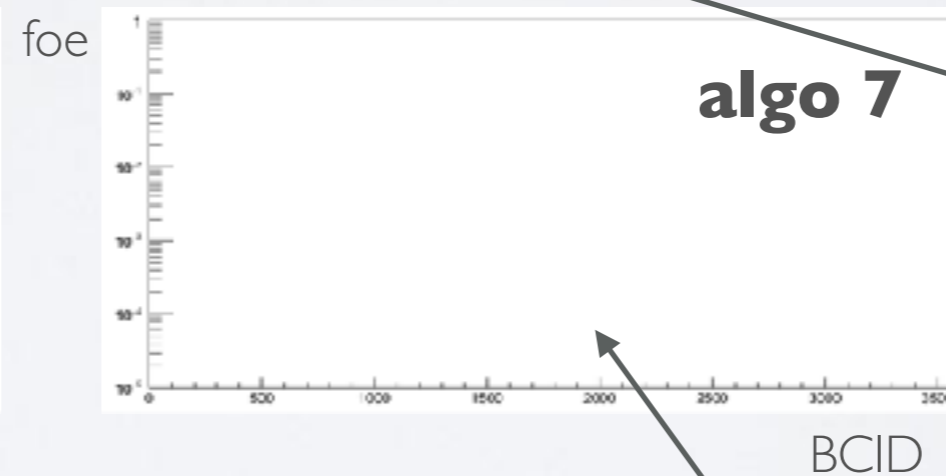
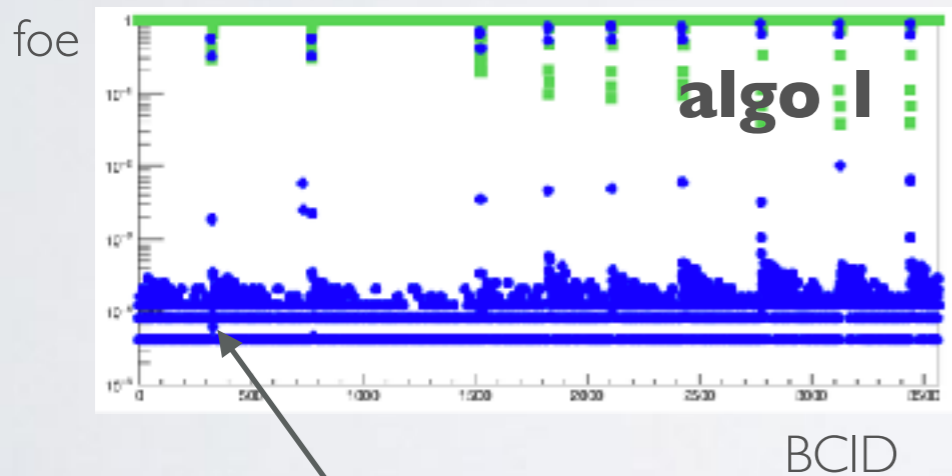
RECORDING 3.

- recording containing two runs (data tag: 2018_09_25_17_00_17)
- interesting because has 9 isolated collision bunches

Algorithms	
0	M3
1	single module F6
6	single module F7
7	single module F8



at this level F6 and F7 give consistent data



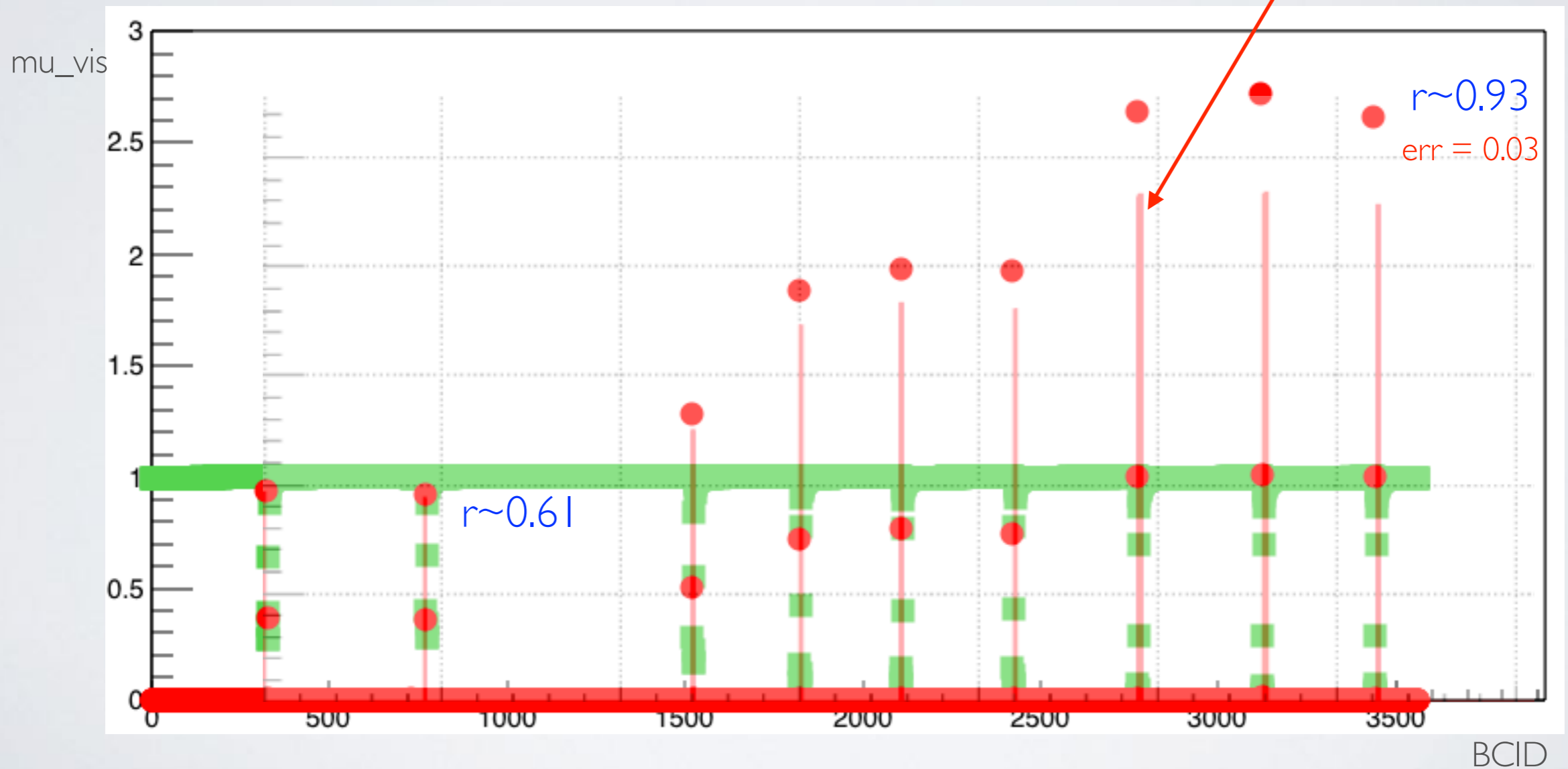
due to F8

noise rate hard to estimate due to tails and values at quantisation level

F8 non contributing any data since un-configured

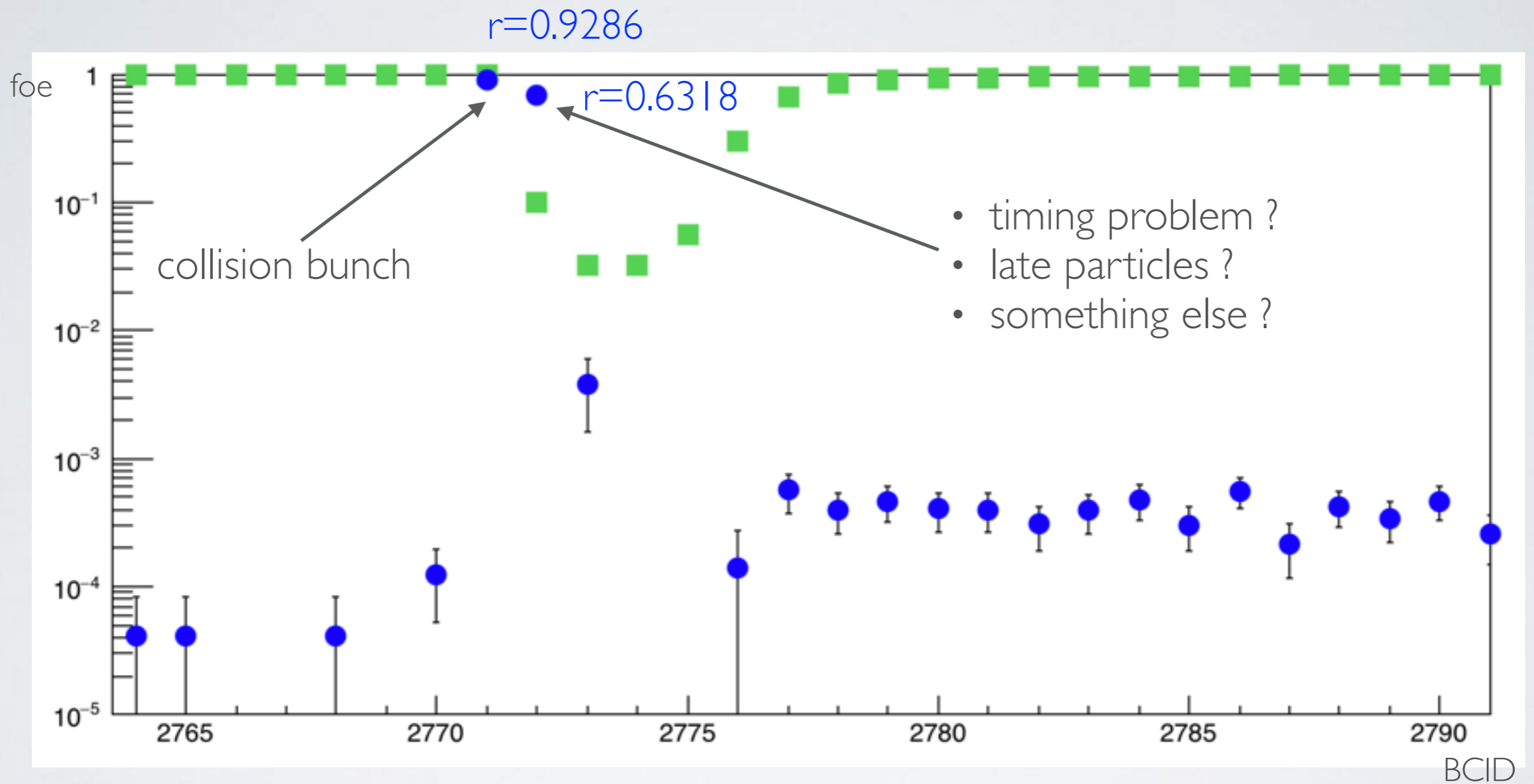
RECORDING 3.

- comparison with official ATLAS lumi statement
- nice correlation of values for first data
- overestimating at higher lumi bunches ?



RECORDING 3.

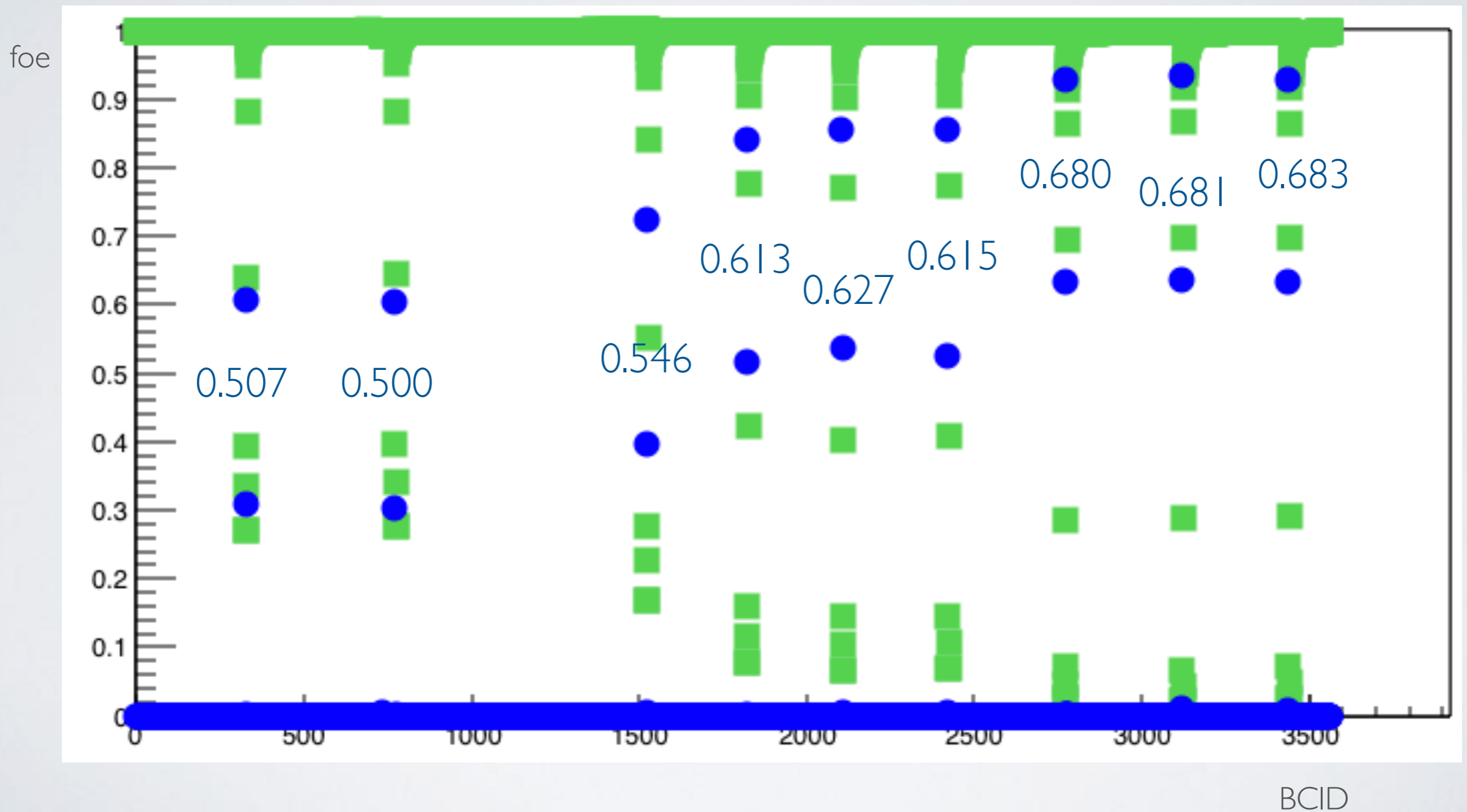
- closer look at individual BCs



RECORDING 3.

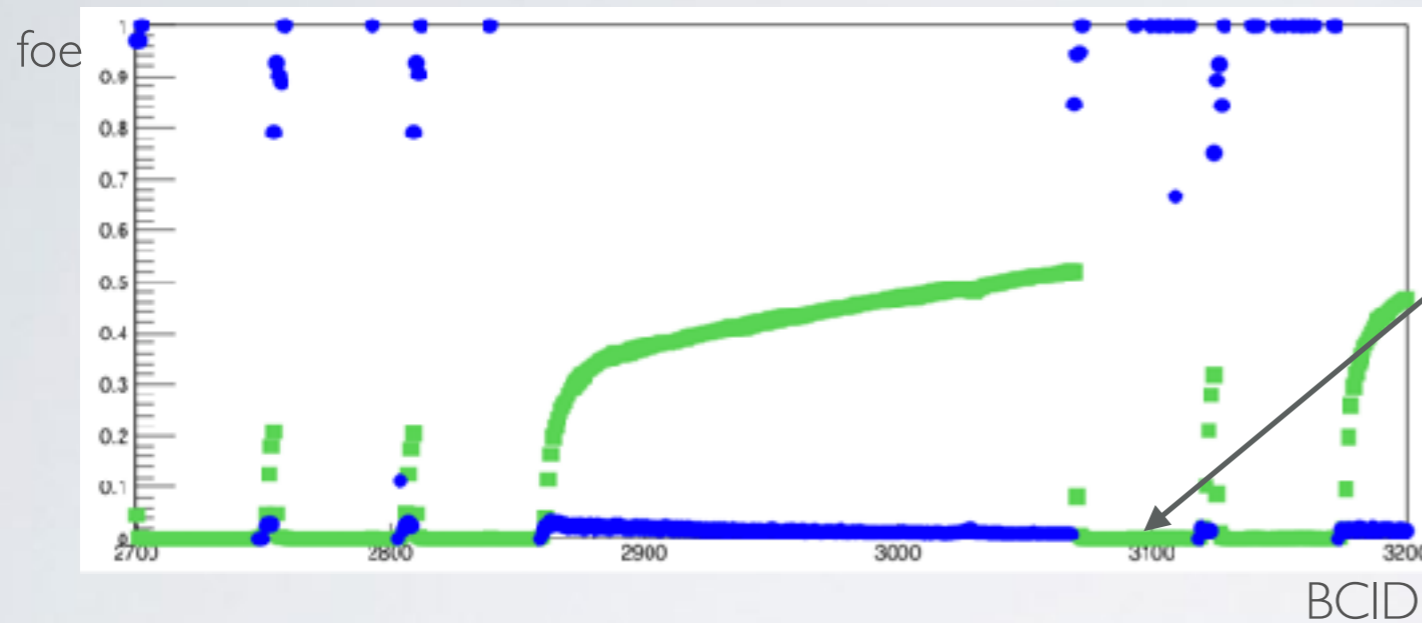
- correlation between the two following BCID

$$r(\text{BCID})/r(\text{BCID-1})$$



RECORDING 4.

- single run with 2544 colliding bunches (data tag: 2018_09_25_22_48_03)



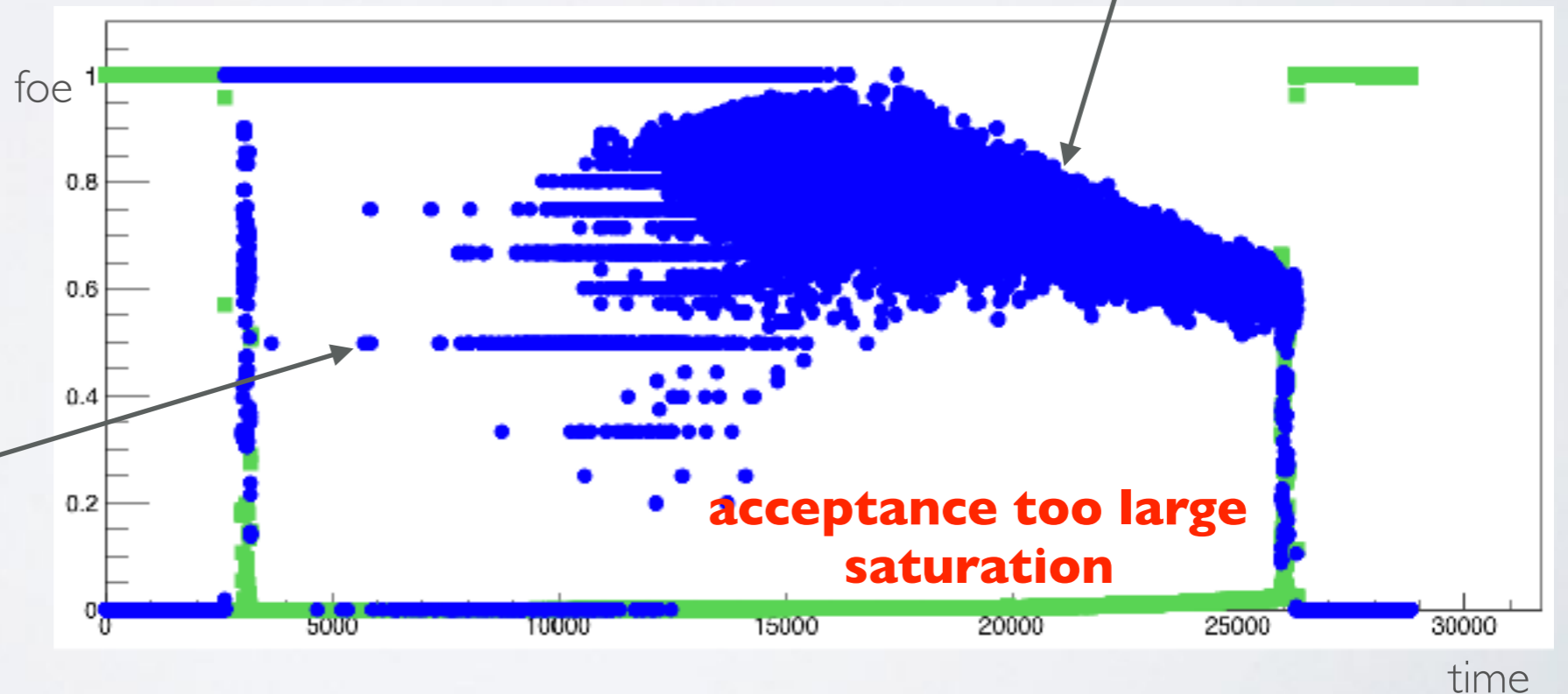
saturation in the train

as lumi drops, we move away from pile-up and start getting hit information

extreme pileup where only in 2 out of 24k instances a BC has been marked 'live'



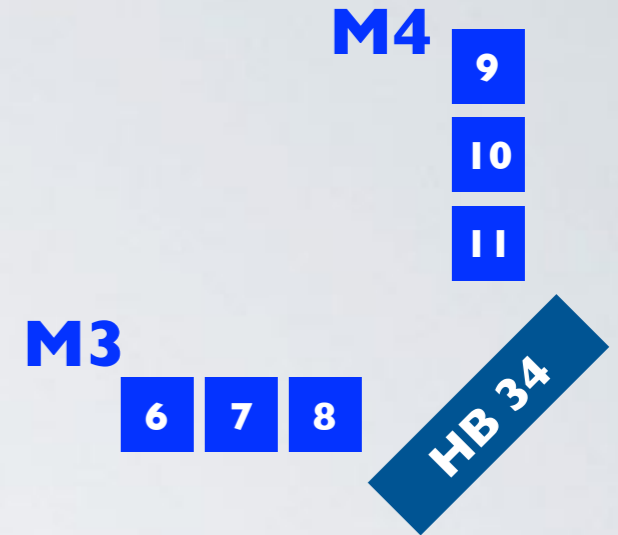
only 0, 1, or 2 hits possible



acceptance too large saturation

ALGORITHM SETUP-3

- running only side C - only HB-34 used
- so far: M3 give some signal, M4 no signal, FE8 does not contribute

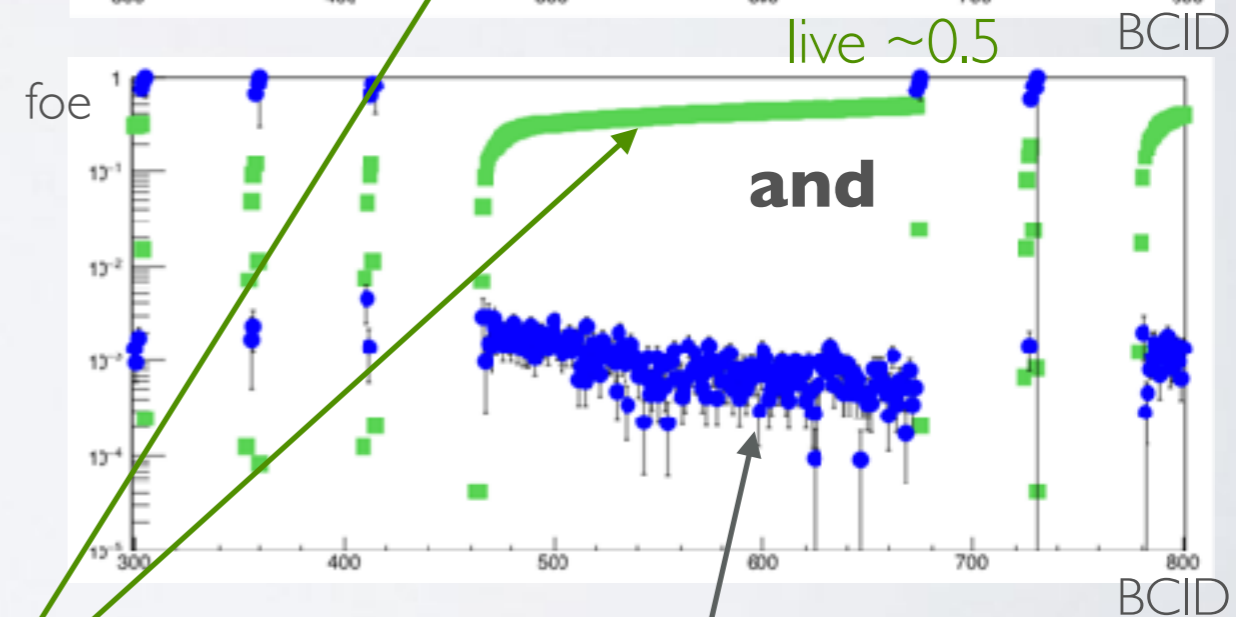
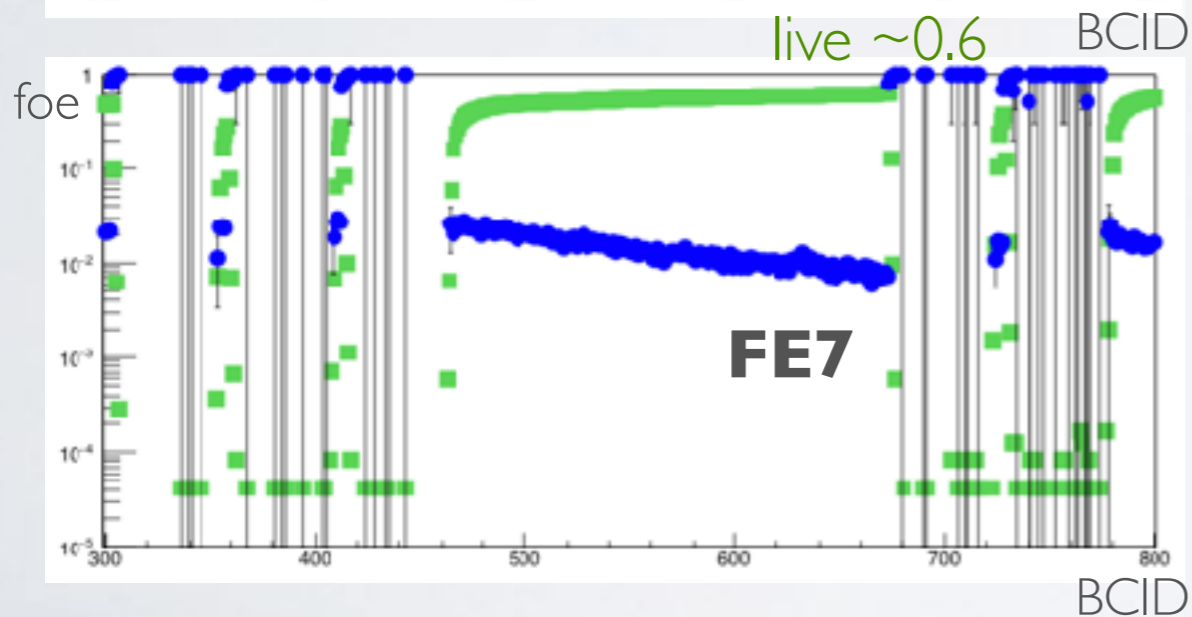
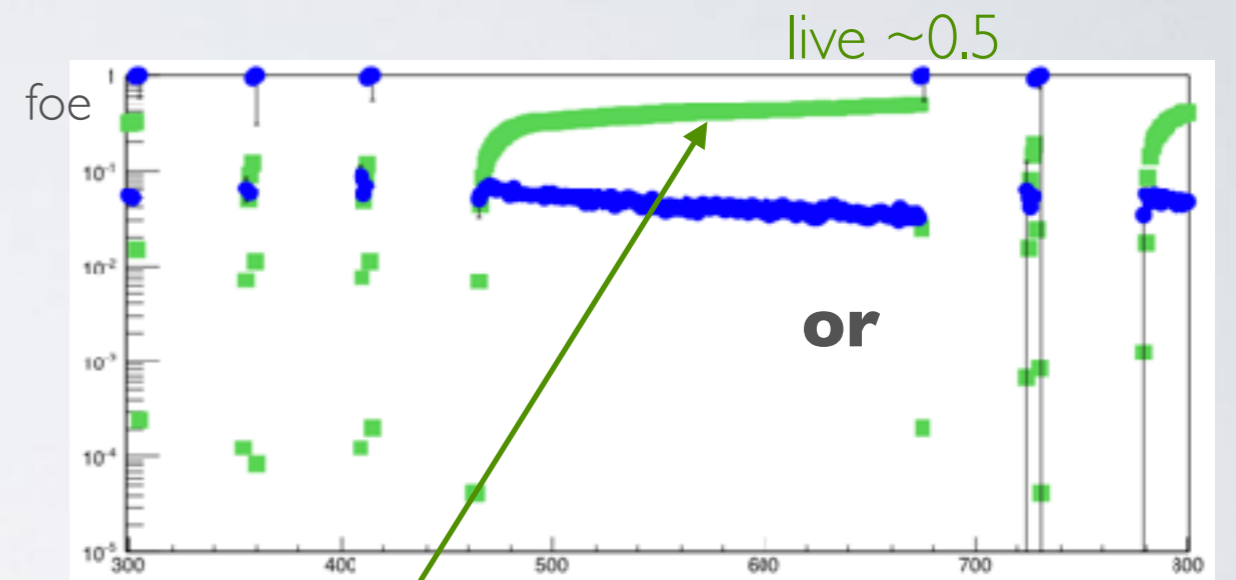
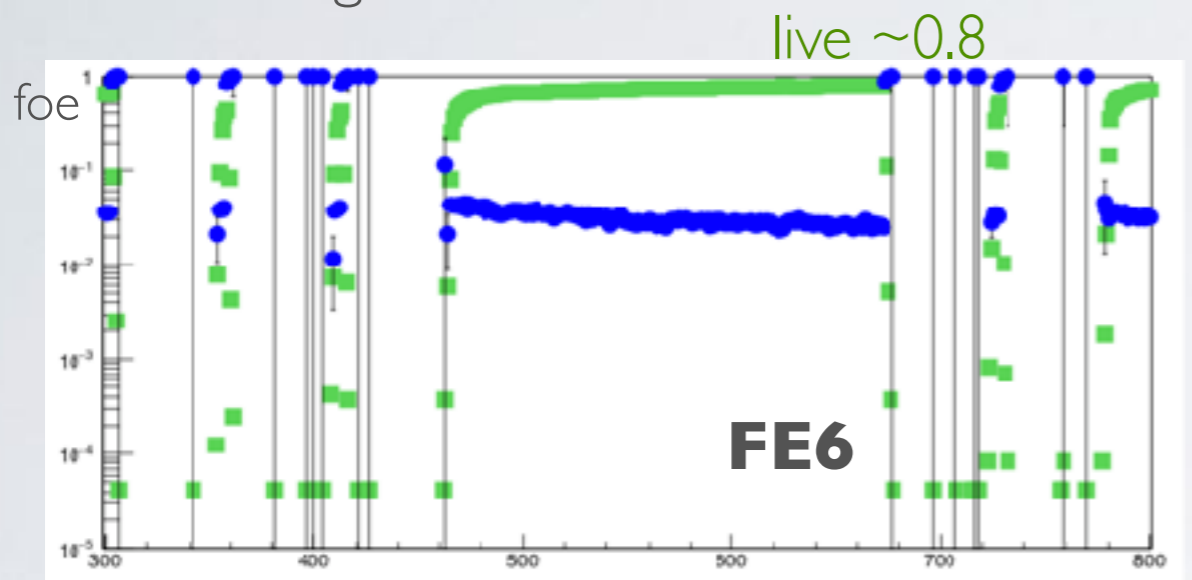


FPGA	Stream	Map	Algorithm	Logic
South	0	0	0	FE6 - single module
		1	1	FE7 - single module
	1	0	6	or(FE6, FE7) - or
		1	7	and(FE6, FE7) - and

RECORDING 6.

Algorithms	
0	single module F6
1	single module F7
6	or
7	and

- two ATLAS runs (data tag: 2018_09_28_22_57_05)
- recording 7., 8., and 10. similar



same level of 'live' fraction

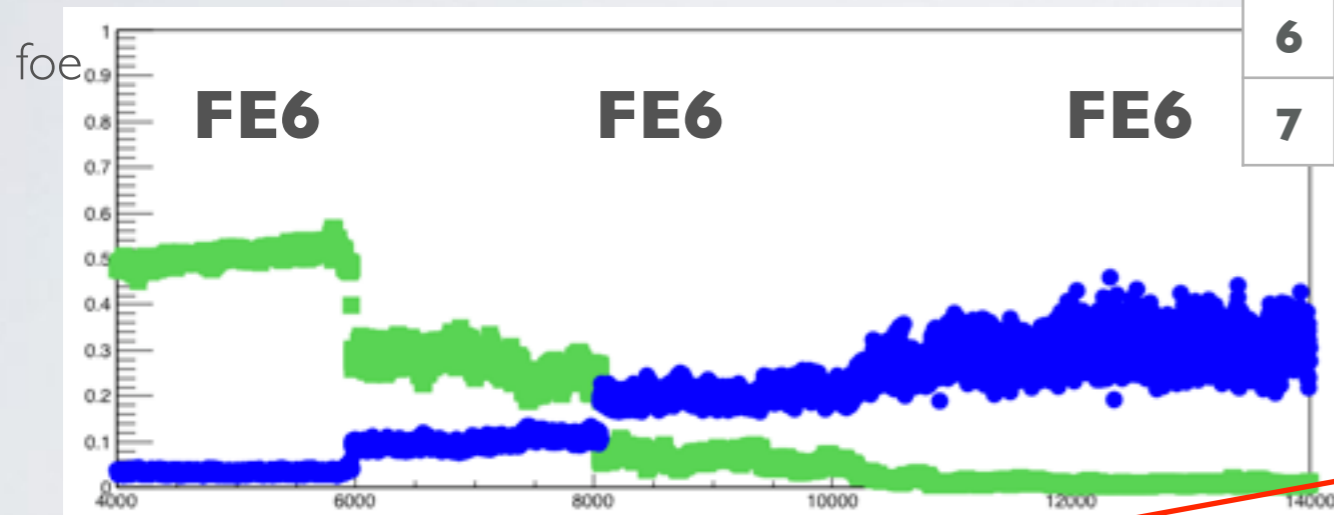
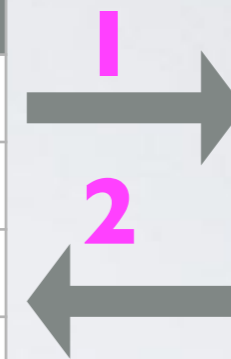
successful noise reduction

RECORDING 9.

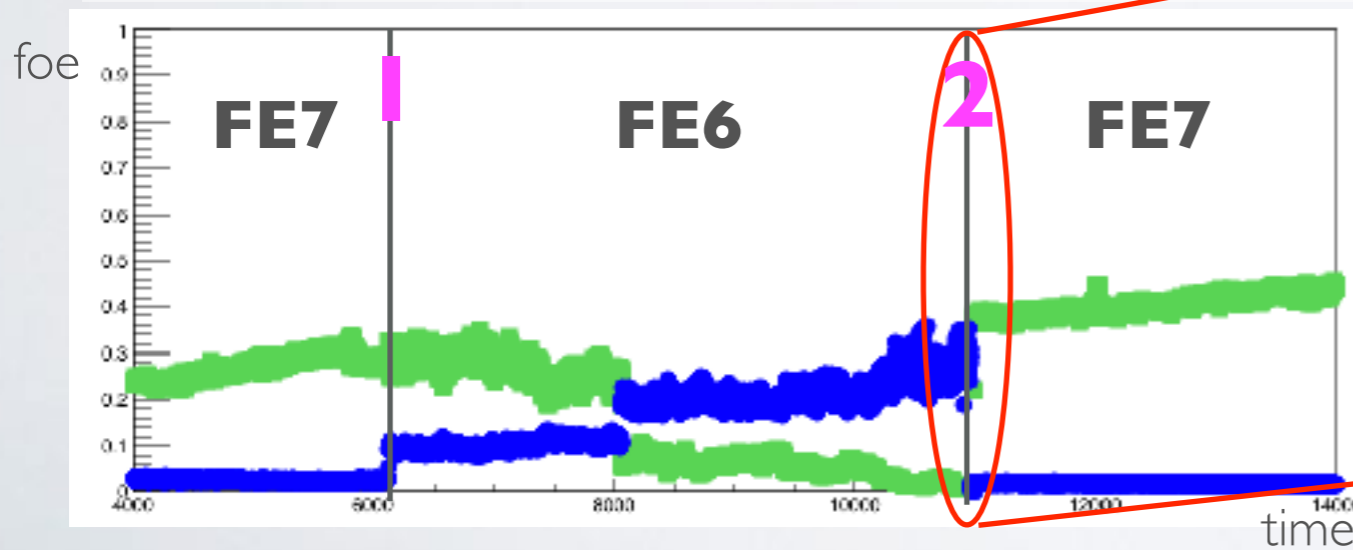
- testing the real-time lumi algorithm reconfiguration
- system works as expected
- ~55 s of data lost

Algorithms	
0	single module FE6
1	single module FE7
6	or
7	and

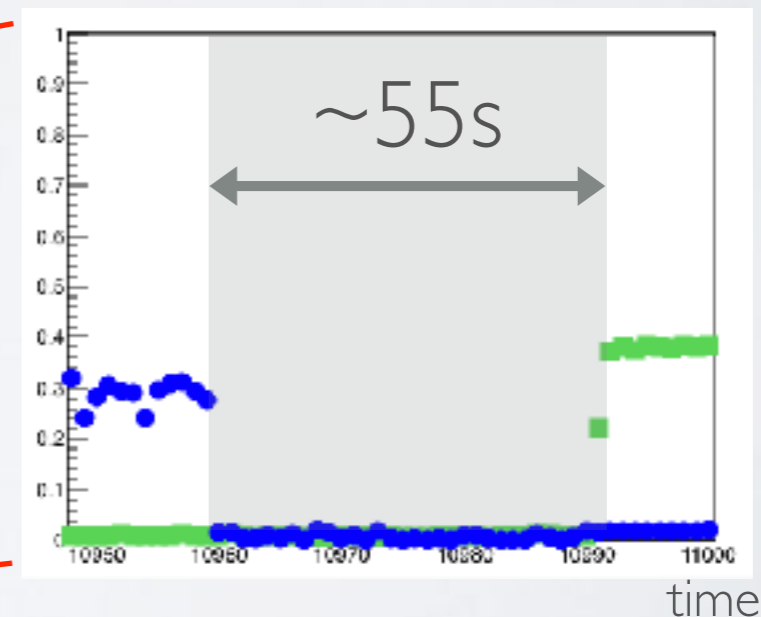
Algorithms	
0	single module FE6
1	single module FE6
6	or
7	and



algo 0



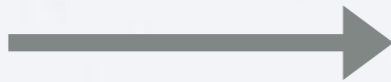
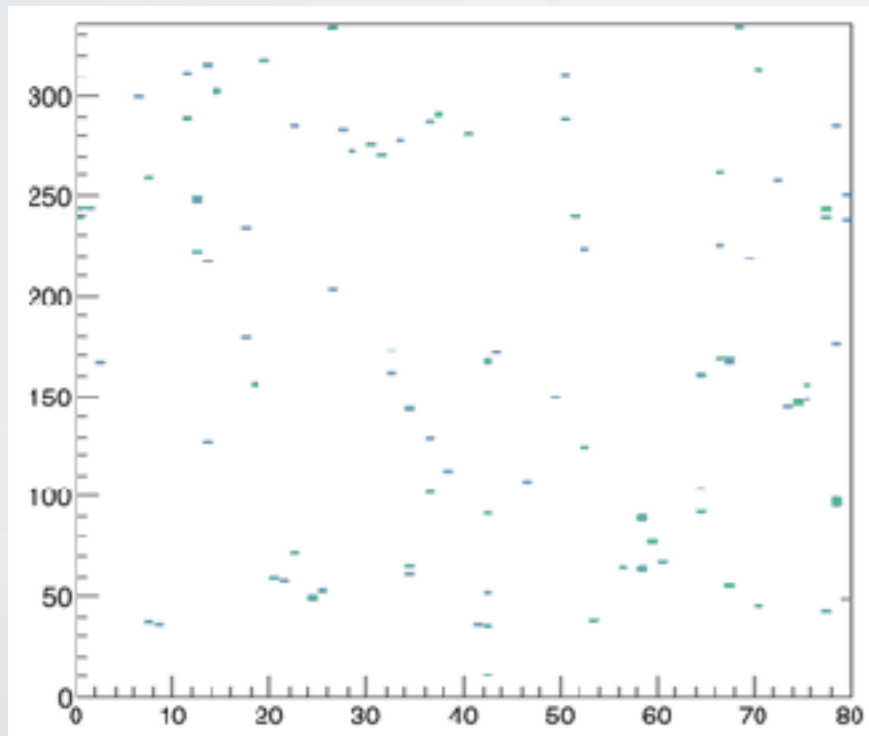
algo 1



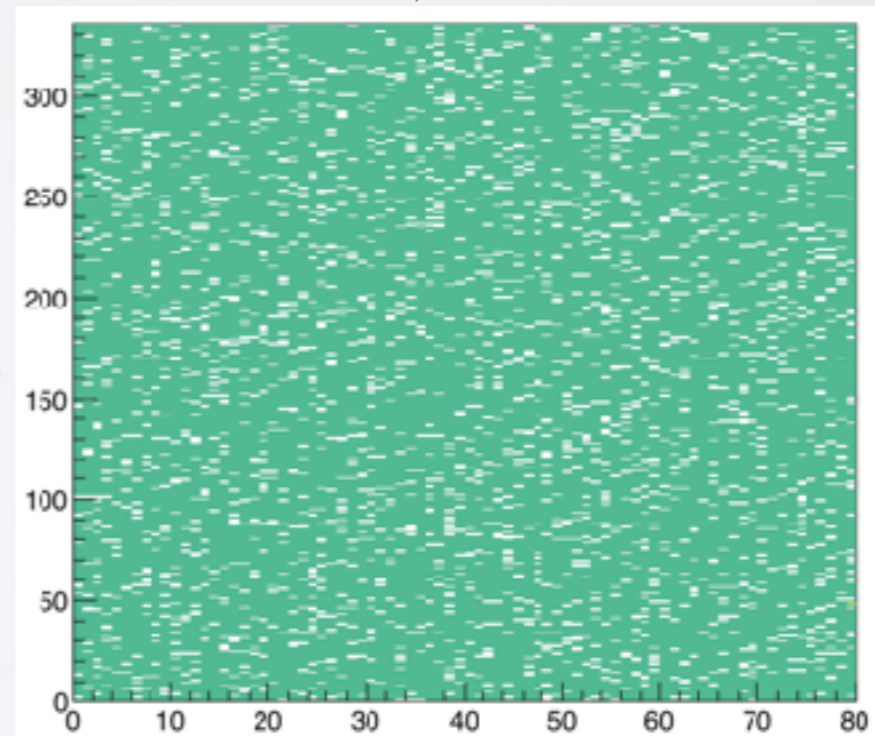
CHANGE OF MASK I.

- saturation due to HitOr mask that is too inclusive
- more selective mask should increase the live-time fraction of the detector
- in absence of more data/information a random subset of already included pixels chosen
- number of contributing pixels reduced by factor ~ 10

99%



8,5%

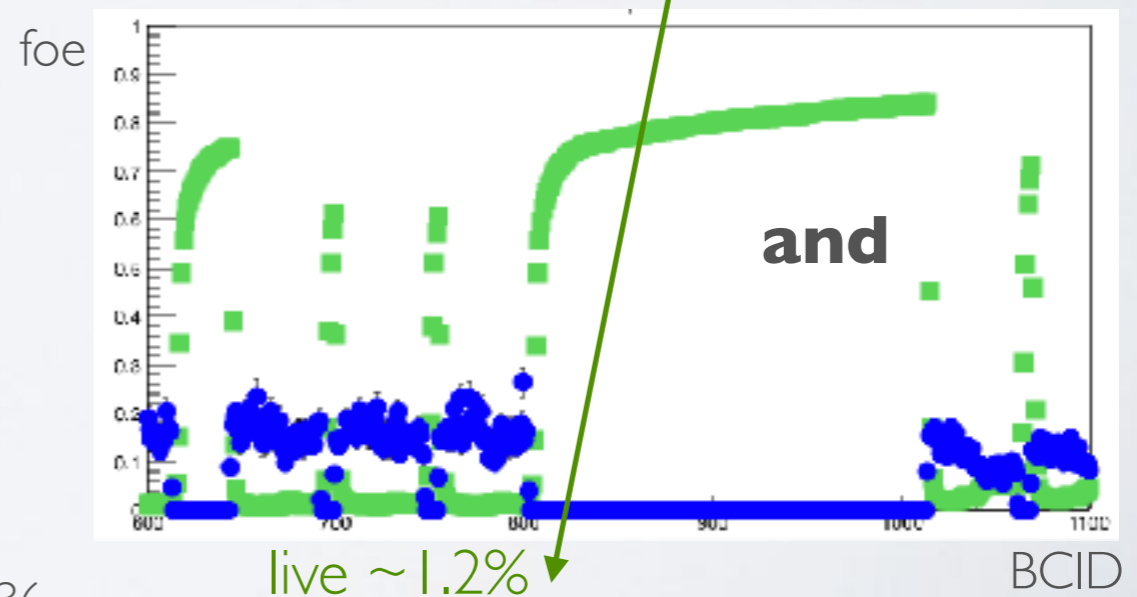
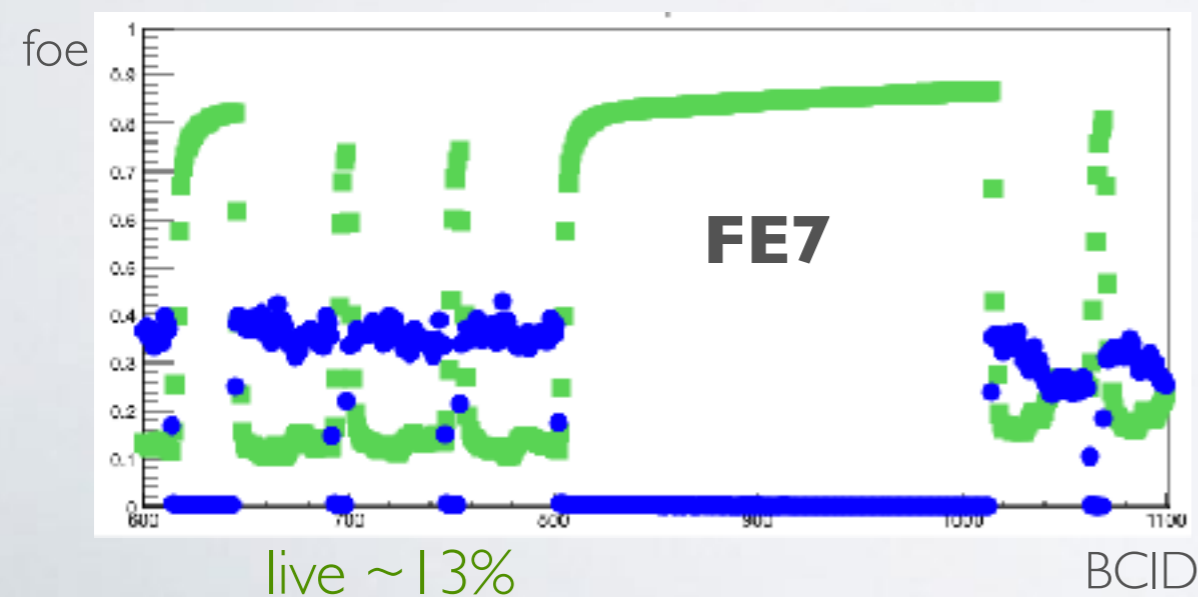
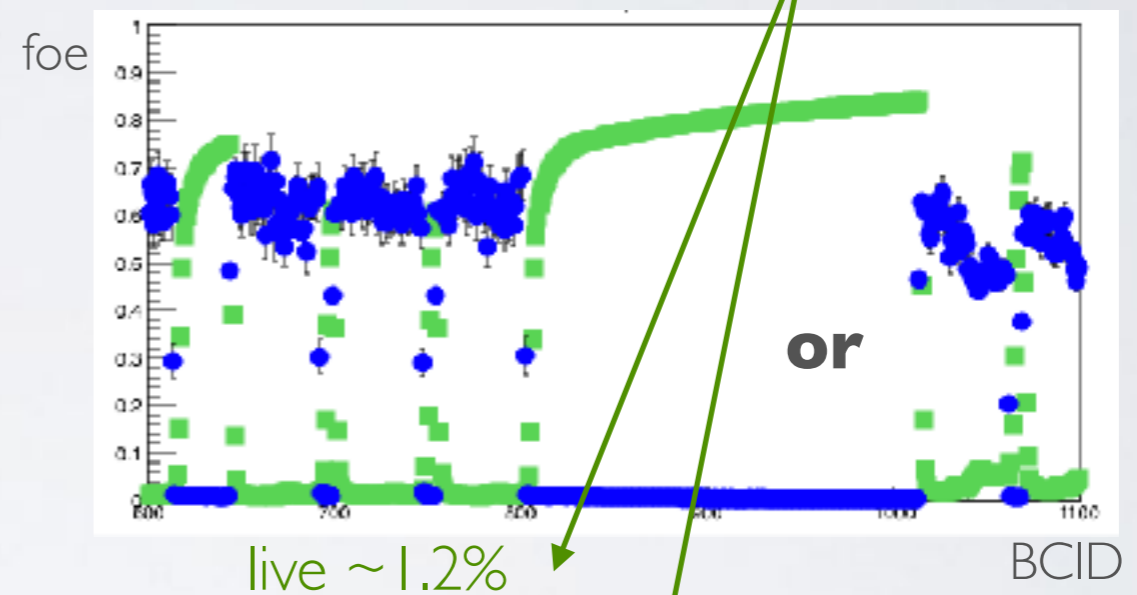
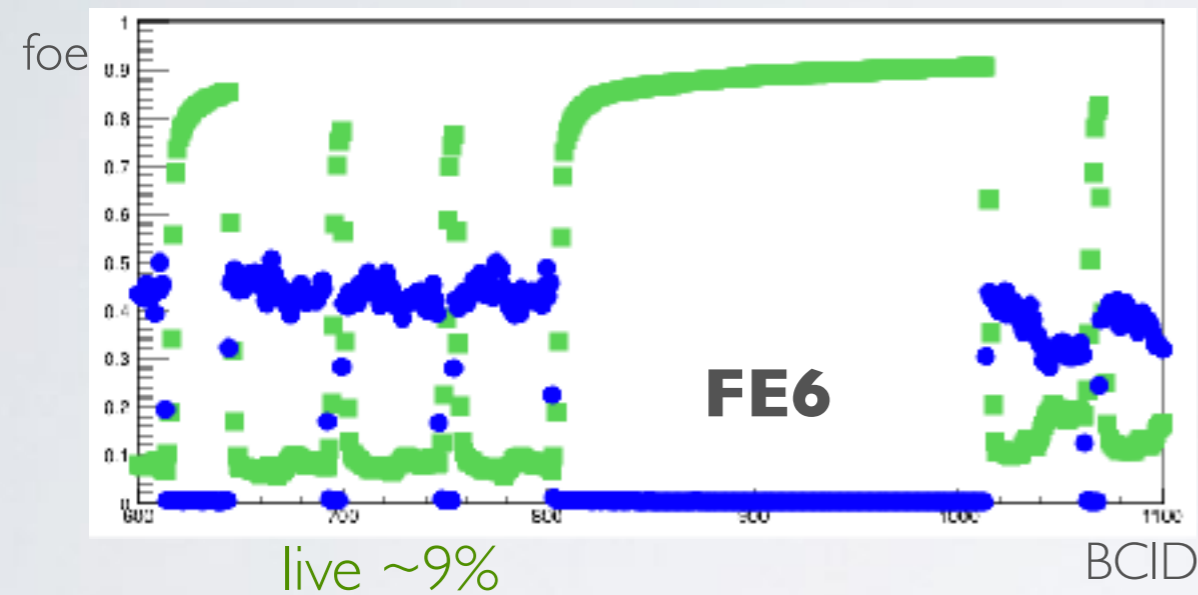


RECORDING II.

Algorithms	
0	single module FE6
1	single module FE7
6	or
7	and

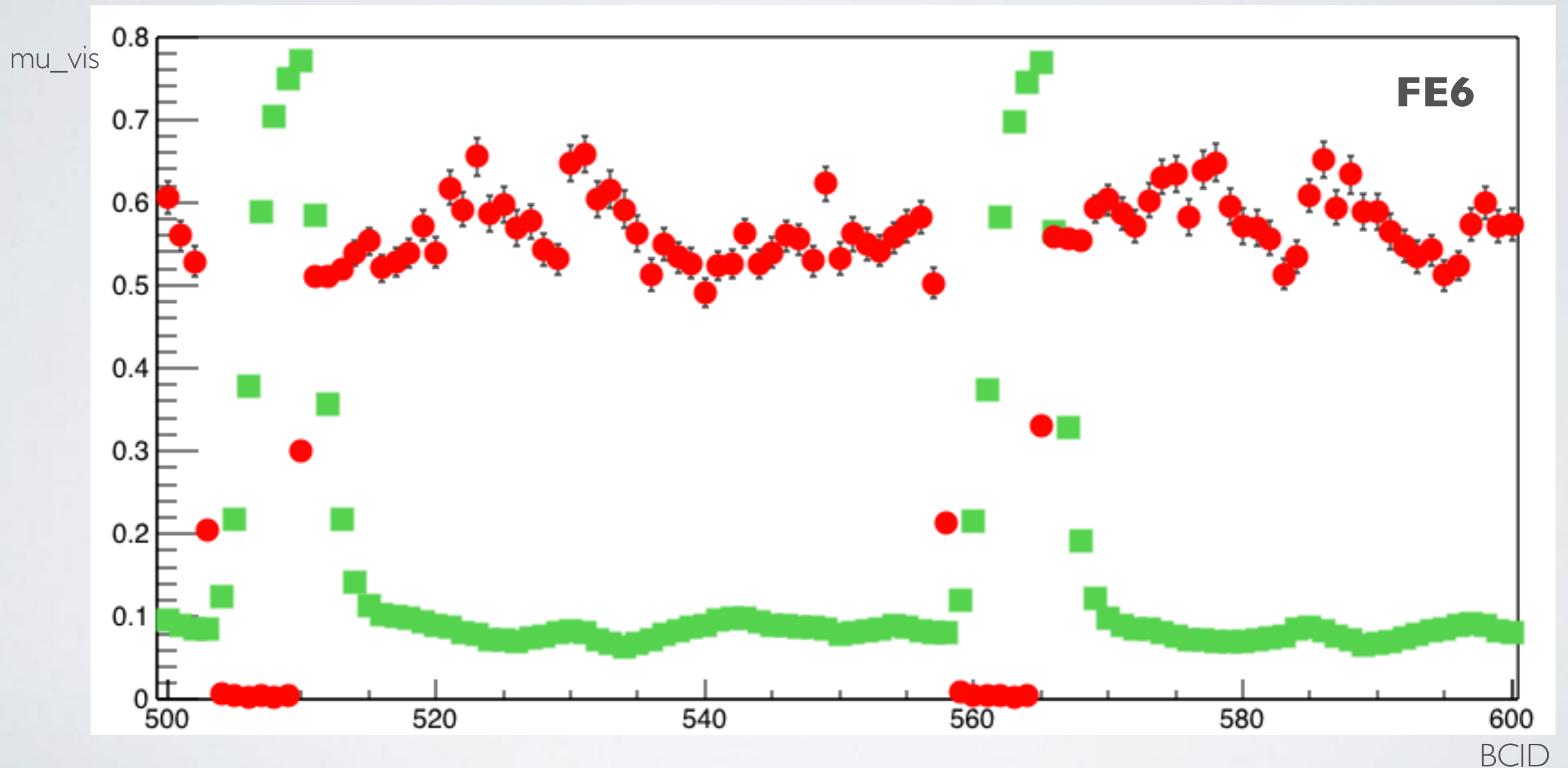
- single run with 2544 colliding bunches (data tag: 2018_10_02_07_48_48)
- mask change well pronounced in the results
- first sensible lumi measurement

same level of 'live' fraction



RECORDING II.

- actual lumi data (mu-corrected)

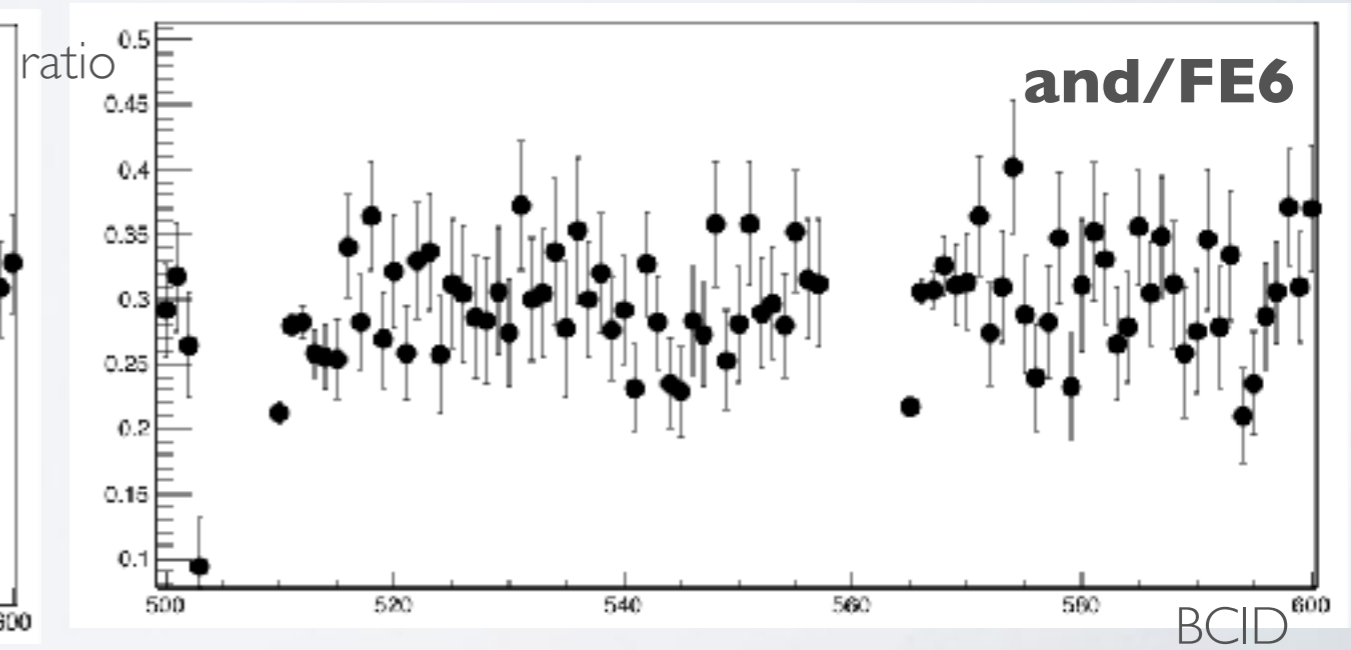
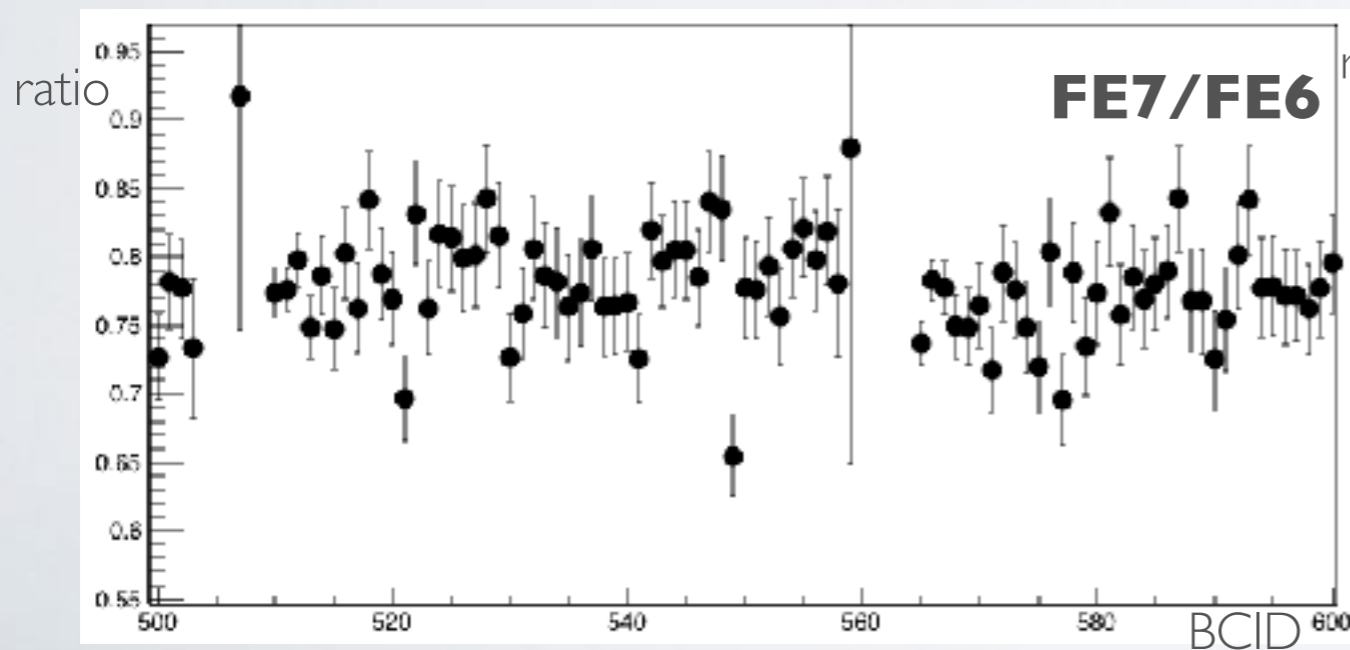
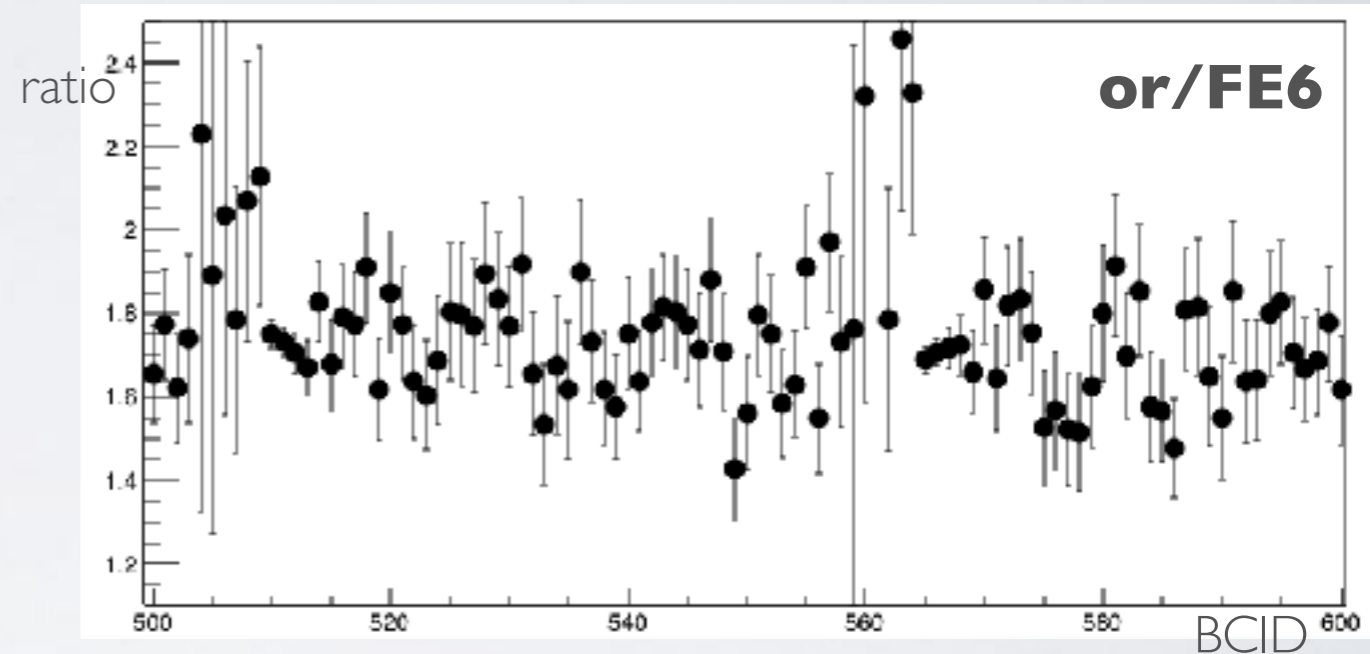


RECORDING II.

- consistency comparison between the algorithms
- algo0 = FE6 taken as a reference

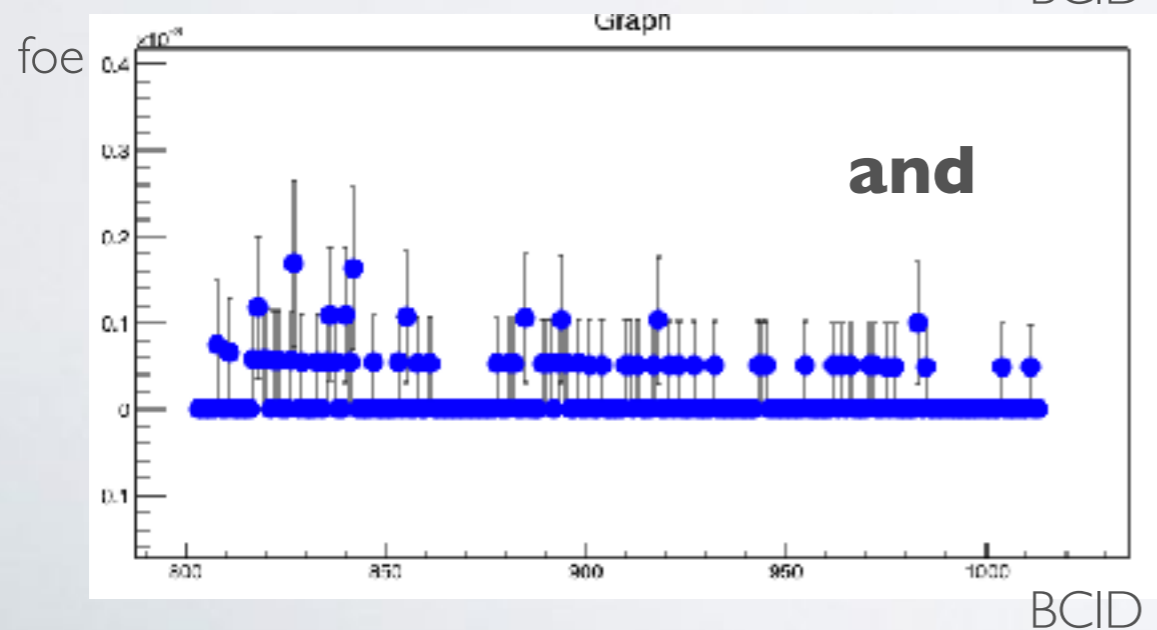
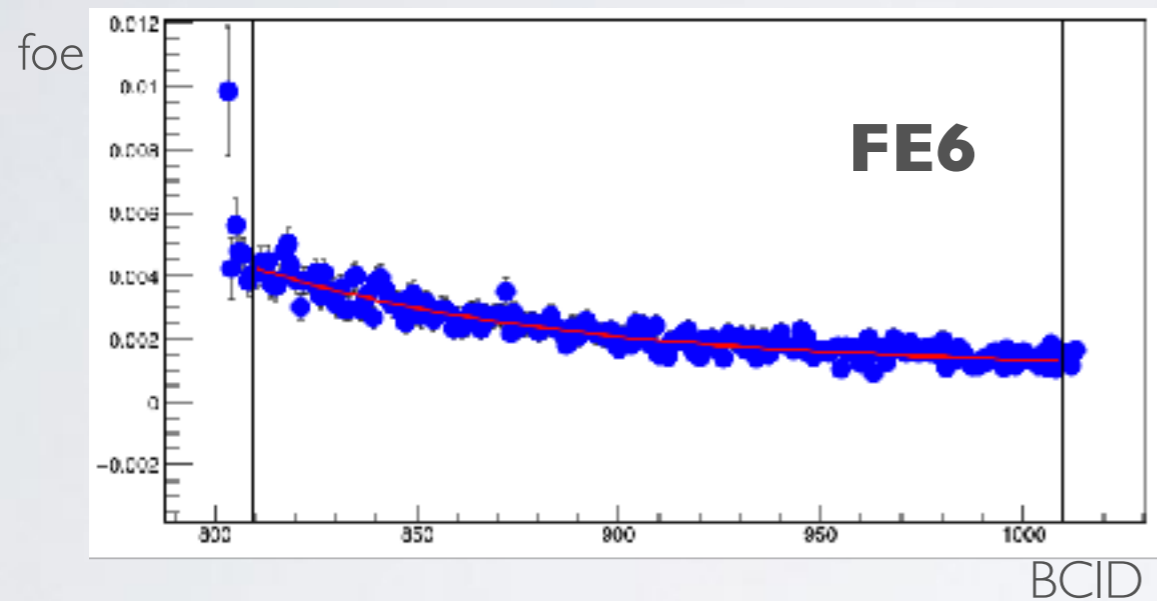
$$\text{ratio} = \frac{\text{lumi}(\text{algo X})}{\text{lumi}(\text{algo 0})}$$

- ratio should be independent of BCID and time



RECORDING II.

- estimating noise
- looking at the abort gap and fitting: $\exp+C$



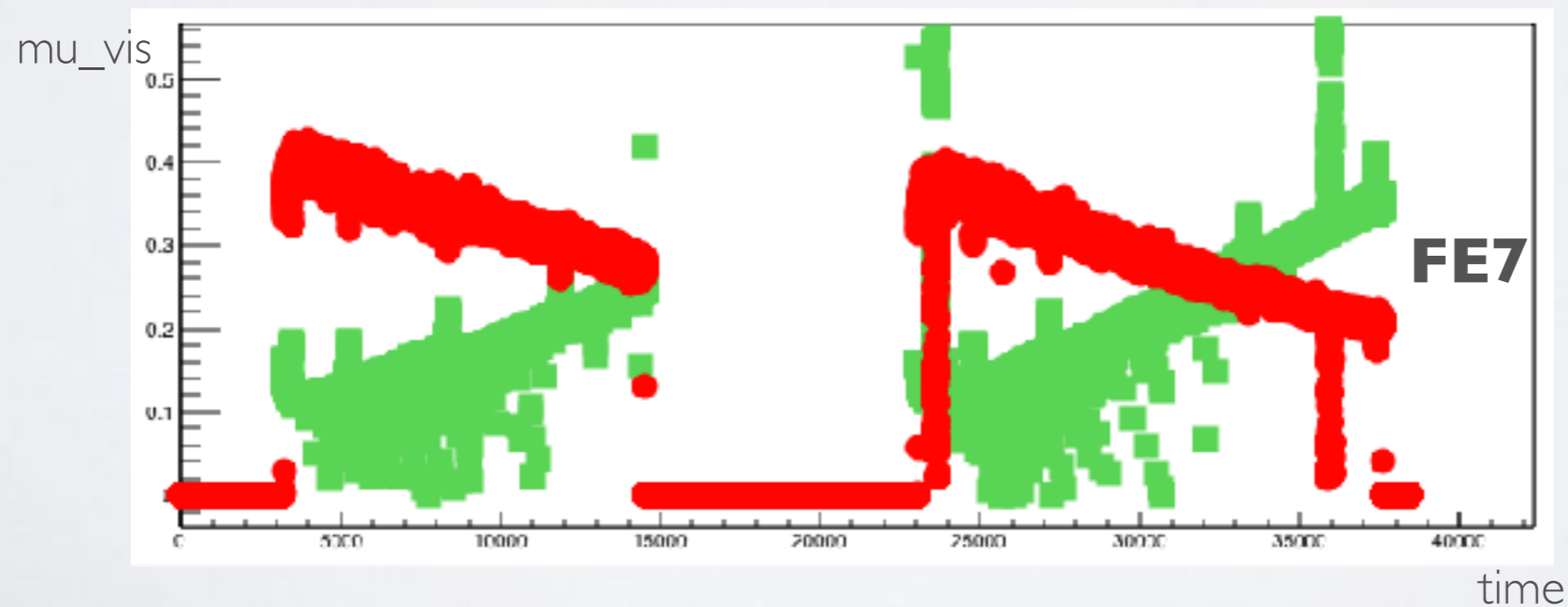
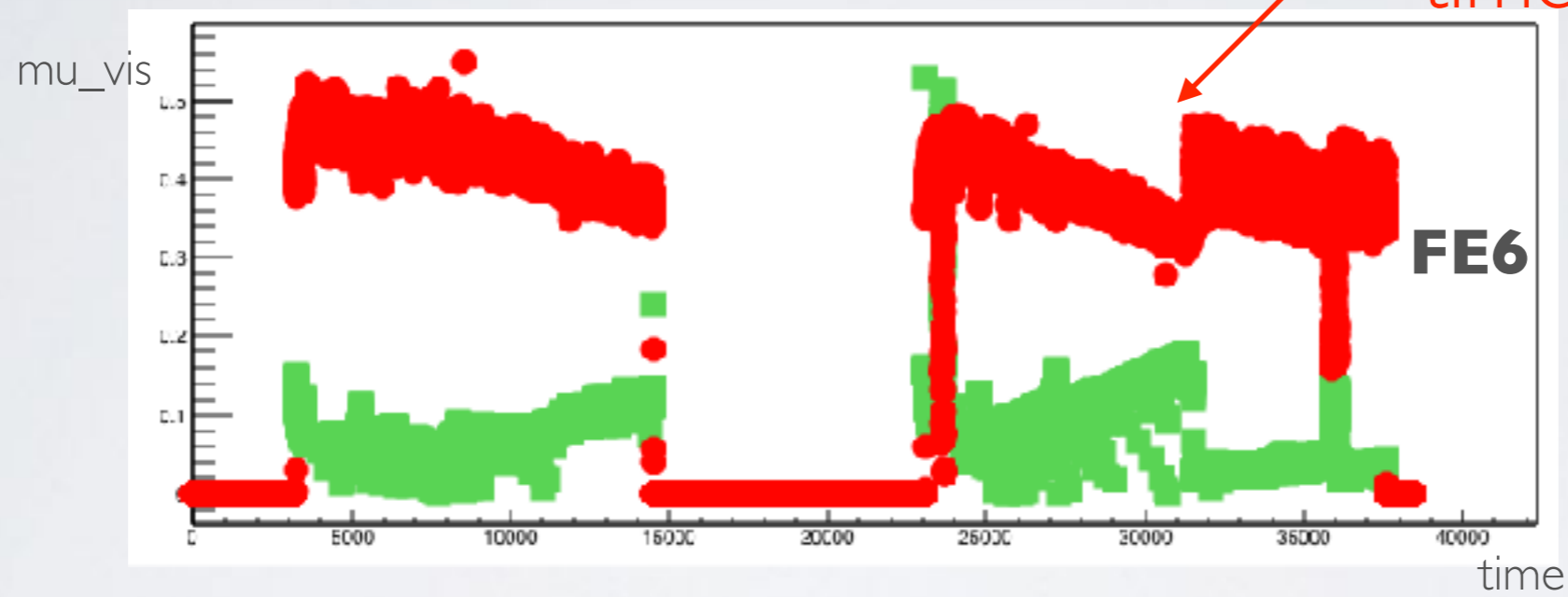
algo	λ	const.
FE6	$(1.26 \pm 0.13) * 10^{-2}$	$(1.06 \pm 0.03) * 10^{-3}$
FE7	$(1.06 \pm 0.10) * 10^{-2}$	$(0.92 \pm 0.16) * 10^{-3}$
or	$(1.16 \pm 0.08) * 10^{-2}$	$(2.04 \pm 0.18) * 10^{-3}$
and	/	/

- decay constants consistent
- individual modules noise level consistent
- or gives ~ 2 times higher noise

RECORDING 12.

- time evolution for two runs
- FE6 experiences problems from time to time

some configuration
on FE changes
(observed multiple
times on FE6, FE10)

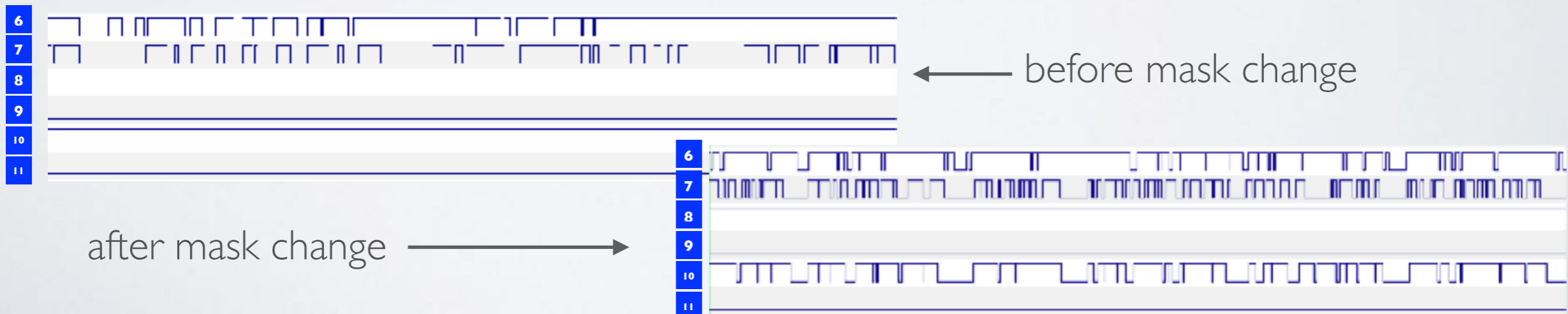


ALGORITHM SETUP-4

- running only side C - only HB-34 used
- so far: M3 give some signal, FE8 does not contribute, FE10 recovered



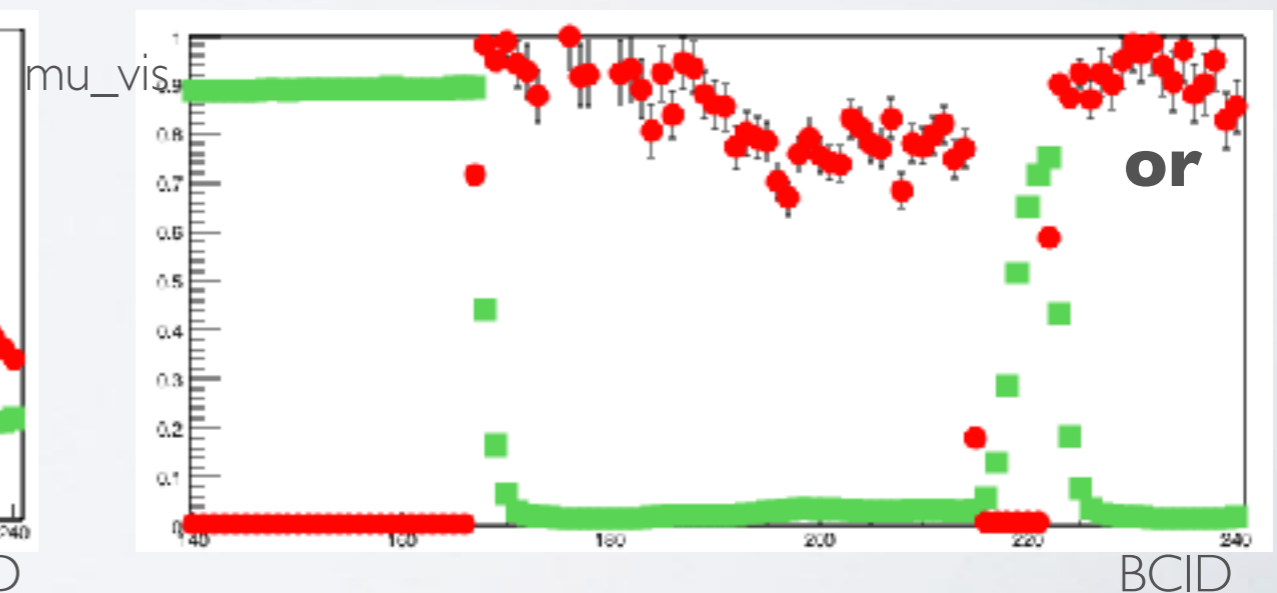
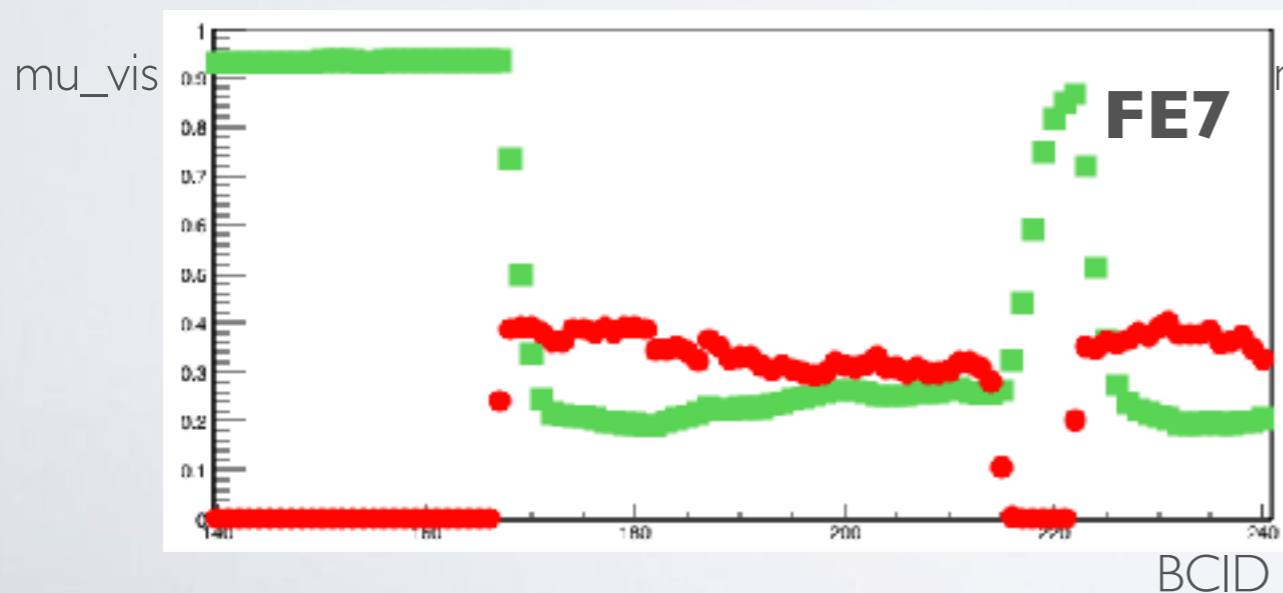
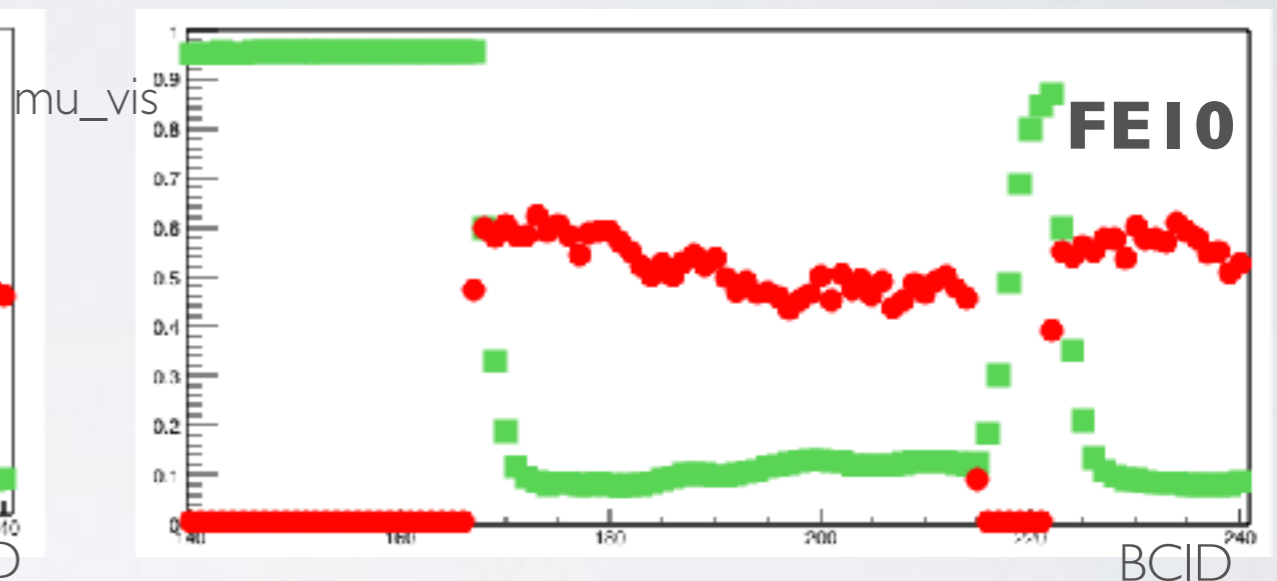
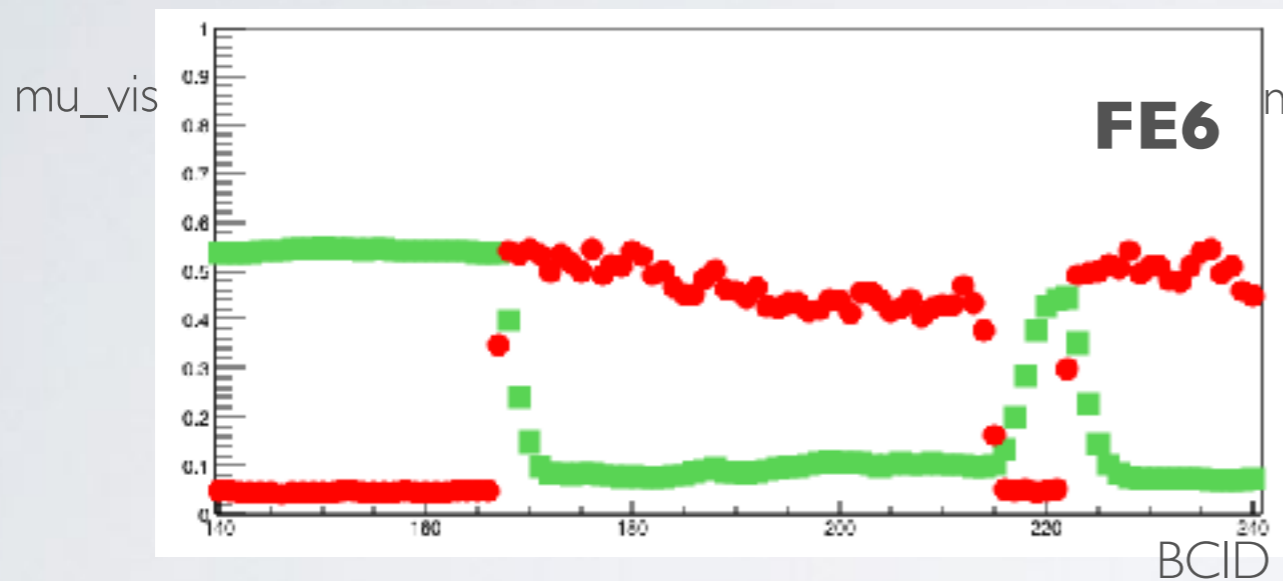
FPGA	Stream	Map	Algorithm	Logic
South	0	0	0	FE6 - single module
		1	1	FE7 - single module
	1	0	6	FE10 - single module
		1	7	or(FE7, FE10) - or



RECORDING 13.

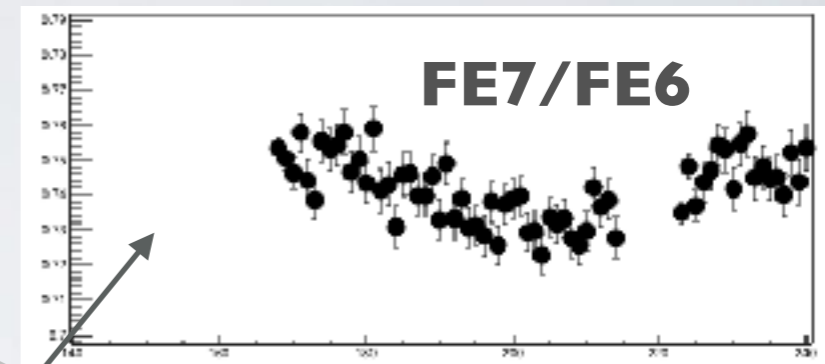
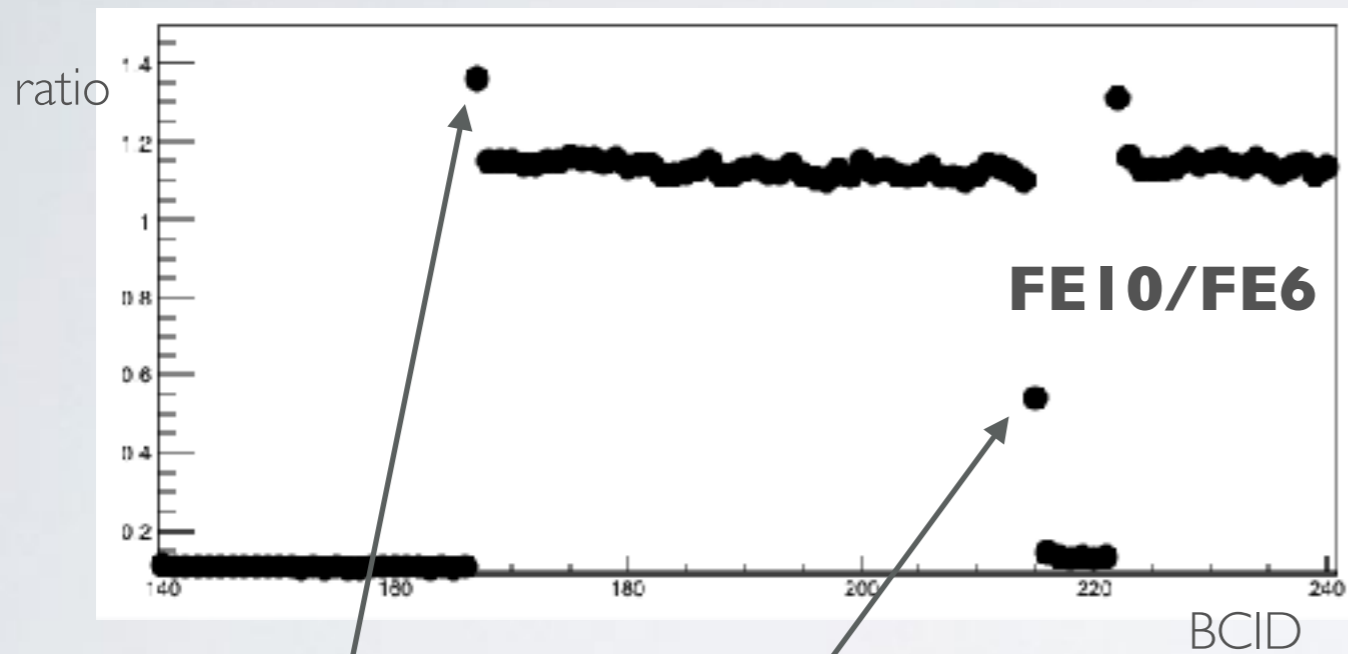
- F10 as a new input to the algorithms
- functional as others

Algorithms	
0	single module FE6
1	single module FE7
6	single module FE10
7	or of two



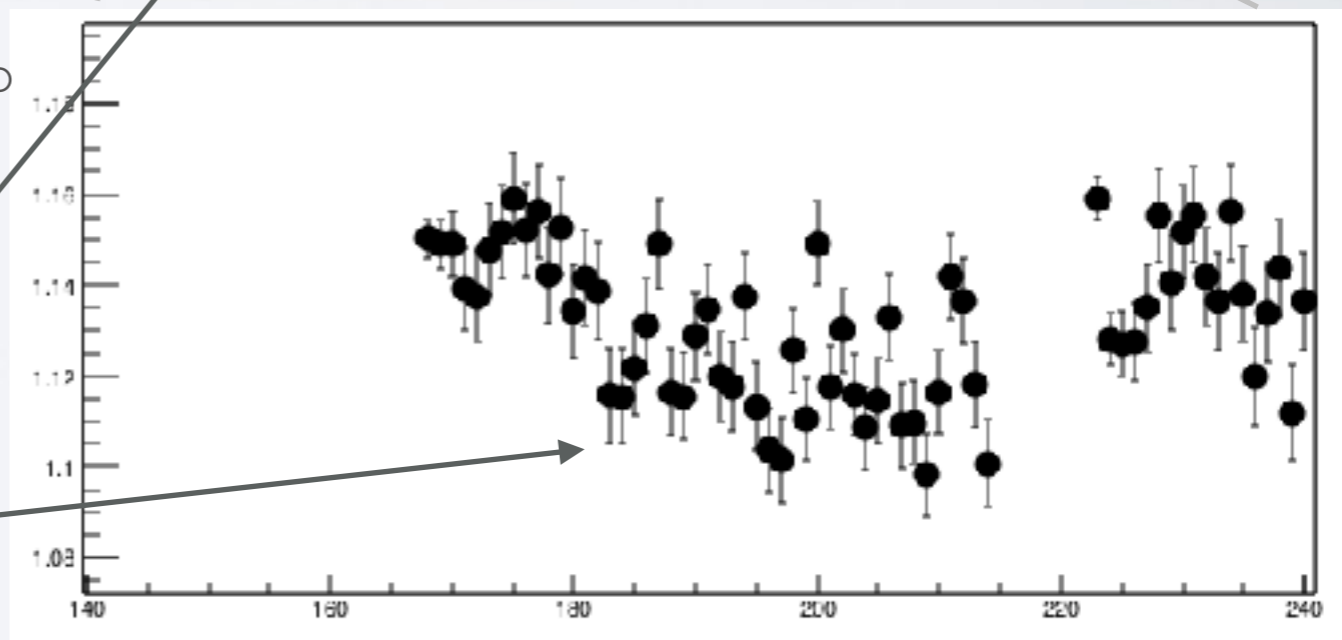
RECORDING 13.

- check of FE10 data
- first and last bunch of the train different



significant disagreement
between the modules

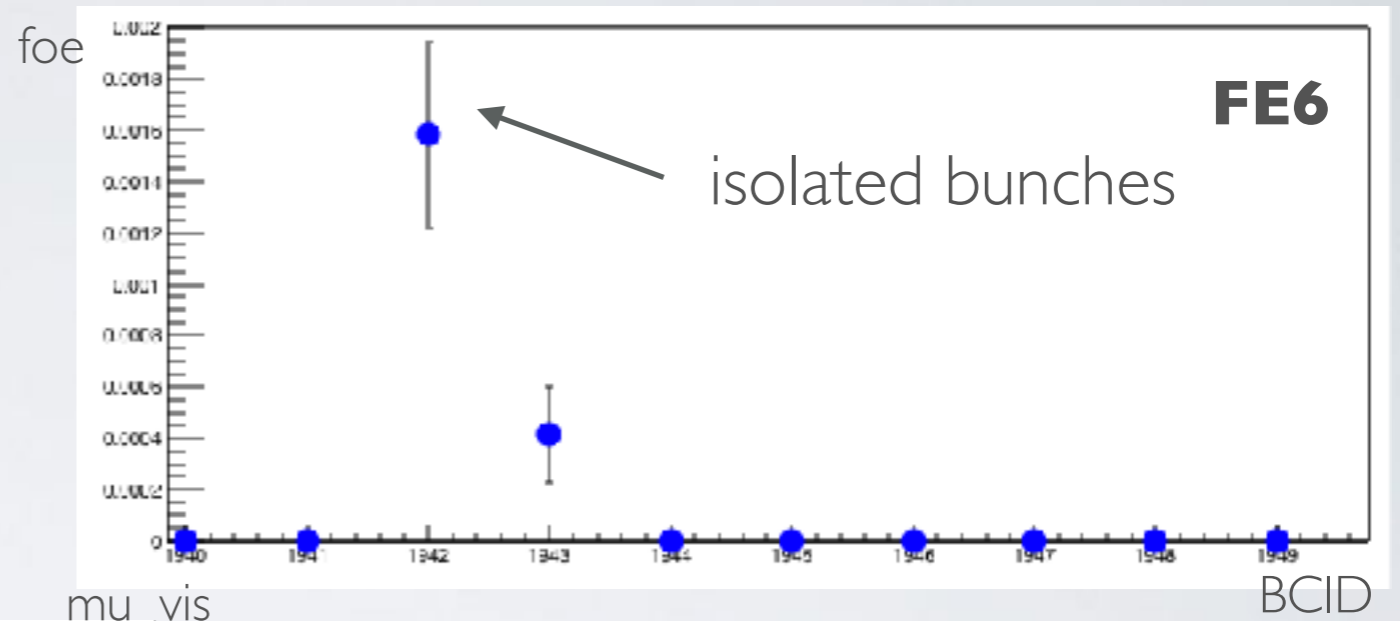
some stat. sig. deviation within
the train



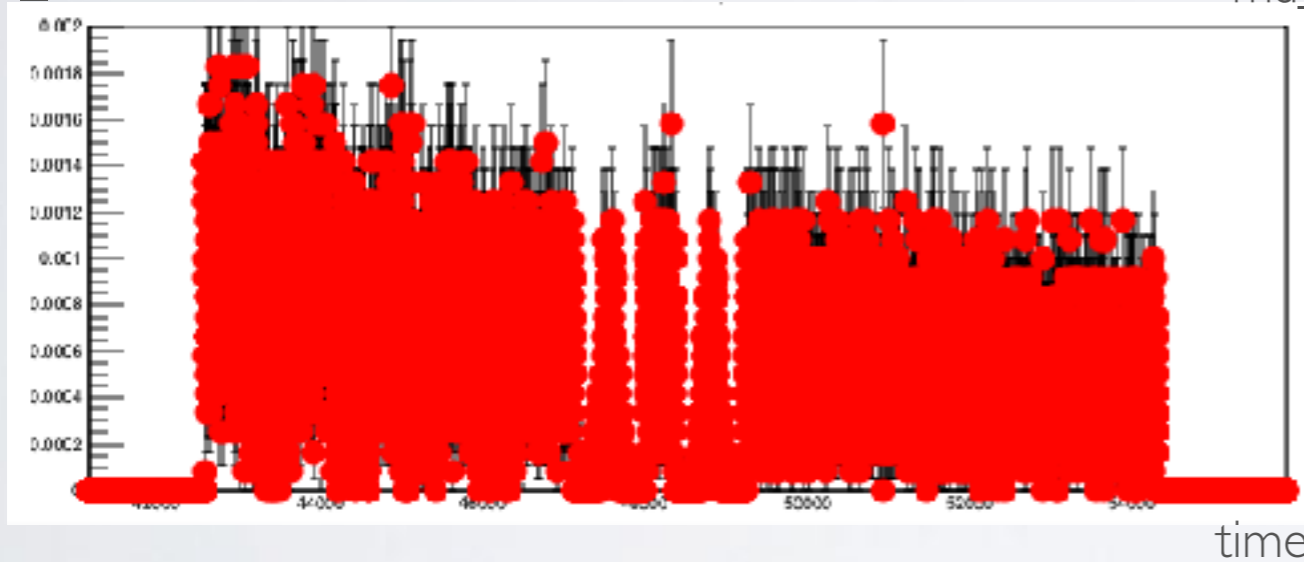
RECORDING 21.

- low lumi runs, includes VdM scan
- readout period changed from $\sim 2s$ to $\sim 1s$

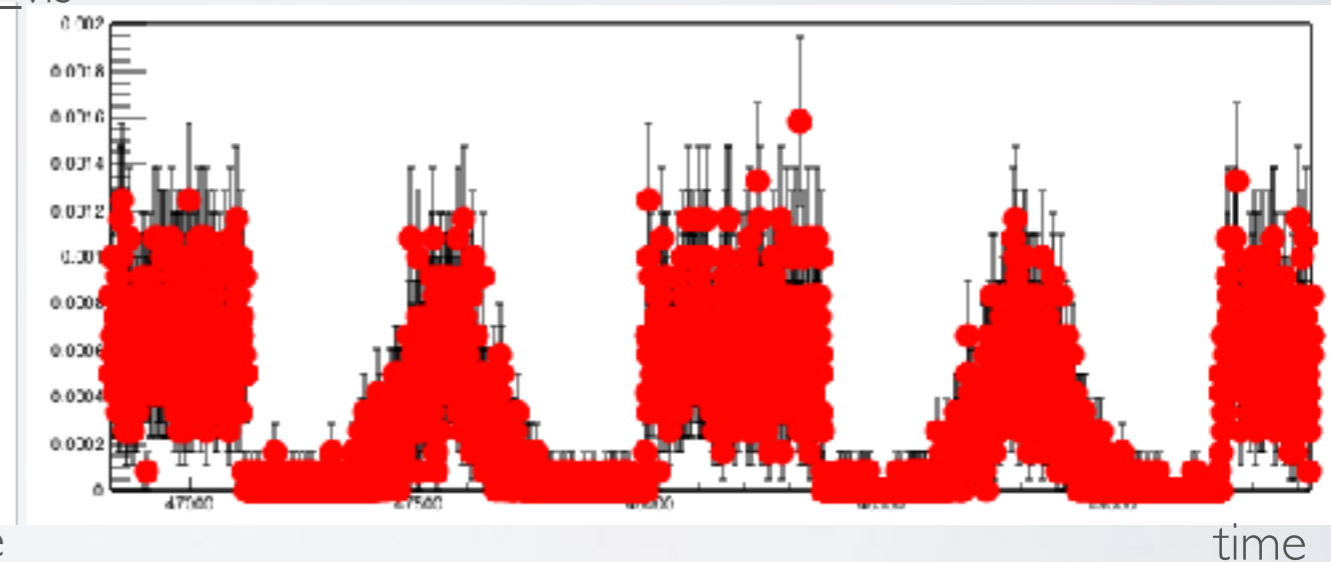
statistic too low for
any proper analysis



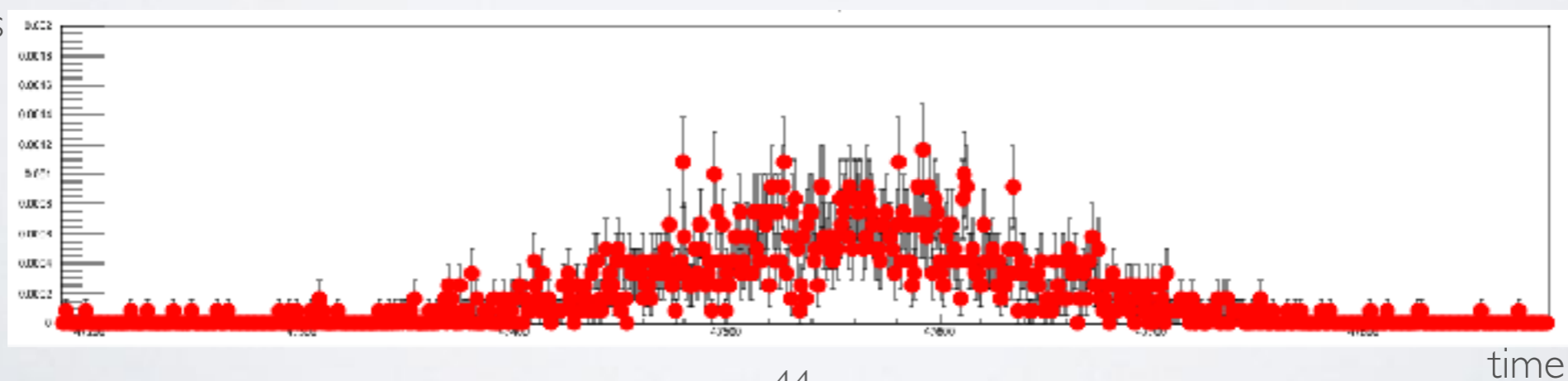
mu_vis



mu_vis



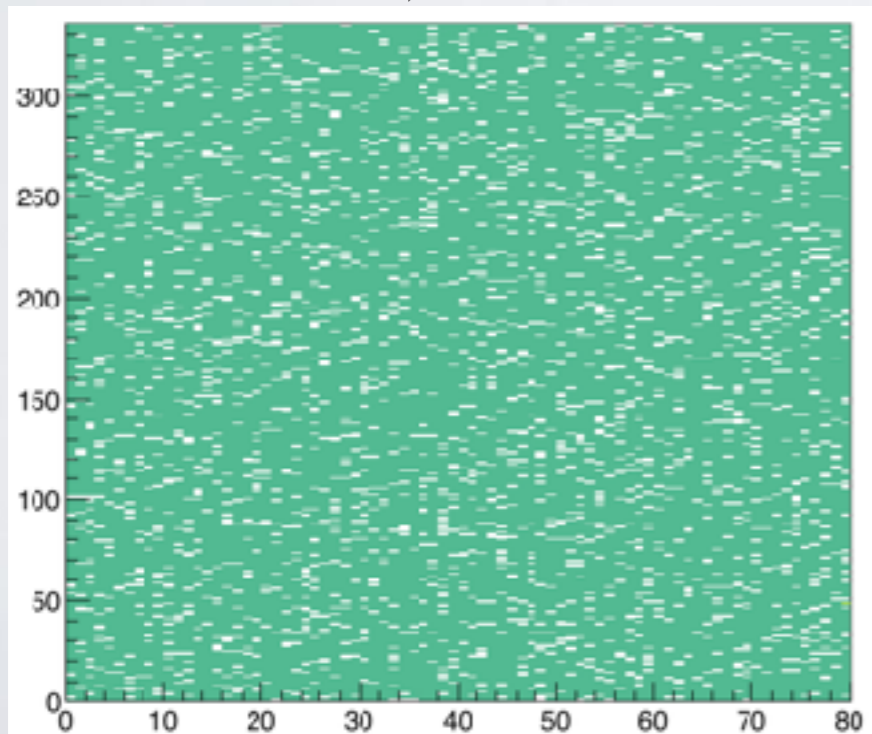
mu_vis



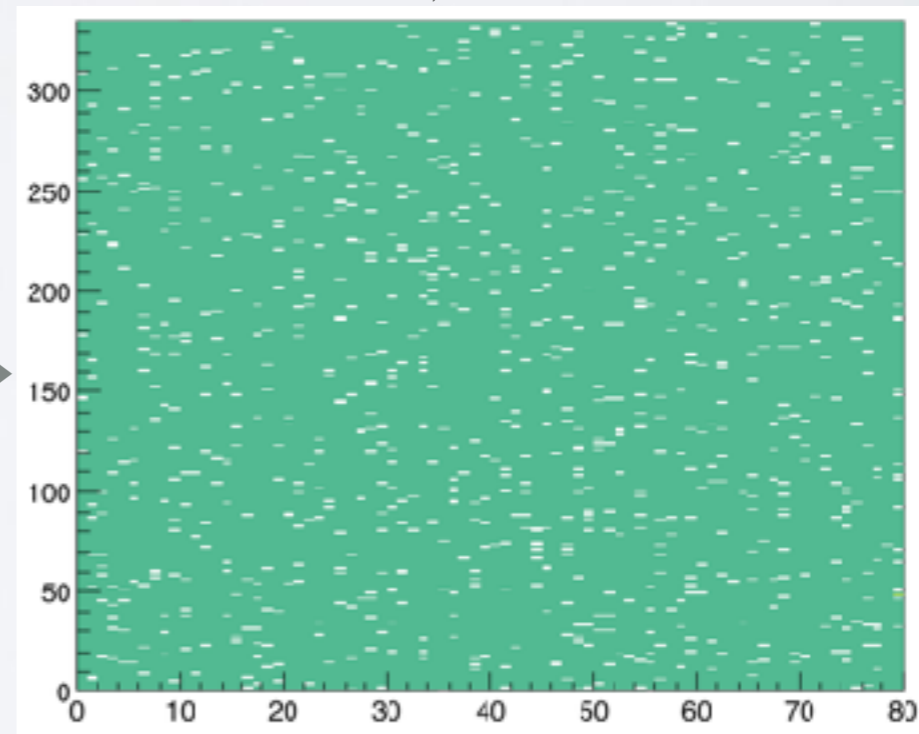
CHANGE OF MASK 2.

- lumi data available, but no estimate how optimal
- estimates show a further reduction would be beneficial
- factor ~ 4 chosen

8,5%



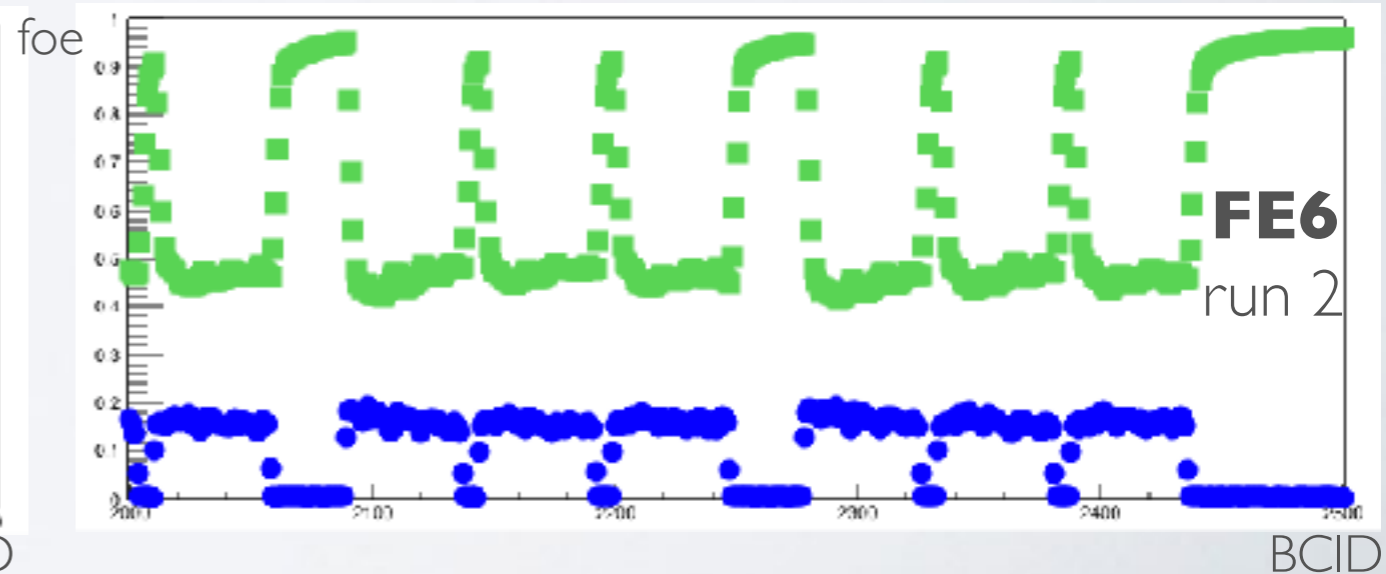
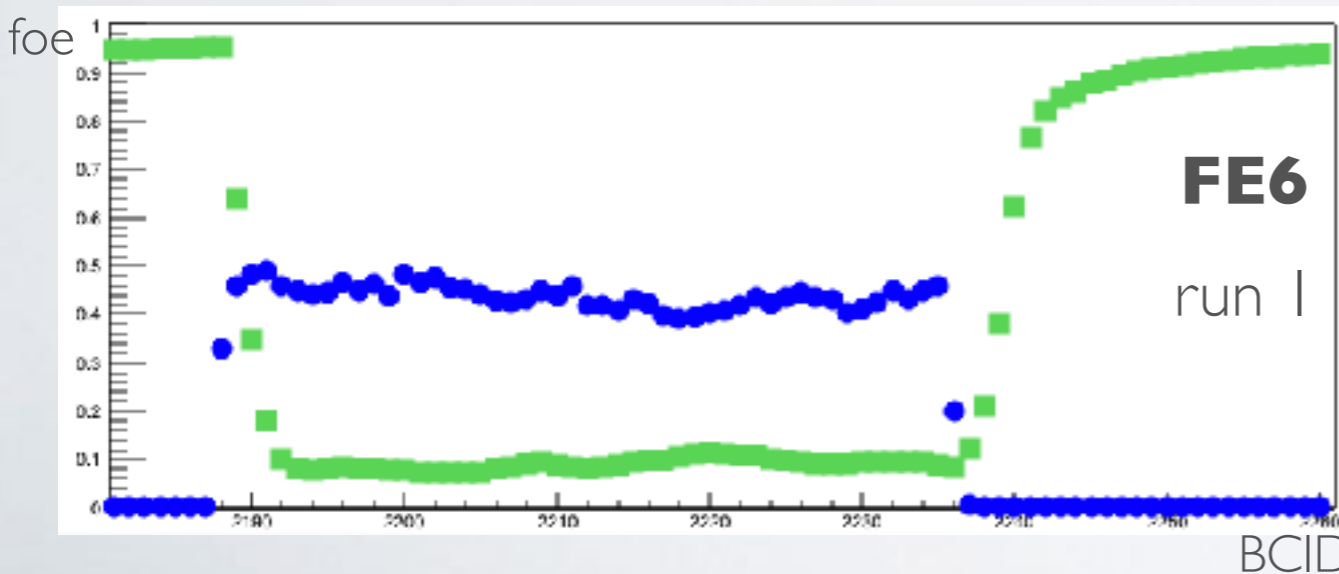
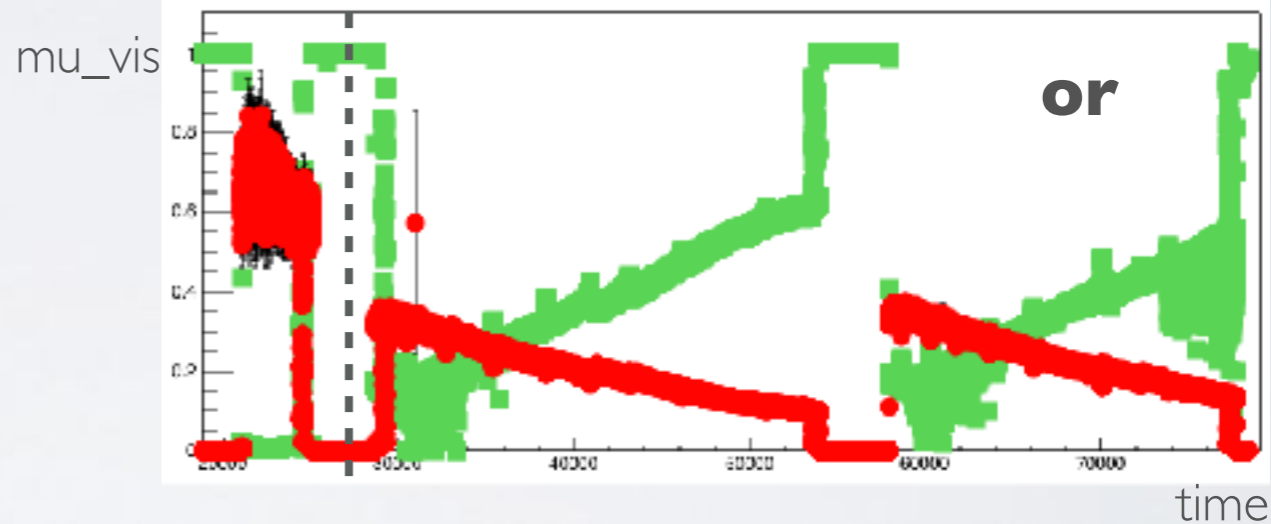
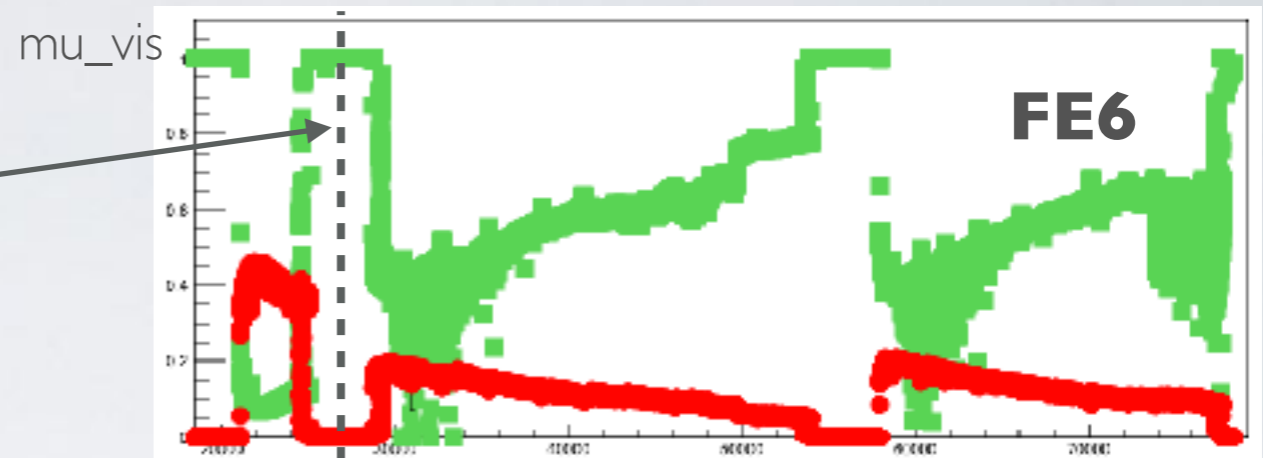
1,2%



RECORDING 22.

- 3 ATLAS runs within this recording
- mask changed between the 1st and 2nd run
- live fraction increased for factor ~ 5
- hit rate decreased for factor ~ 3

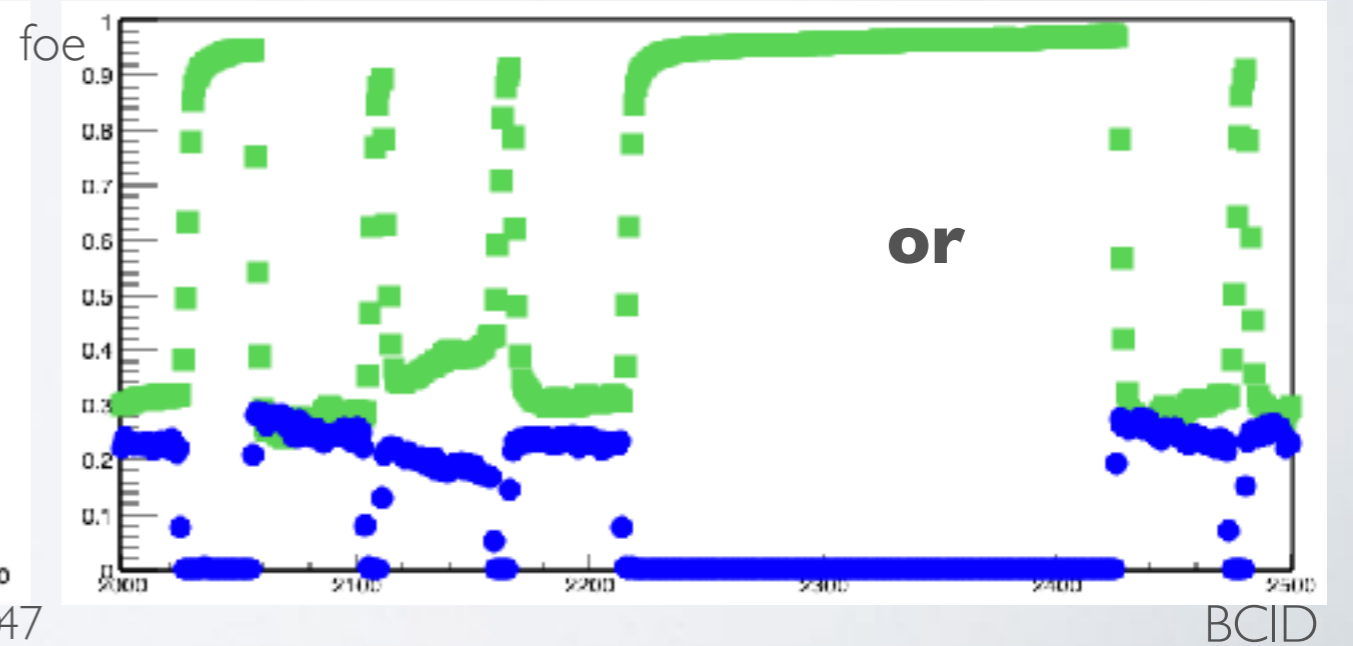
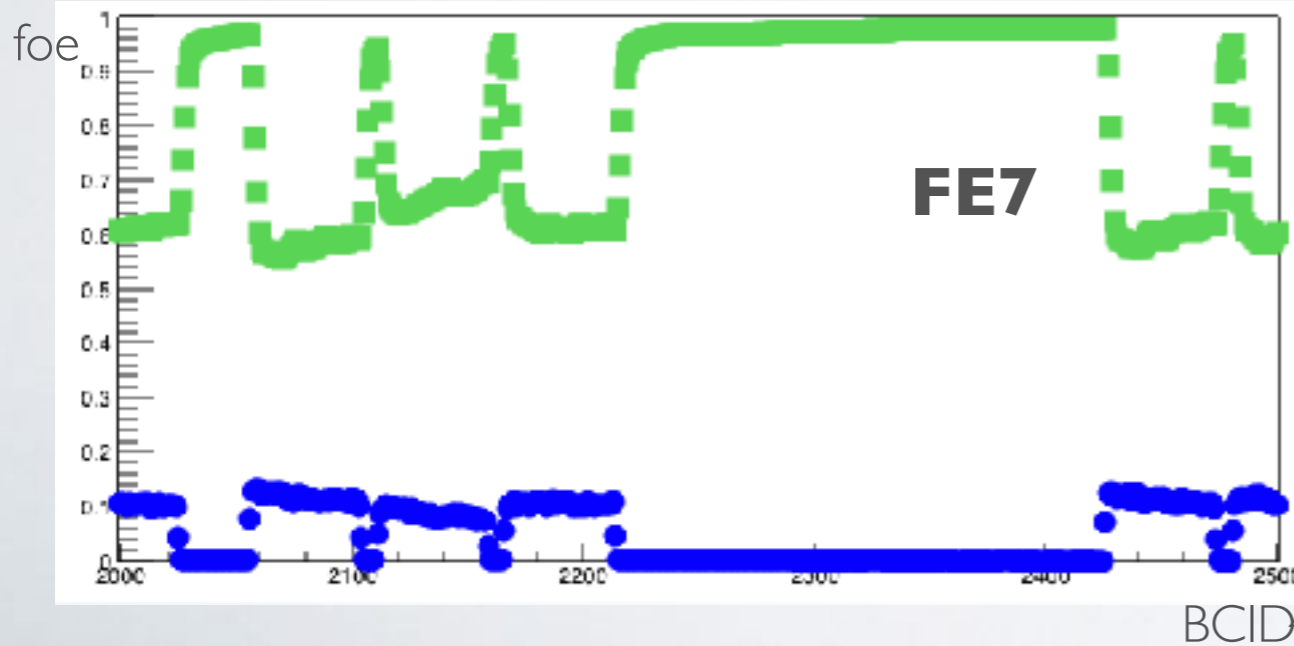
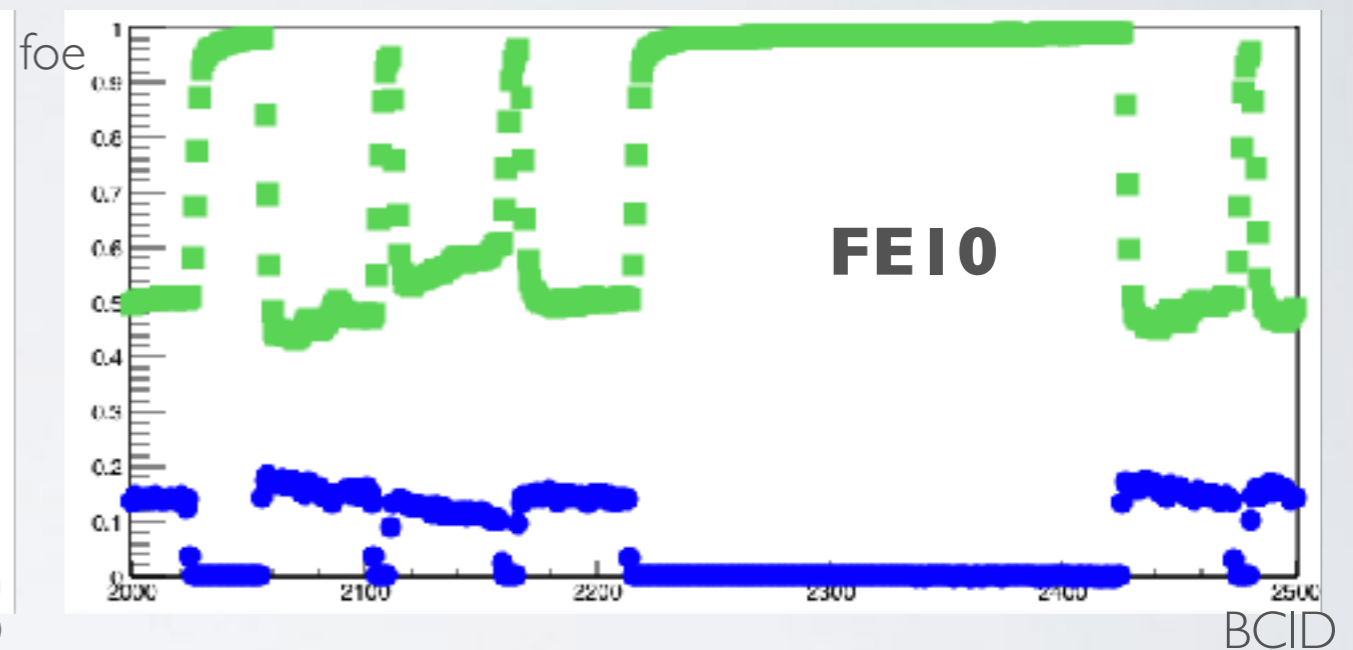
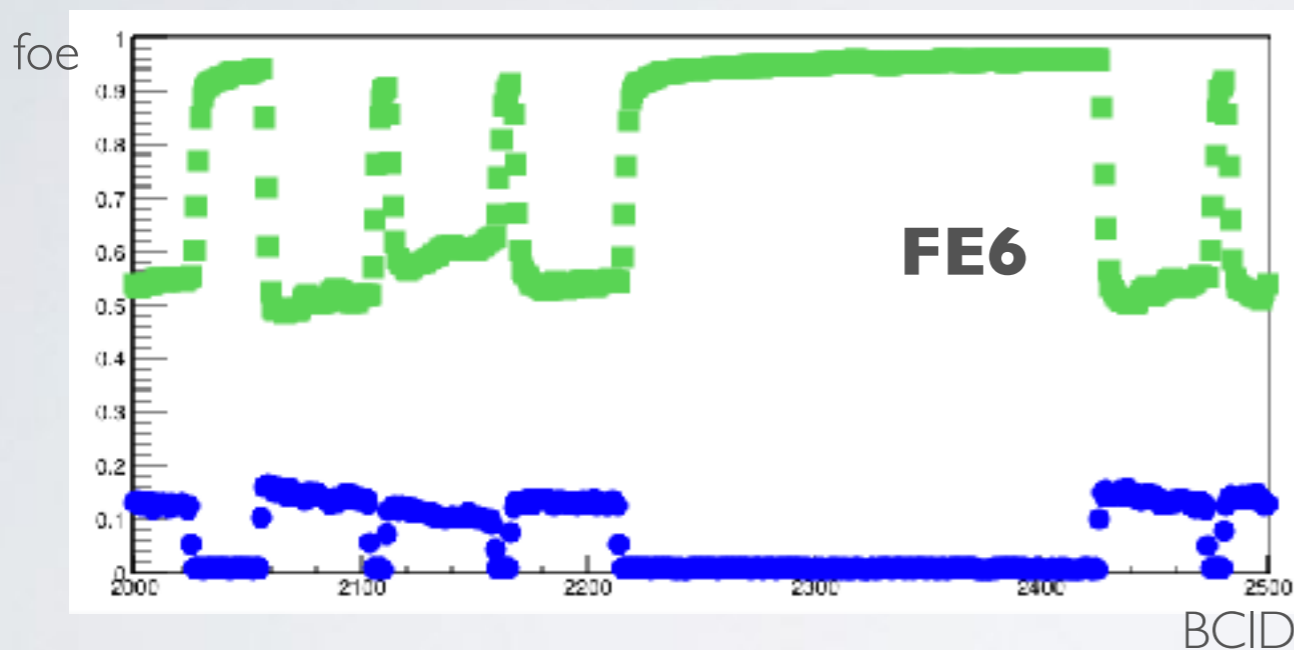
Algorithms	
0	single module FE6
1	single module FE7
6	single module FE10
7	or of two



RECORDING 22.

- comparison of algorithms within run 2

Algorithms	
0	single module FE6
1	single module FE7
6	single module FE10
7	or of two



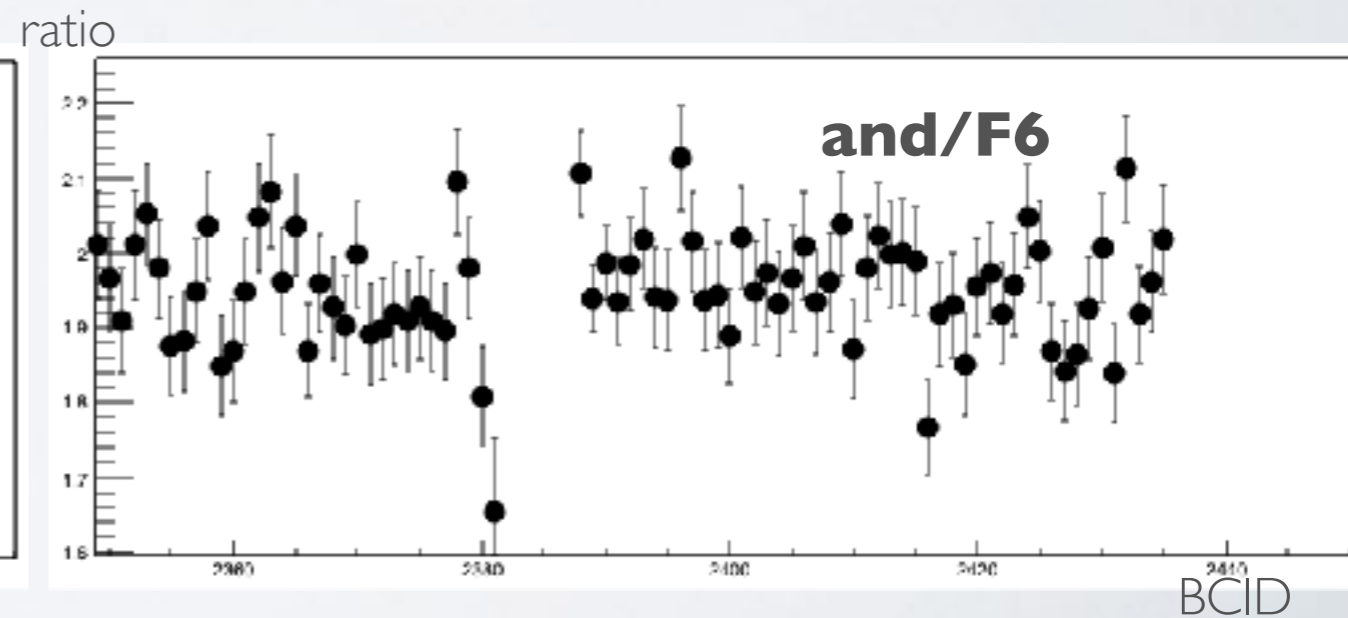
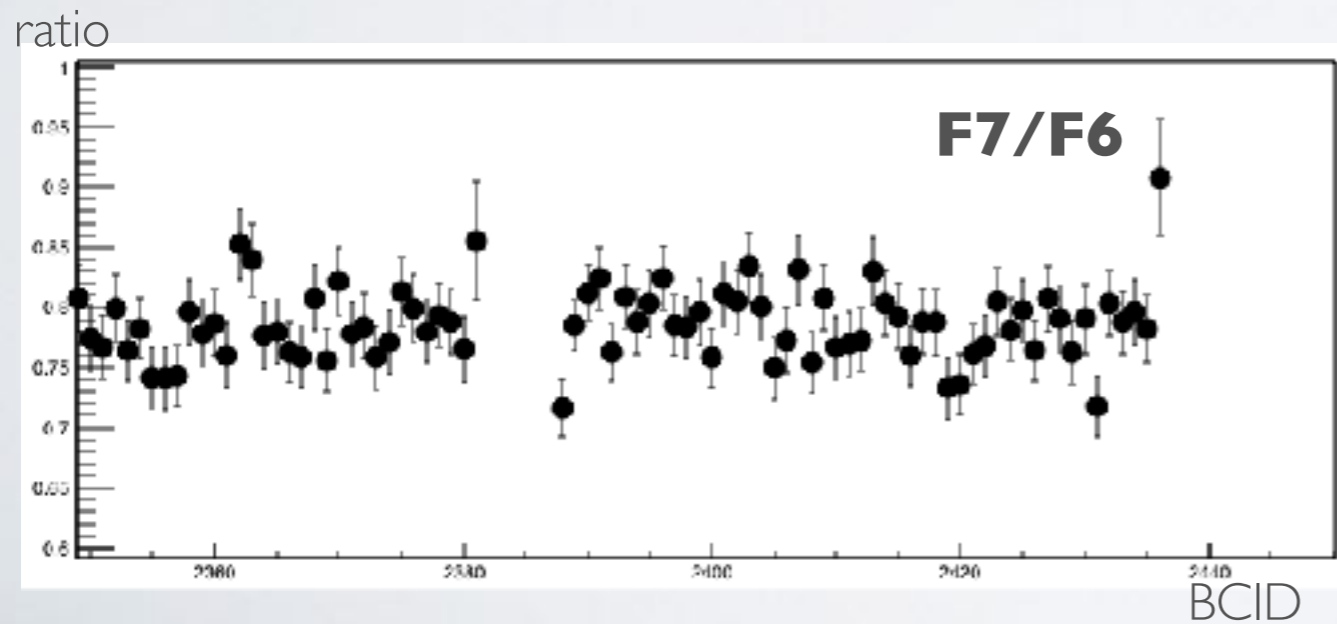
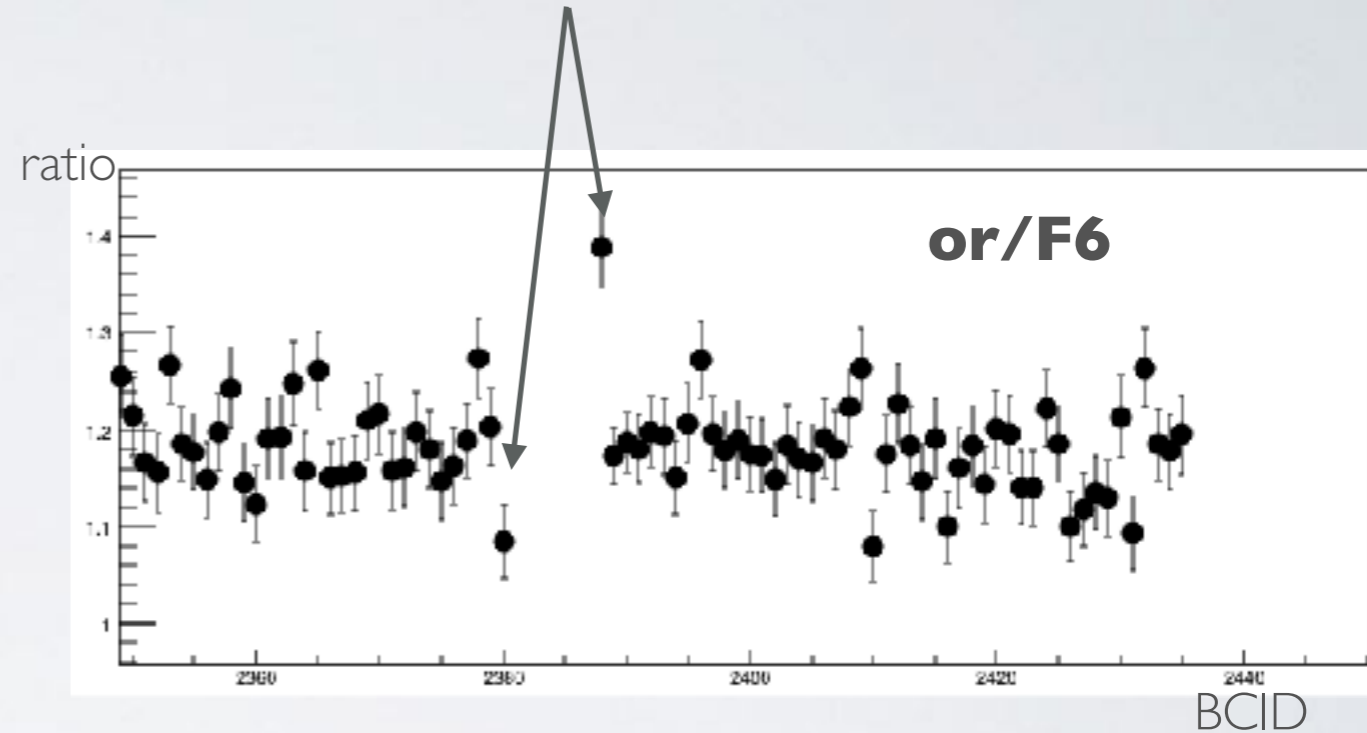
RECORDING 22.

- run 2 used for comparing algorithm consistency
- algo0 = F6 taken as a reference

$$\text{ratio} = \frac{\text{lumi}(\text{algo X})}{\text{lumi}(\text{algo 0})}$$

- ratio should be independent of BCID and time

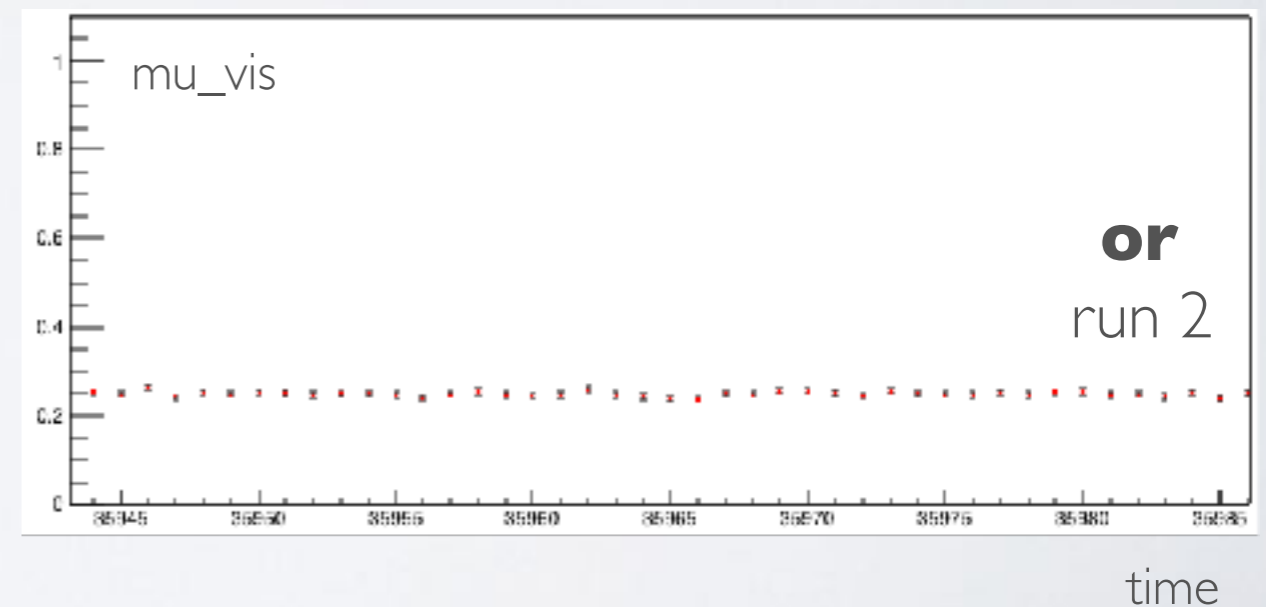
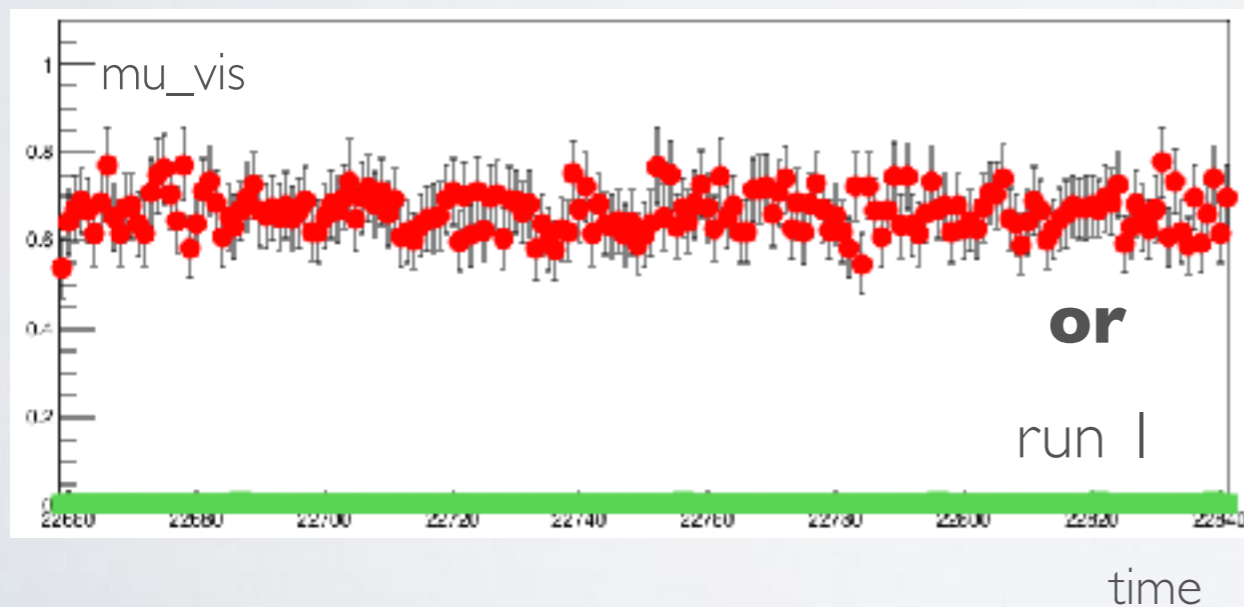
first and last still stand out



RECORDING 22.

- comparison of statistical errors for a single reading
- main drive of change is the effective area
- statistical error estimated on μ_{vis}

μ_{vis}	run 1	run 2
F7	0.35 ± 0.01 (2,8%)	0.1 ± 0.003 (3,0%)
or(F7,F10)	0.7 ± 0.07 (10%)	0.3 ± 0.007 (2.4%)



RECORDING 22.

- knowledge of the stat. errors so far
- for single module algorithms we are in the right region
- for combinations of 2 modules we should not increase the size much
- reducing the active area?
 - estimating that would not help
 - measured rate is decreasing already so we would start losing statistics

area	error
1	3,0%
2	2,4%
4	2,8%
8	10%

correct area for
this level of
understanding

ALGORITHM SETUP-5

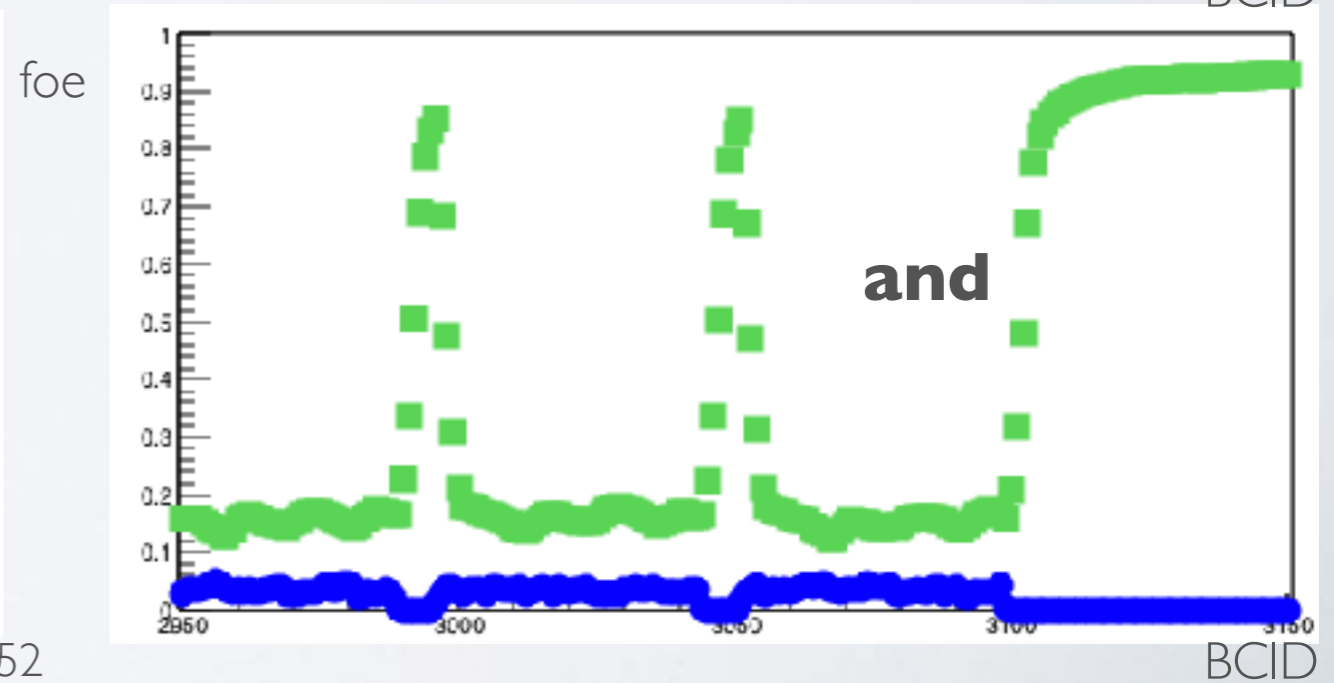
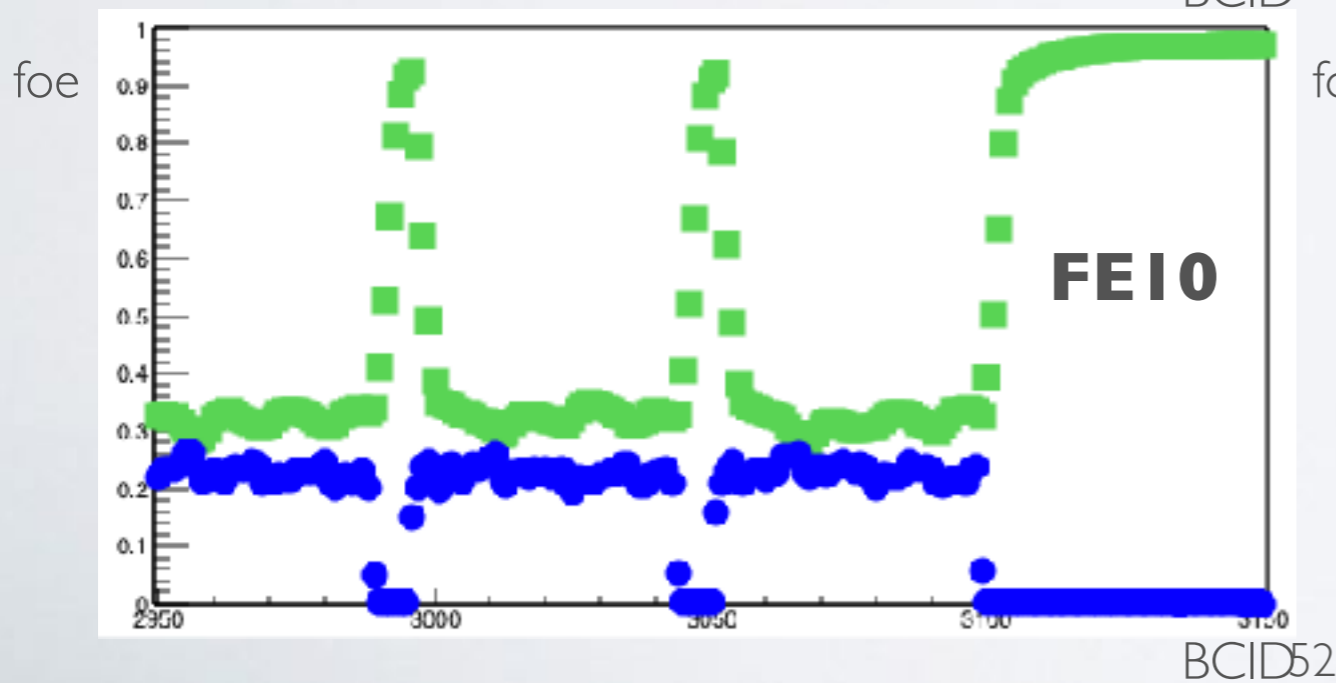
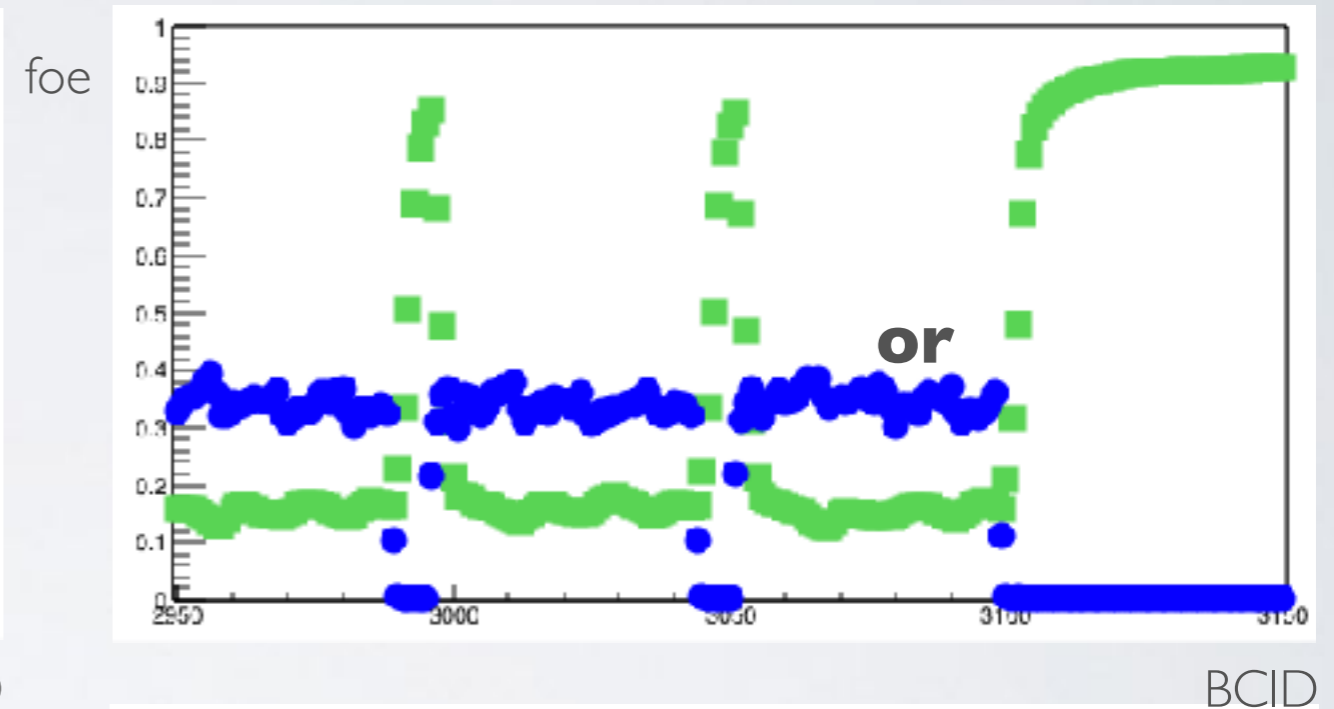
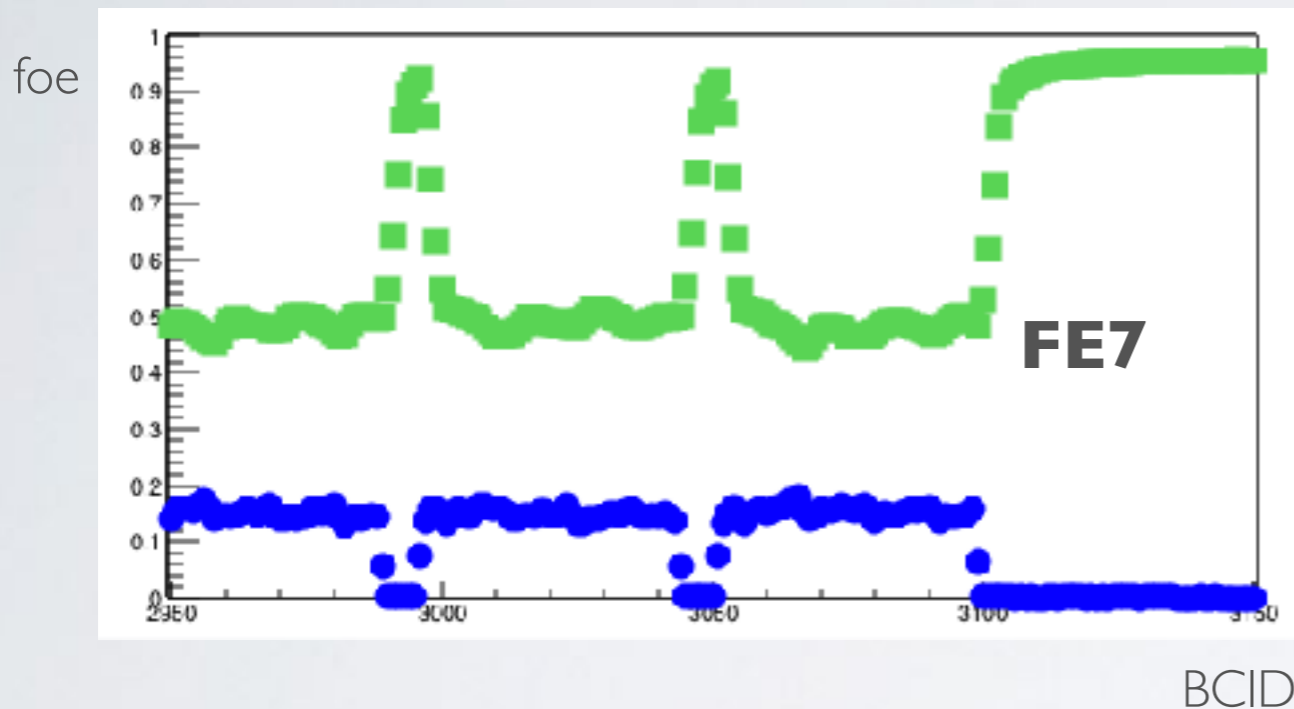
- running only side C - only HB-34 used
- so far: M3 give some signal, FE10 recovered, high level of live fraction



FPGA	Stream	Map	Algorithm	Logic
South	0	0	0	FE7 - single module
		1	1	FE10 - single module
	1	0	6	or(FE7, FE10) - or
		1	7	and(FE7, FE10) - and

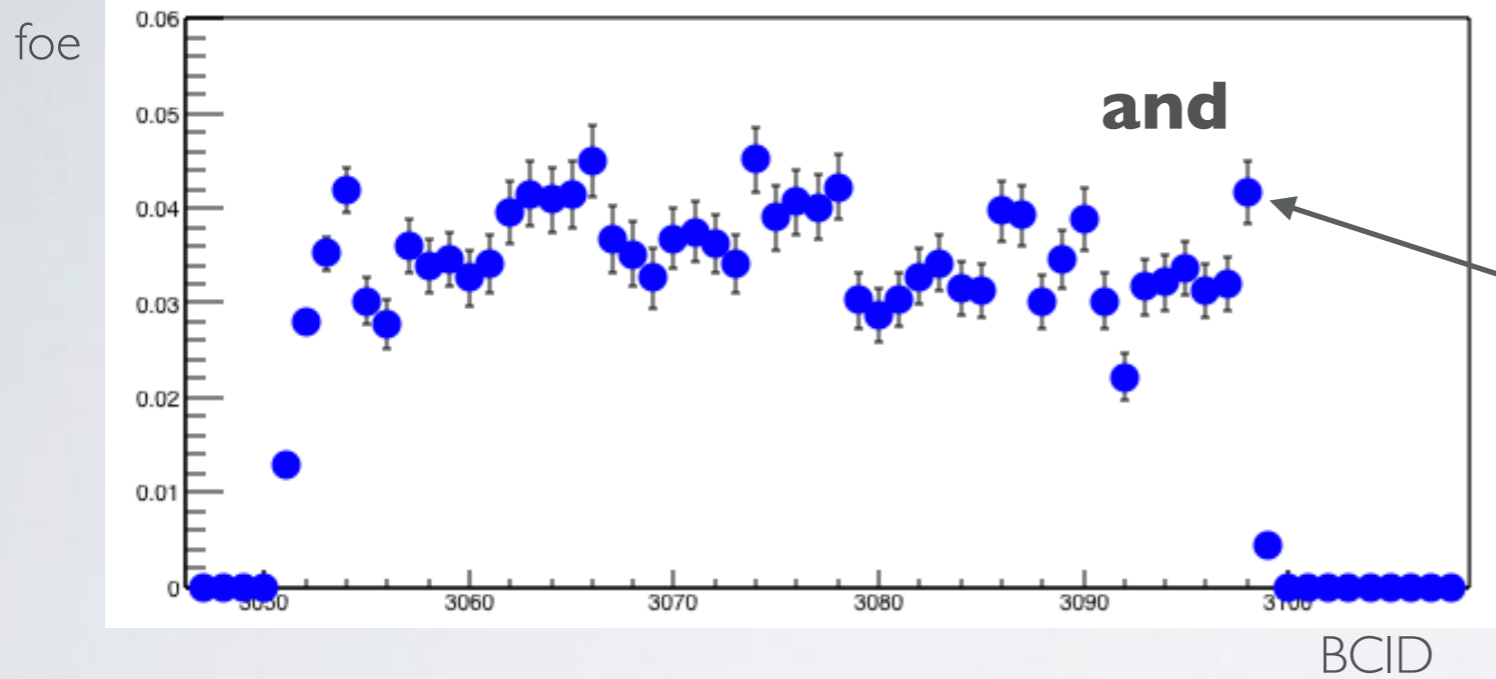
RECORDING 25.

- comparison of AND and OR algorithm
- algorithm consistency can not be checked because of different mu-correction for 'AND'

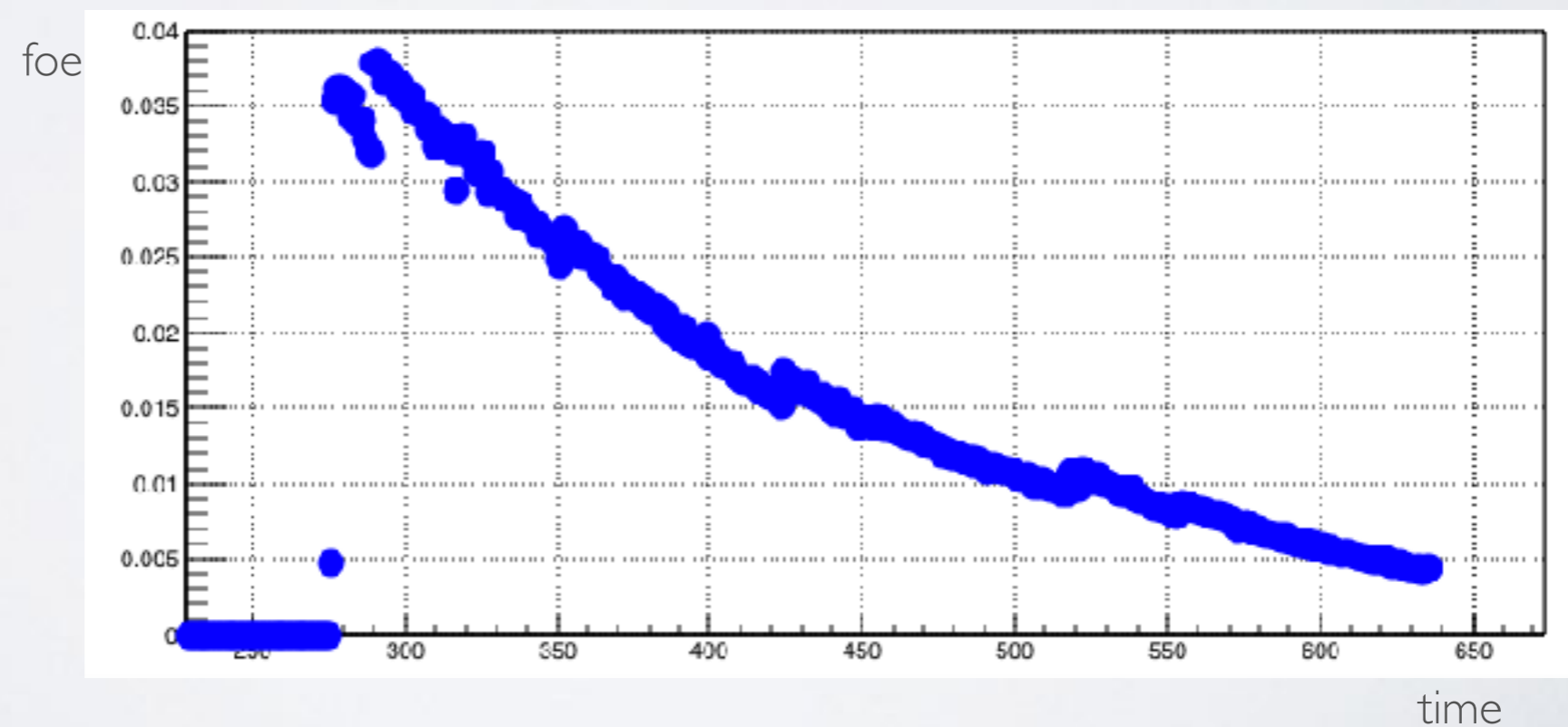


RECORDING 25.

- 'AND' algorithm data

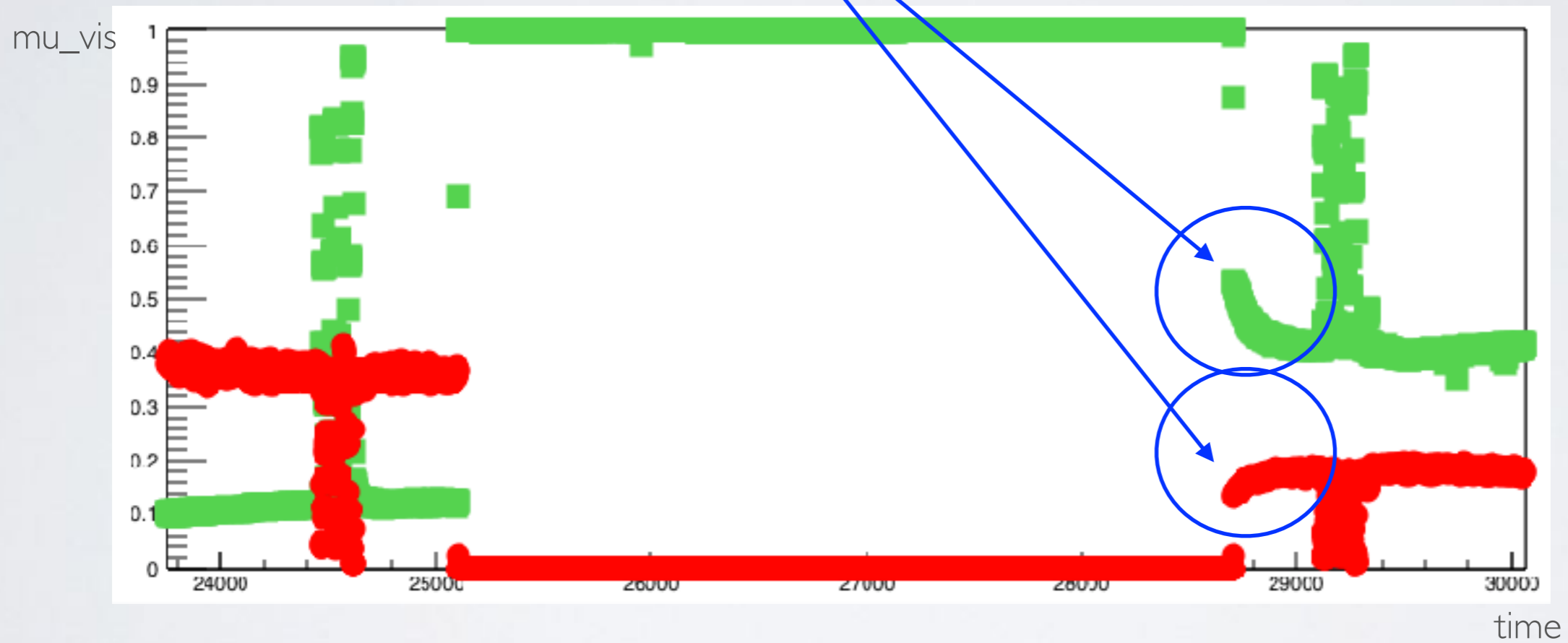


borderline statistics



OTHER

- a time constant in the detector response observed
 - order of ~ 5 min

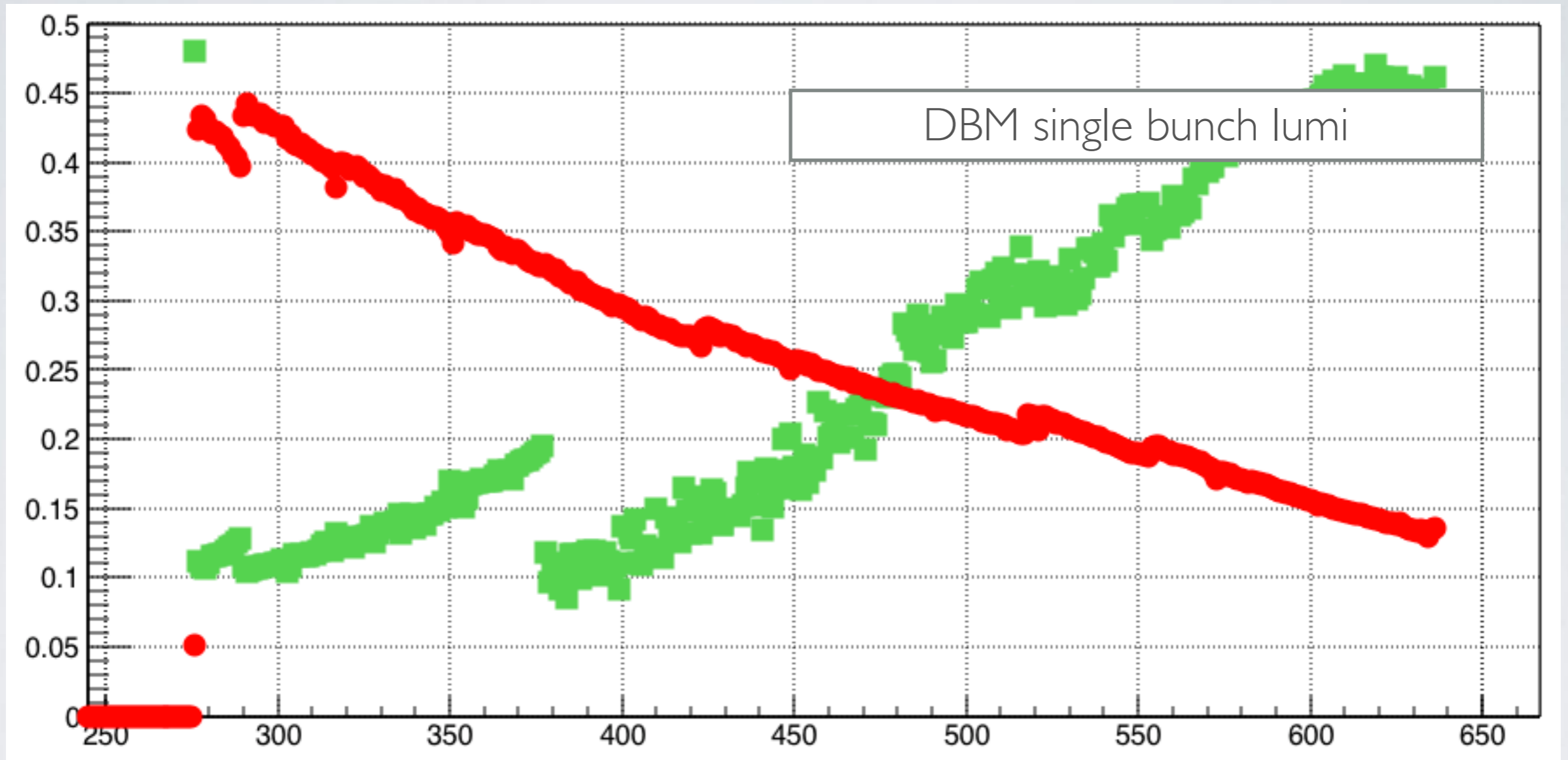


CONCLUSION

- luminosity readout system operational and reliable - no issues in 3 weeks of usage
- configuration iterated to a sensible working point
- no absolute calibration obtained
- some systematic issues remaining - more data and configurations would be needed

SAMPLE DATA

μ_{vis}



sample

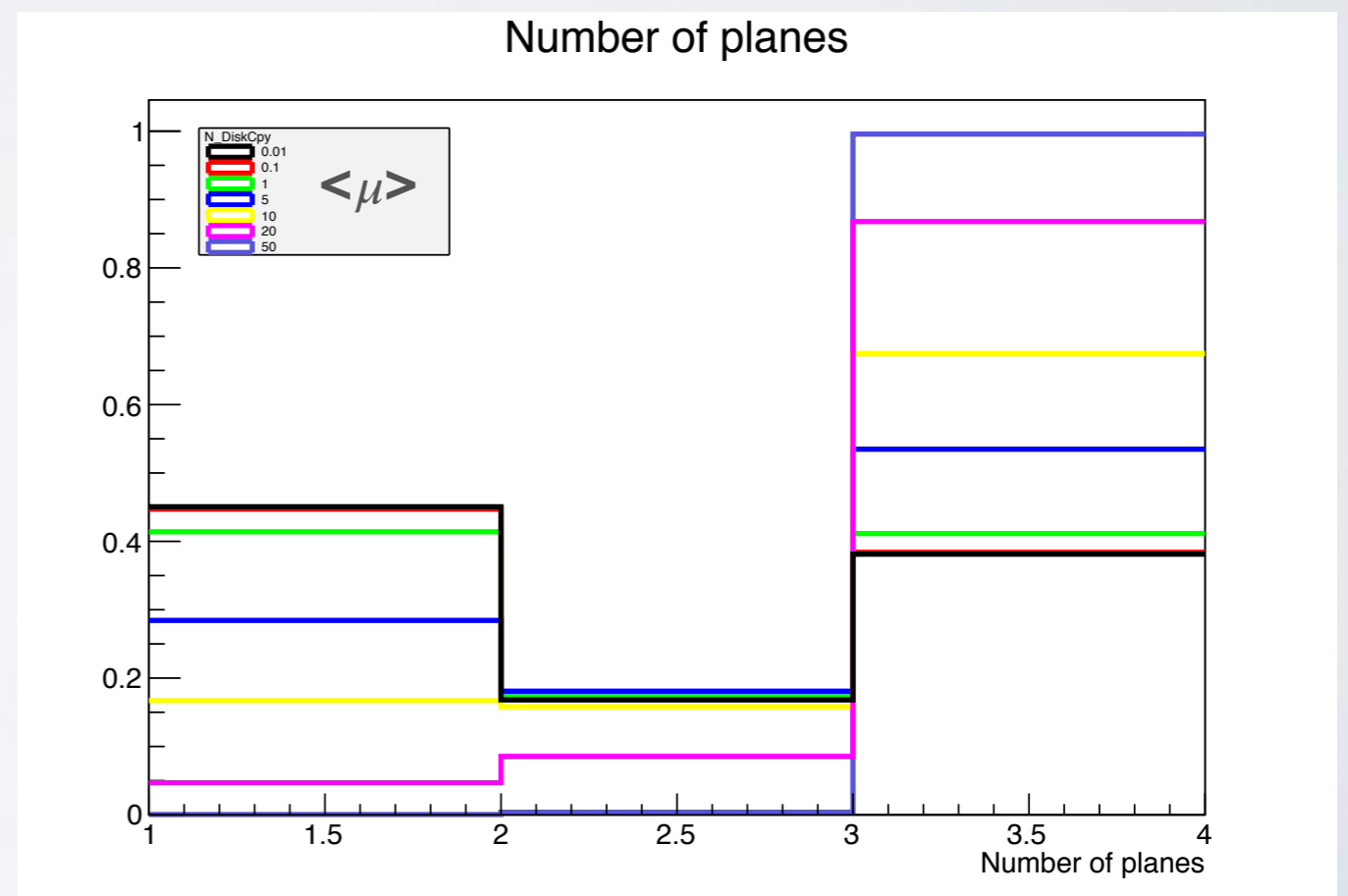
BACKUP

ORIENTEERING WITH SIMULATION

- full ATLAS simulation up to hit-level used
- low pT minimum bias sample of 10^7 events :
 - mc14_13TeV.119995.Pythia8_A2MSTW2008LO_minbias_inelastic_low.merge.HITS.e3038_s2045_s2008

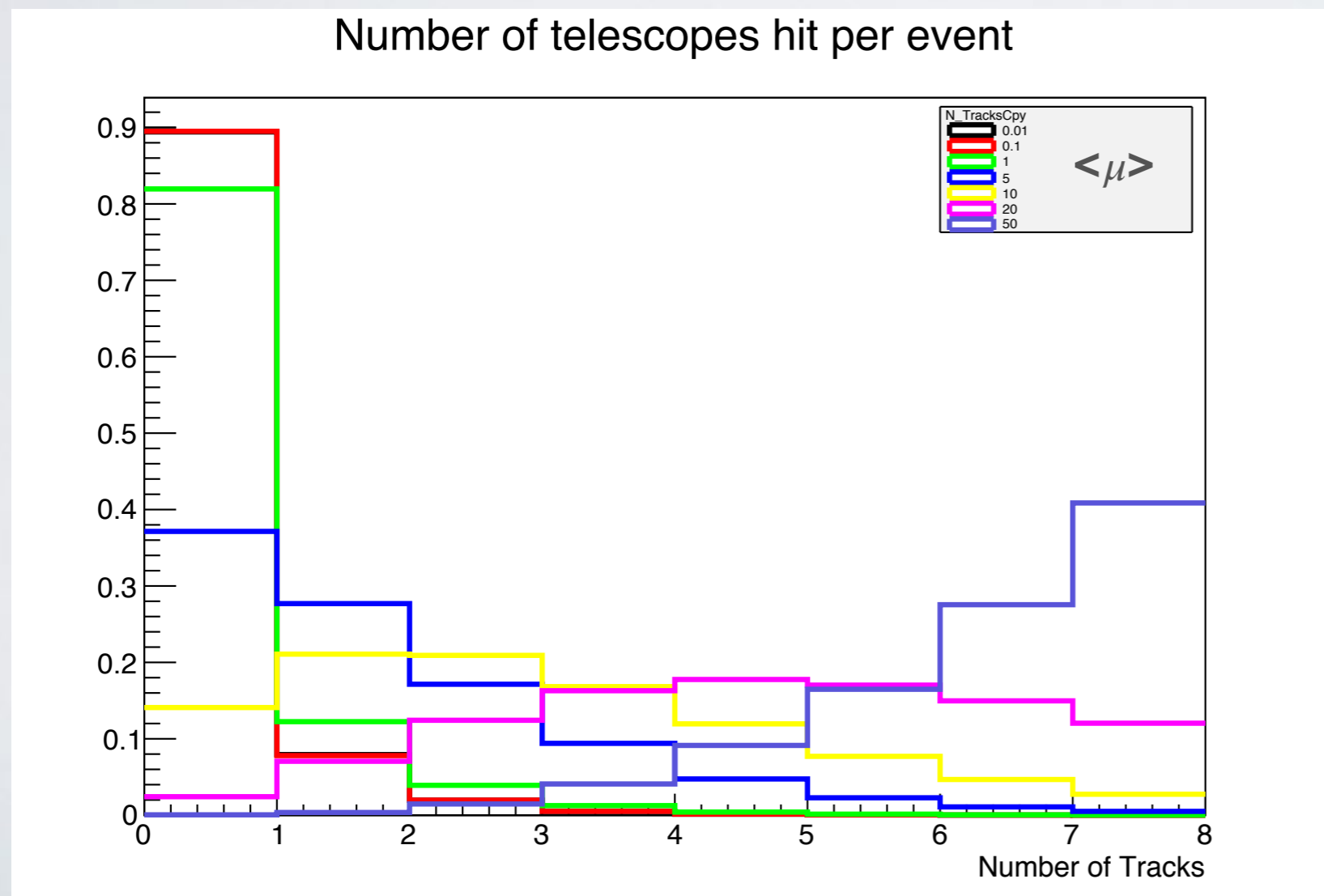
Probabilities

$\langle \mu \rangle$	Cpx (plane 0)	Cpx
0.01	0.00133 9	0.00197 9
0.1	0.01331 9	0.01962 1
1	0.12544 8	0.17973 7
5	0.48882 8	0.62880 1
10	0.73828 6	0.86176
20	0.93176 5	0.98077 8



T-STREAM POINT OF VIEW

- interested in number of tracks
- probability for event with given number of tracks in one telescope:

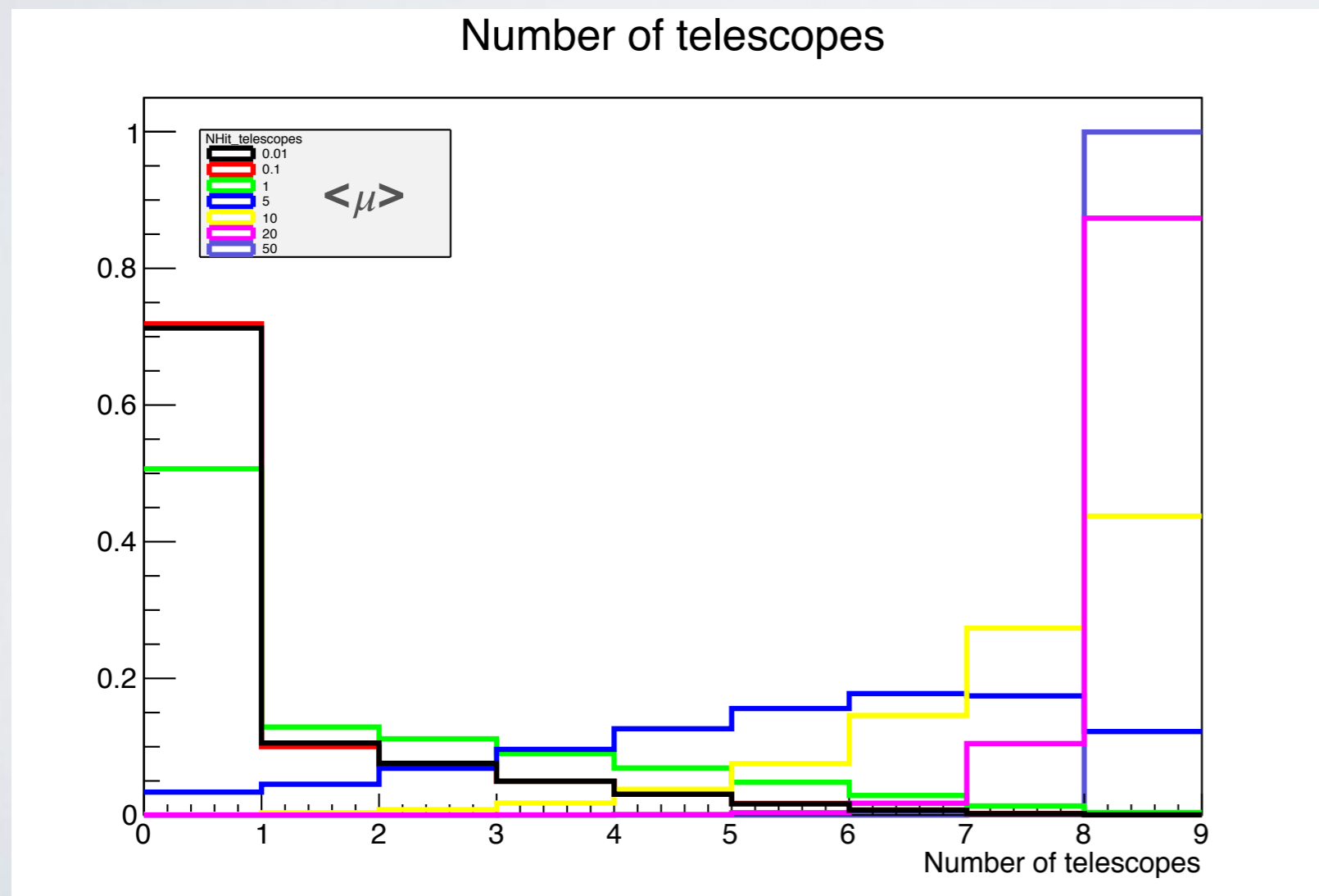


no apparent problems with this measurement approach

one could fit the distribution to get the number of pp collisions

H-STREAM POINT OF VIEW

- interested in number of planes or telescopes hit (single HitOr signal provided)
- probability for event with given number of telescopes hit:

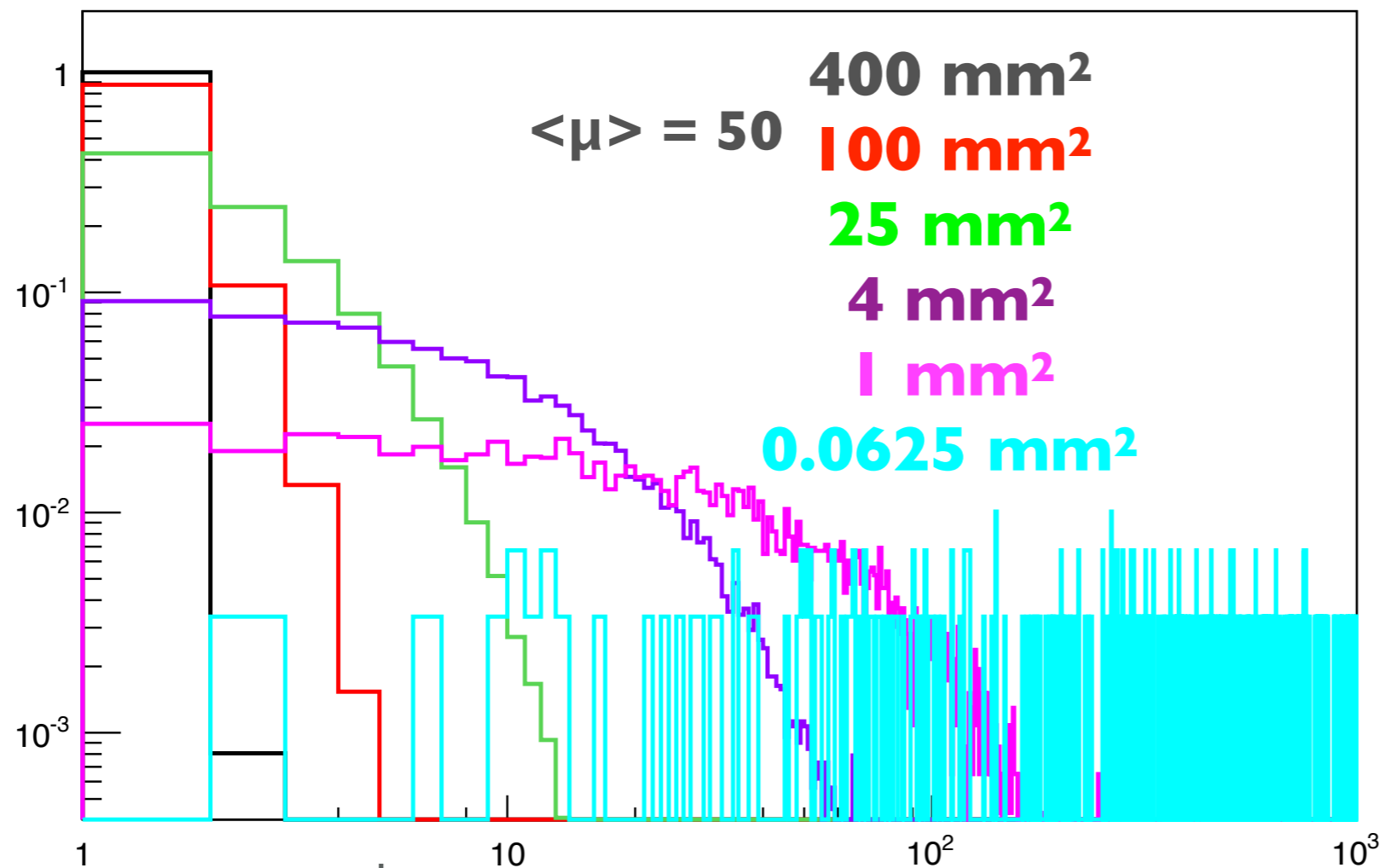


shows saturation at high luminosity

all telescopes hit, meaning that consecutive bunch collisions will result in HitOr='1'

H-STREAM MASK AREA

BCID distance between the hits for plane 0 of CPX

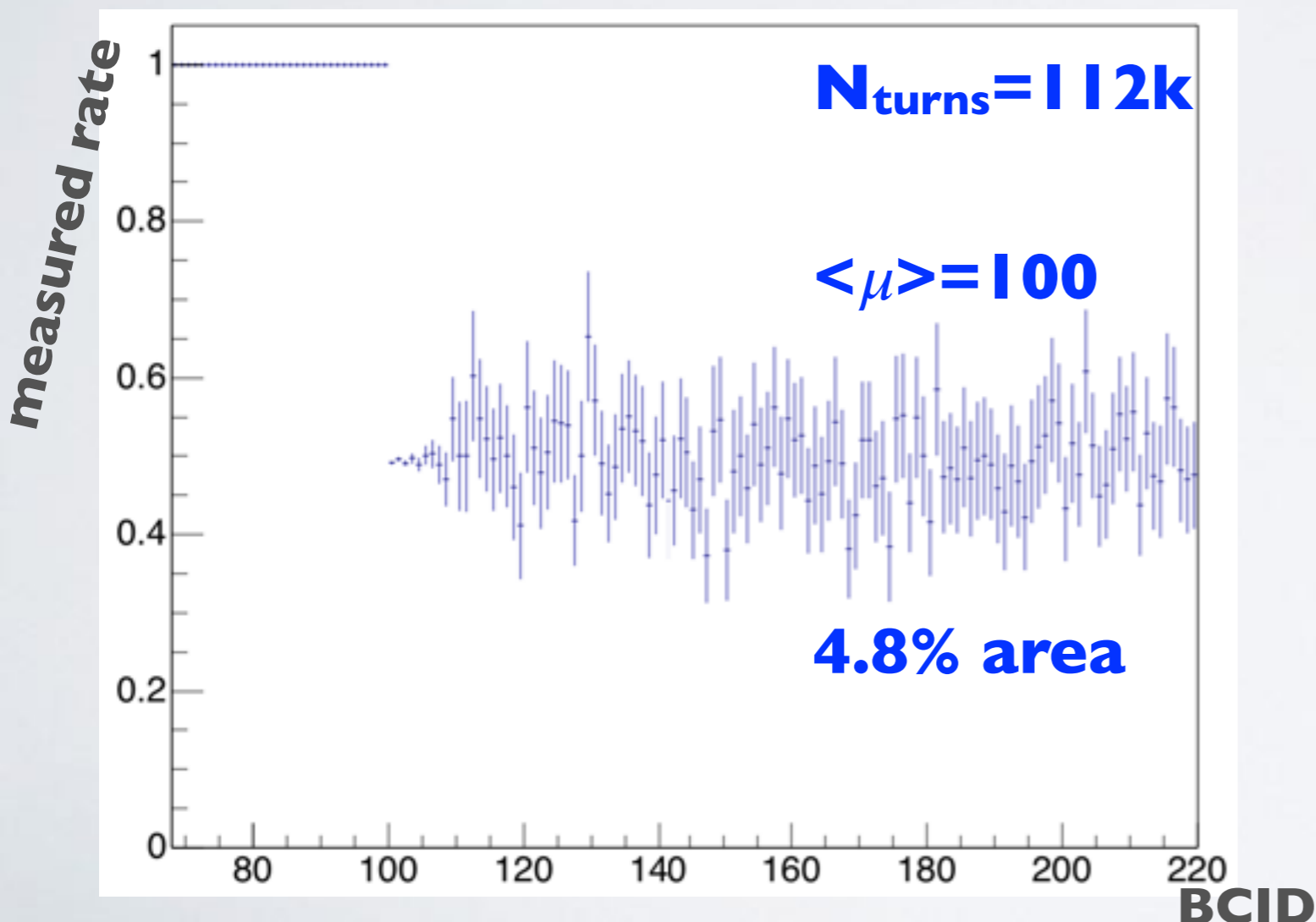


←
unseen because
of pileup

- simple case $ToT=5$ always:
- if only $I=0,3\%$ of area is active $\sim 10\%$ events are missed

SIMULATED RATE

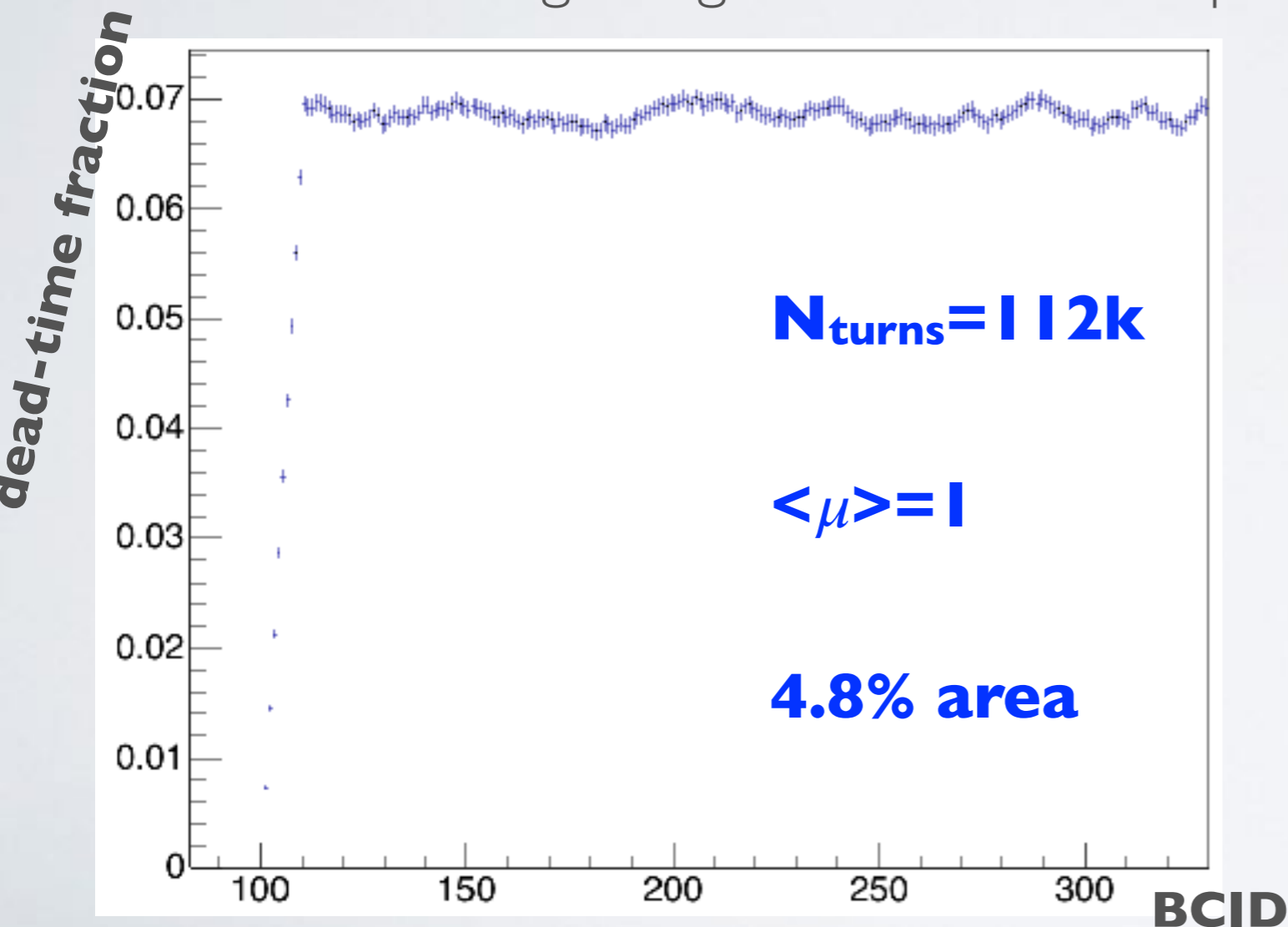
- rate of observed events for 0-counting (empty events fraction)
- statistical error significantly better for start of the bunch train



- extreme case
- masking of pixels provides means to make DBM saturation free also for highest luminosity
- biggest challenge will be to make detector fast + precise due to statistical error

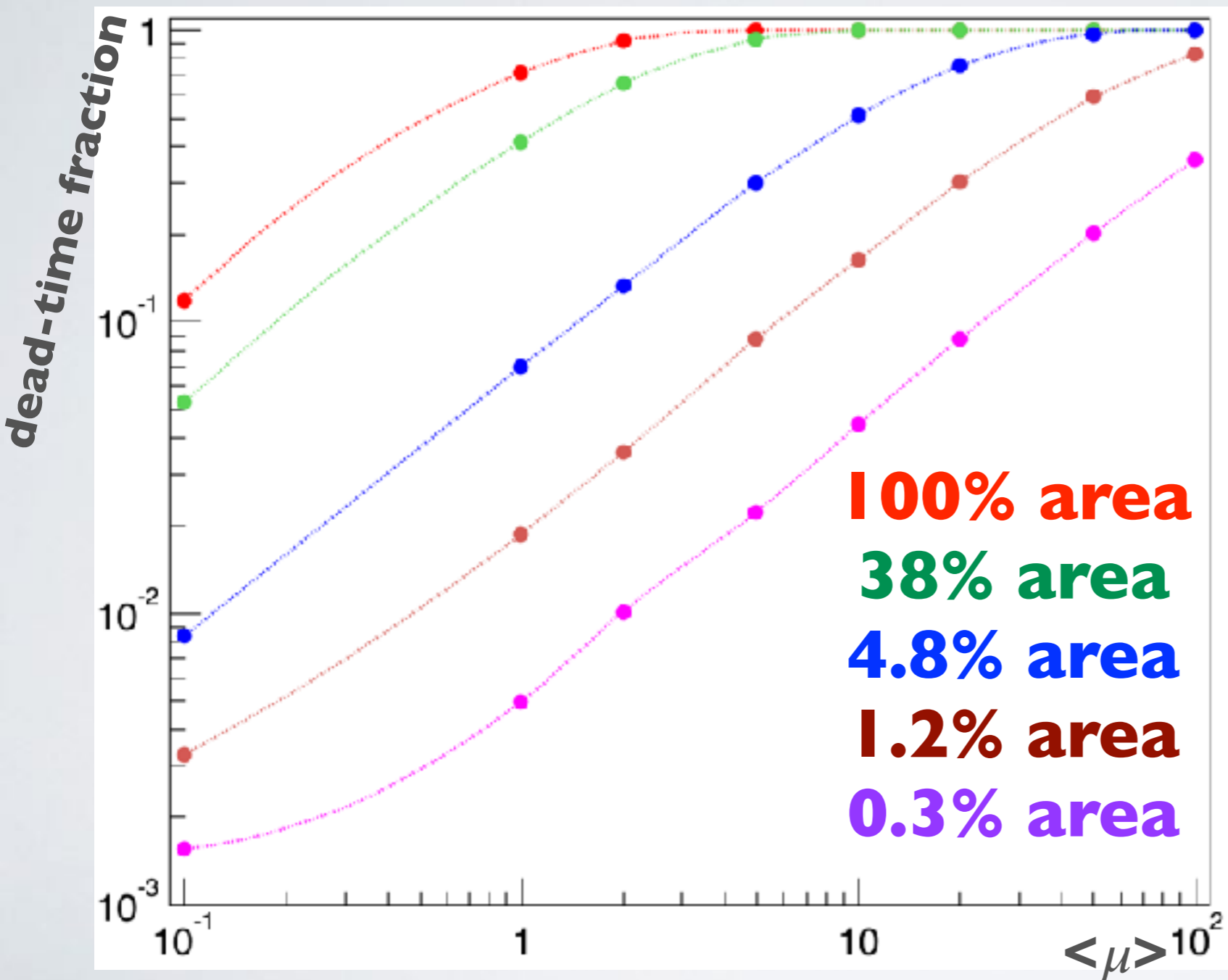
SIMULATED DEAD-TIME

- dead time defined as fraction of time where HitOr is constant and equals '1'
- rise time on beginning of bunch train depends on ToT calibration



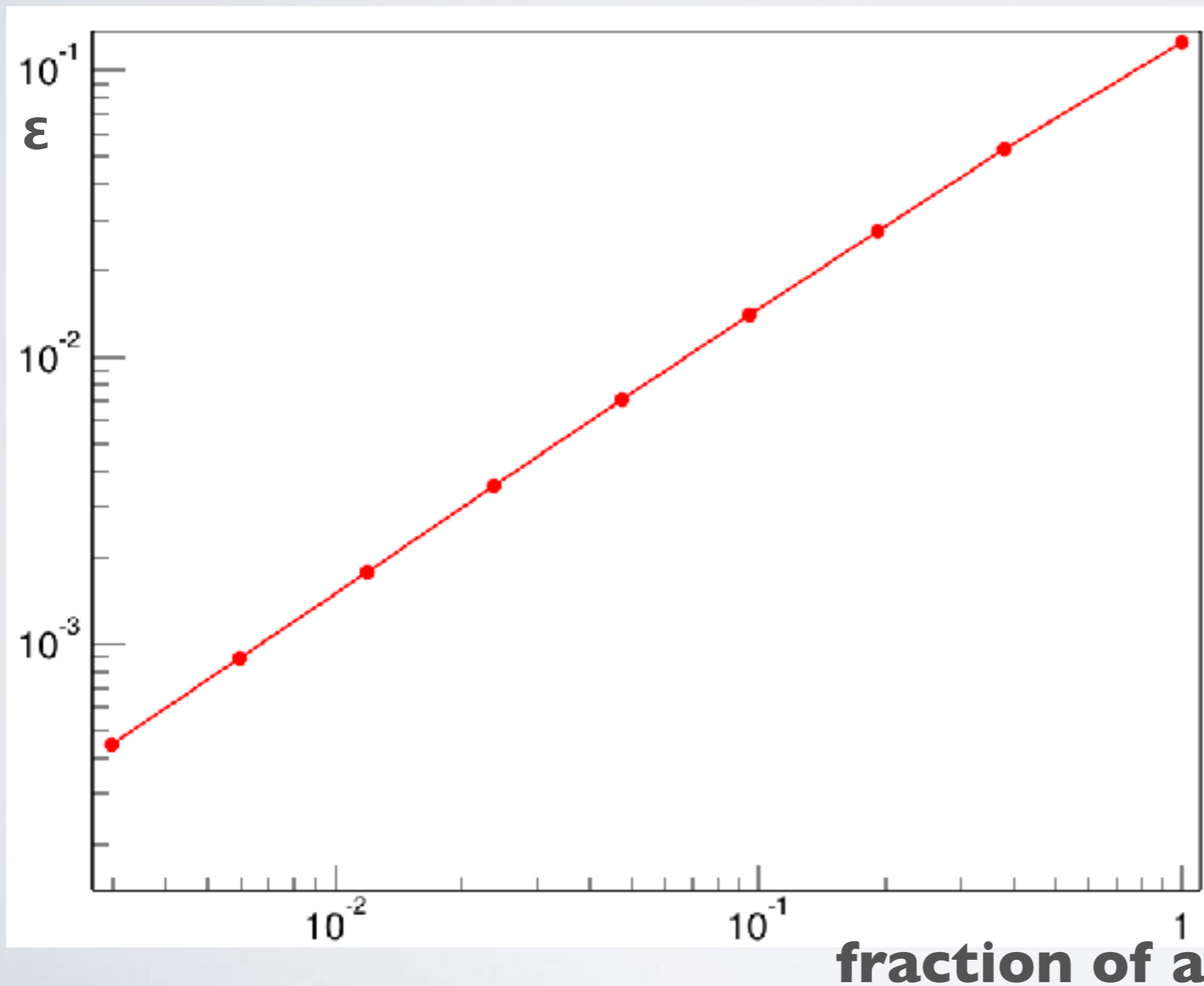
- statistical significant fluctuation of dead-time
- pattern more pronounced when we near saturation region
- will reduce in real life, because Landau charge distribution has not been taken into account

DEAD-TIME FRACTION



- statistics reduction can be a problem for DBM
- we might need to adapt mask according to expected luminosity
 - not a robust system
 - unfortunately a quick set of a mask within a feedback loop might not be doable + it costs time

EFFICIENCY



- efficiency for HitOr is a function of active area
- determined for 0-counting algorithm:

$$r = e^{-\langle \mu \rangle} \epsilon$$

- with simulated rate and knowledge about true $\langle \mu \rangle$ one can determine ϵ
- this can be used as first estimation of calibration