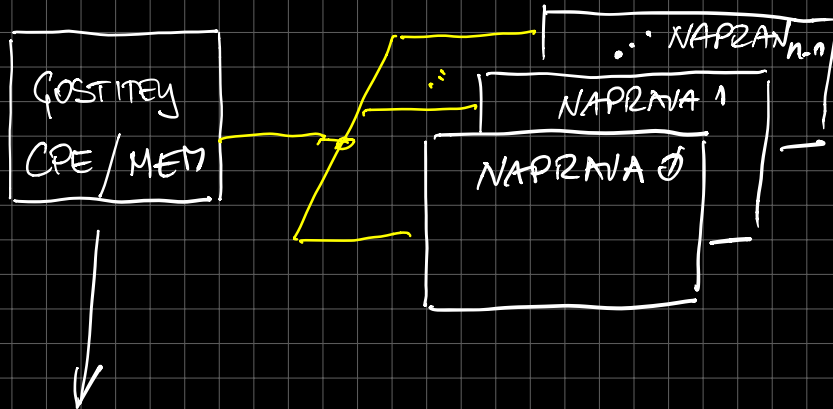


Delavnica "Programiranje CPE"

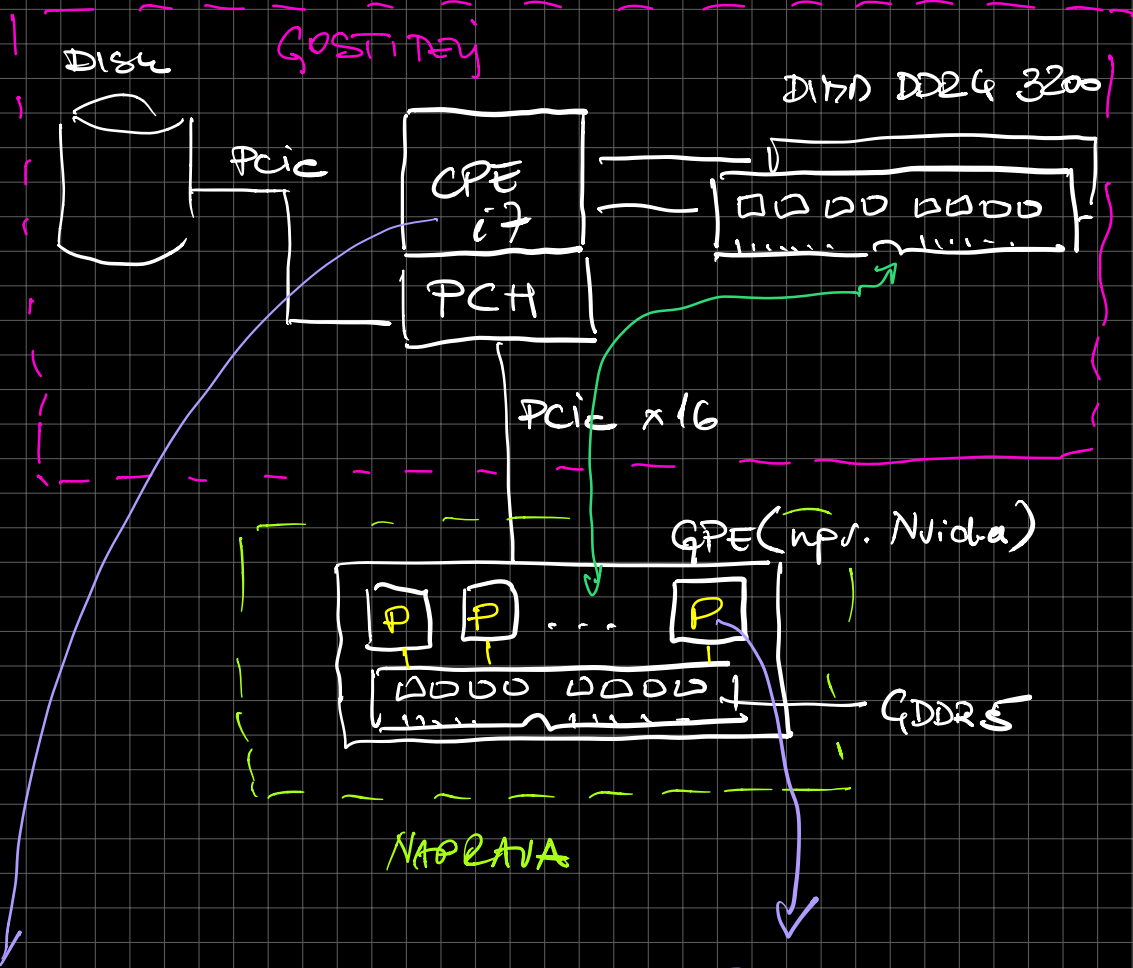
20.4.2021

HET. RAČ. SISTEM



- naloga:
- pripravi vse podatke za naprave
 - pripravi programe, ki se bodo izvajali na napravah
 - prenos podatkov med svojim MEM in posameznimi napravami
 - na naprave prenese program in ga izvede

Primer:



Program na posobitelu

- main() {

 {
 ↓
 API OpenCL
 }

Program na napravi

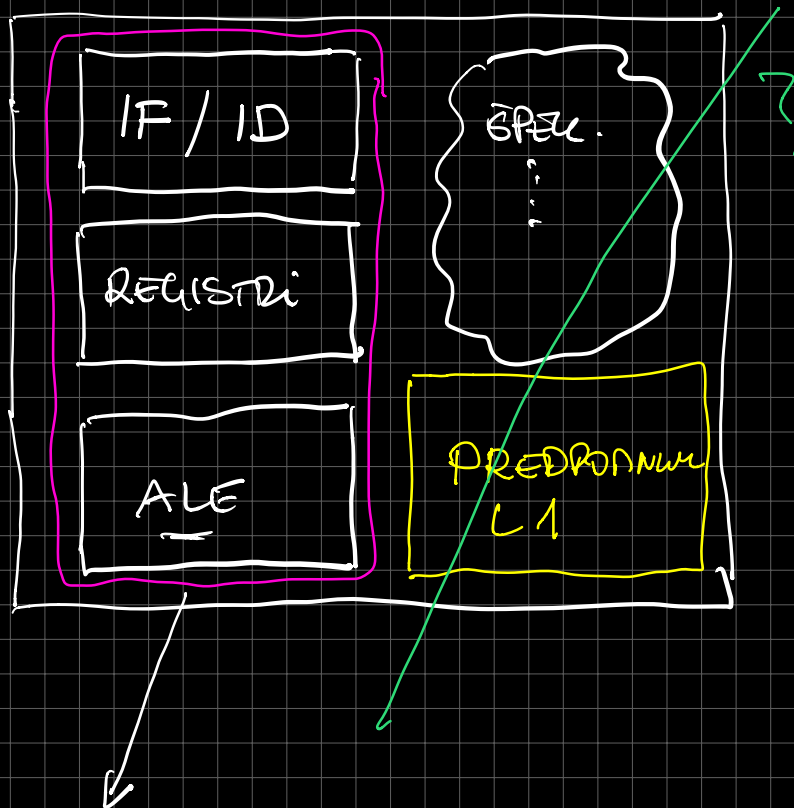
→ ŠČEPEC
(kernel)

--kernel --- () {

}

✓
Kljuba navodil se
preizgubi in tega izoper ne
popravi

CPE



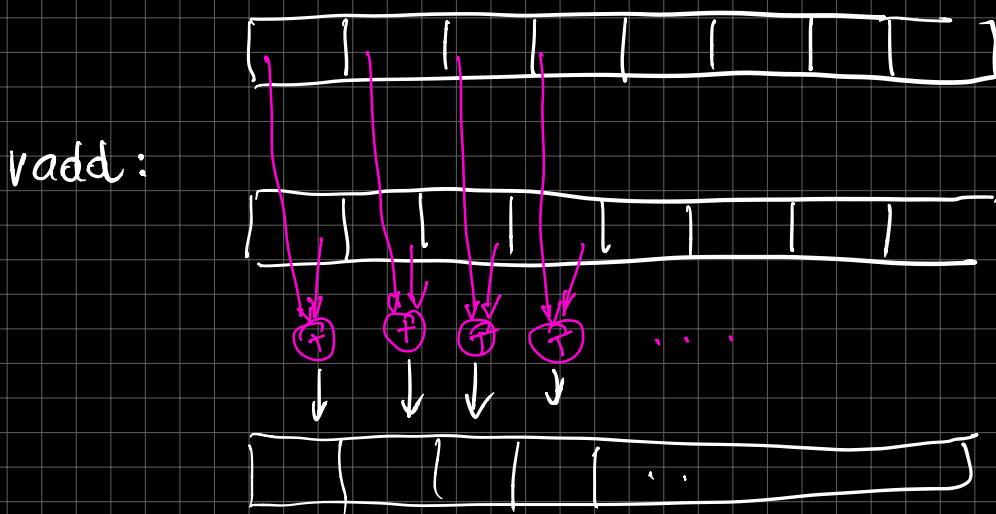
```
while (tid < 128) {
```

```
    c[tid] = a[tid] + b[bid];  
    tid += 1;  
}
```

1. evoluční kroky

→ SIMD → vektorová zpracování

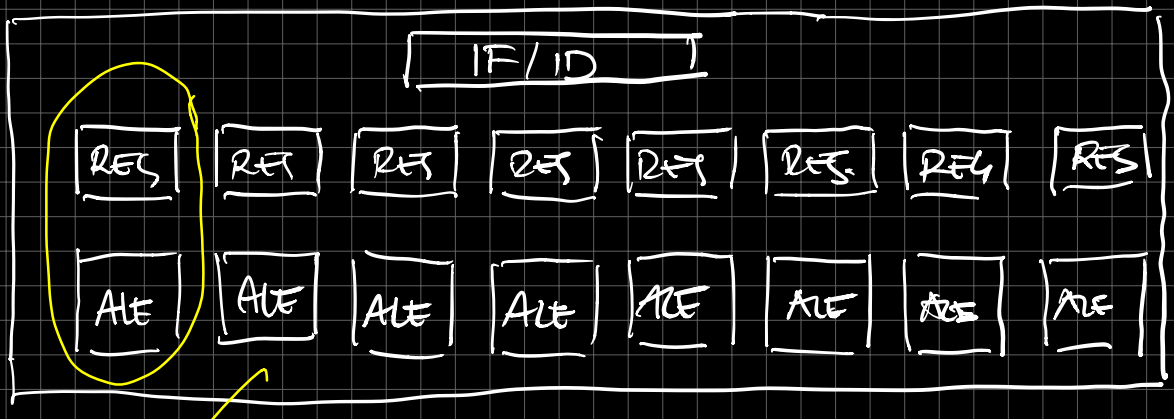
vektorová zpracování:



potřebujeme:

8 ALU

8x registrařích míst



while (tid < 128) {

c[tid : tid+7] =

a[tid : tid+7] + b[tid : tid+7];

tid += 8;

}

VSEH 8 ALU DOBI ISTOVASNO ISTO OPERACIJO,
KI JO PORAJNO IZVEDI

2. redy: ZAR evolvencje



```
c[tid] = a[tid] + b[tid];
```

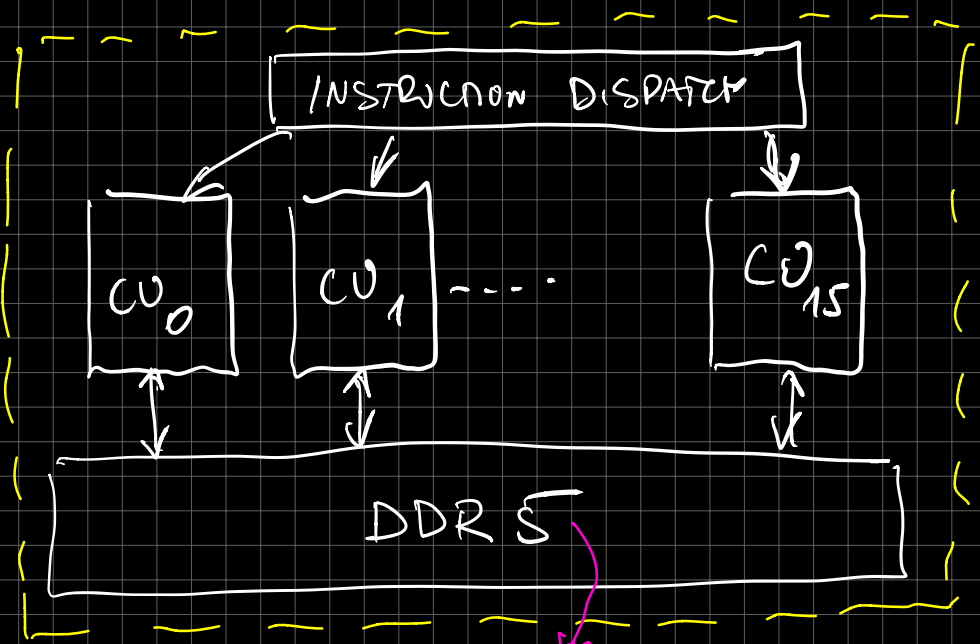
22
REF: 22
load reg1, r[tid]
load reg2, r[tid]
add reg1, reg2

u je CPU je te 8 (= 64 PE)

$$c[tid] = a[tid] + b[tid]$$

$$c[bid+be) = \dots$$

CPU

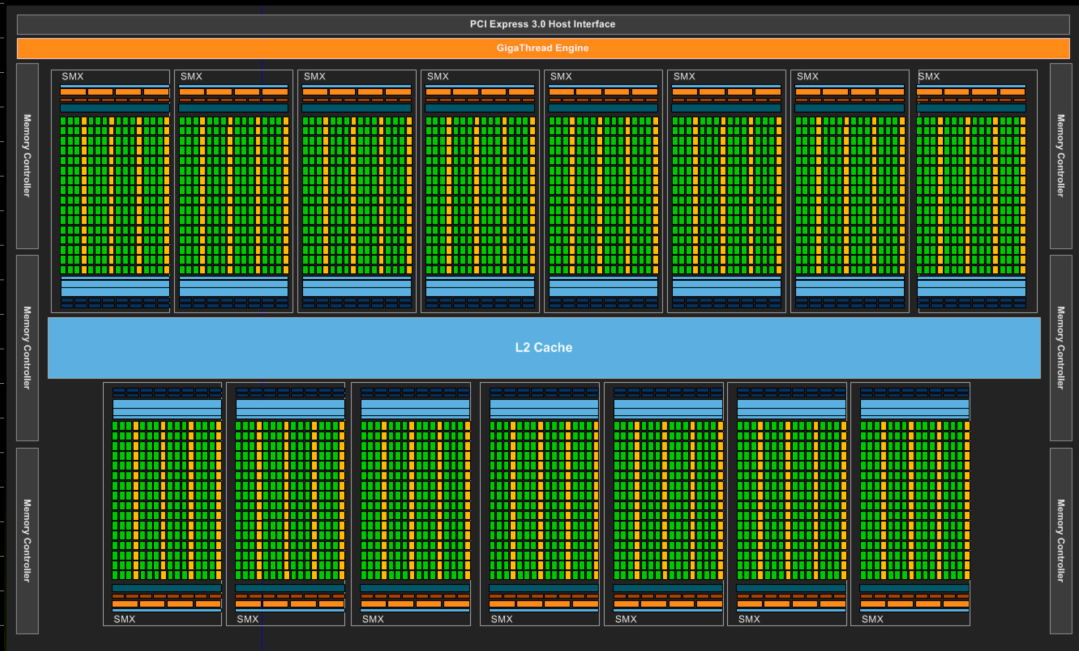
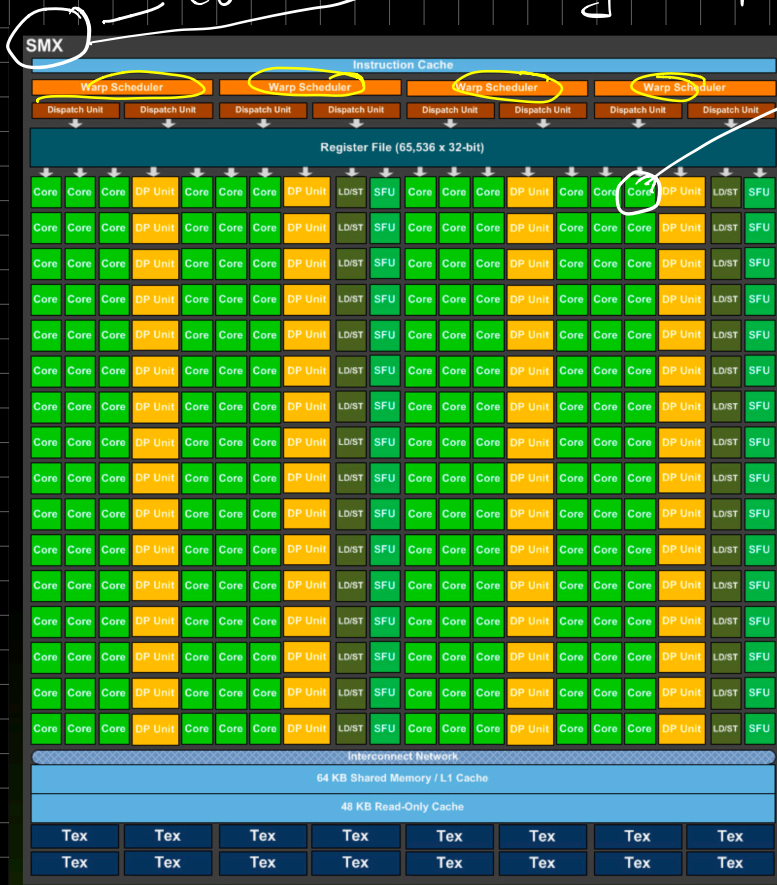


GLOBALNI POMILNIK

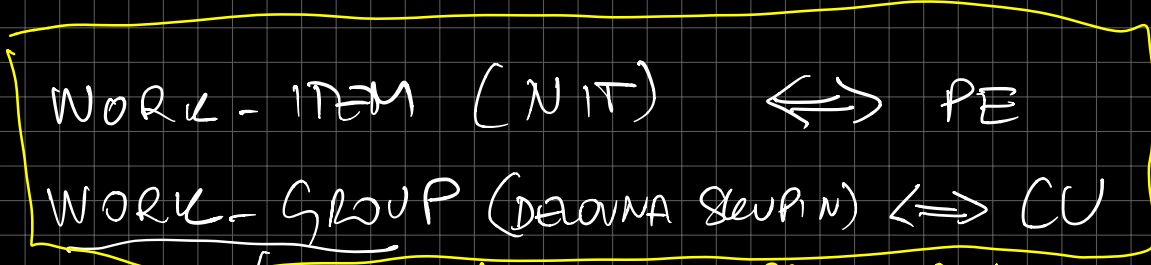
NVIDIA TESLA K40 :

CU

Streaming Multiprocessor



Operacijska ABSTRAKCIJA HW



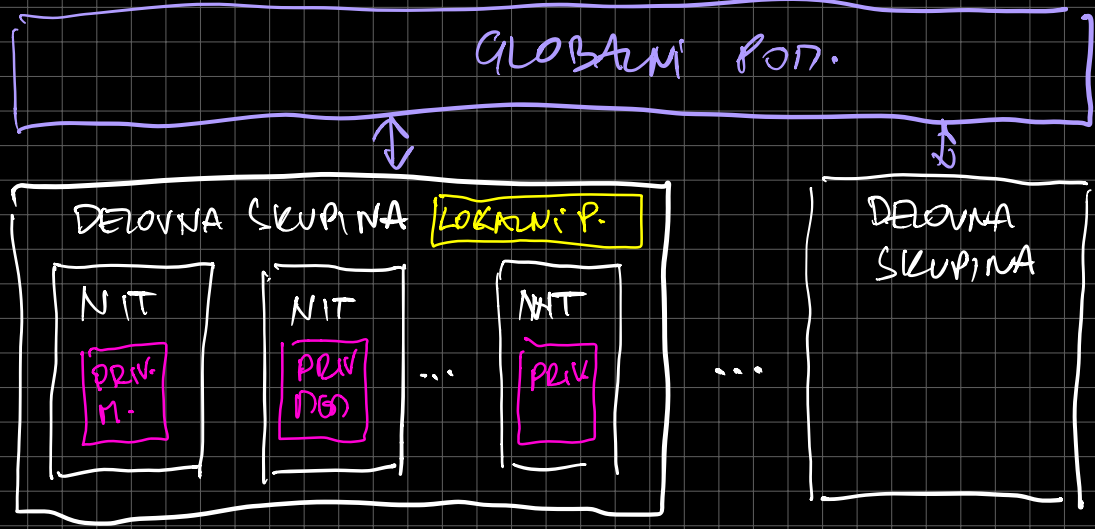
ABSTRAKCIJA PROJEKTA ENOT

- Večanje nit, ki se izvaja na eni CU

GLOBAL MEMORIJA \leftrightarrow GLOBALNI DDRS PODNIK

LOCAL MEMORIJA \leftrightarrow LOCALNI SRAM PODNIK

PRIVAT MEMORIJA \leftrightarrow REGISTERI



OpenCL

OpenCL API

→ knjižnica funkcij
ki jih uporabljajo
programi na posrednikju

OpenCL C

prog. jezik C
vornev, pisarji
šopcer

OpenCL deluje

→ preden gostitelj prevede skripto za
napravo, mora upotat: deluje:

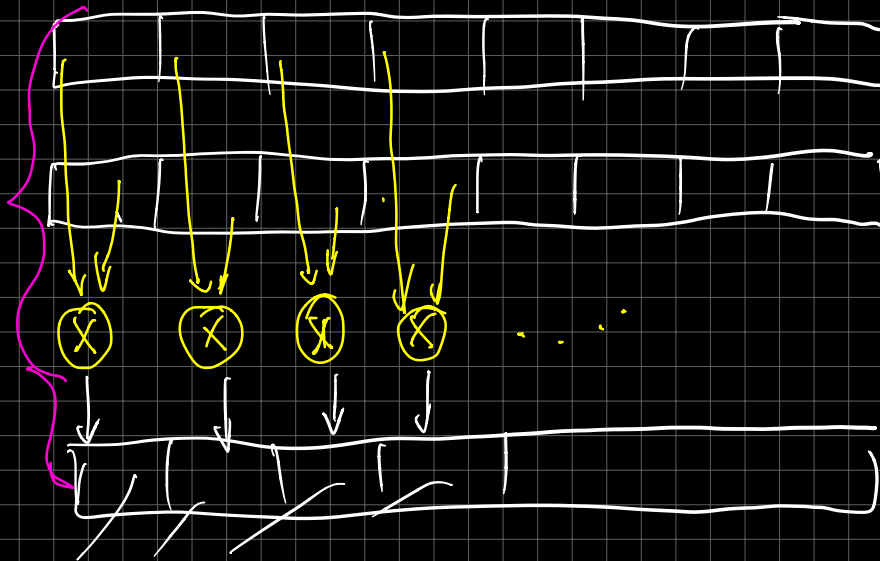
1. Gostitelj ⇒ PLATFORMA
(npr. Nvidia ali AMD)

2. Naprave

IZ TEGA USNVAJAMO KONTEXT

→ naprave, programi, vrne
vrate in sm. dostop

PRVI PROGRAM NA GPE:

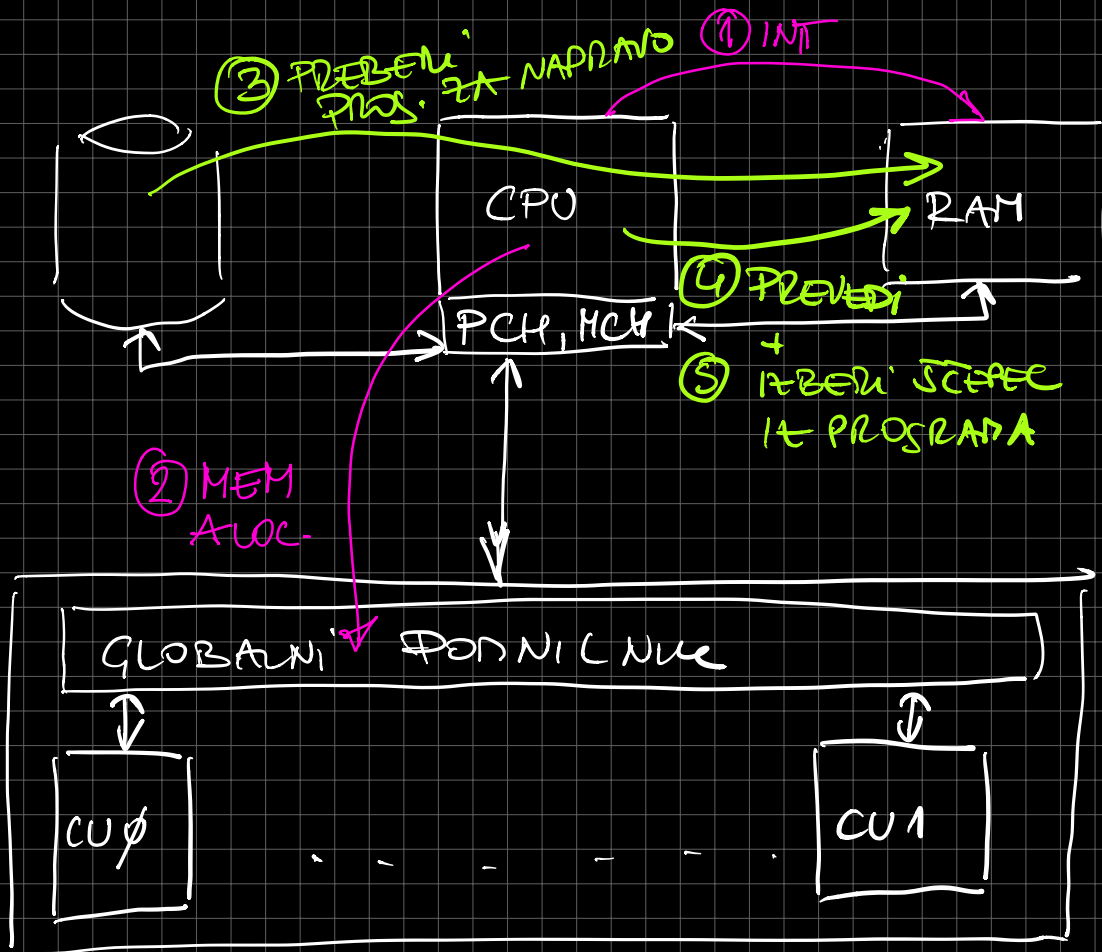


Σ

Štoper → navodilo za eno samo nit

$$c[tid] = a[tid] * b[tid];$$

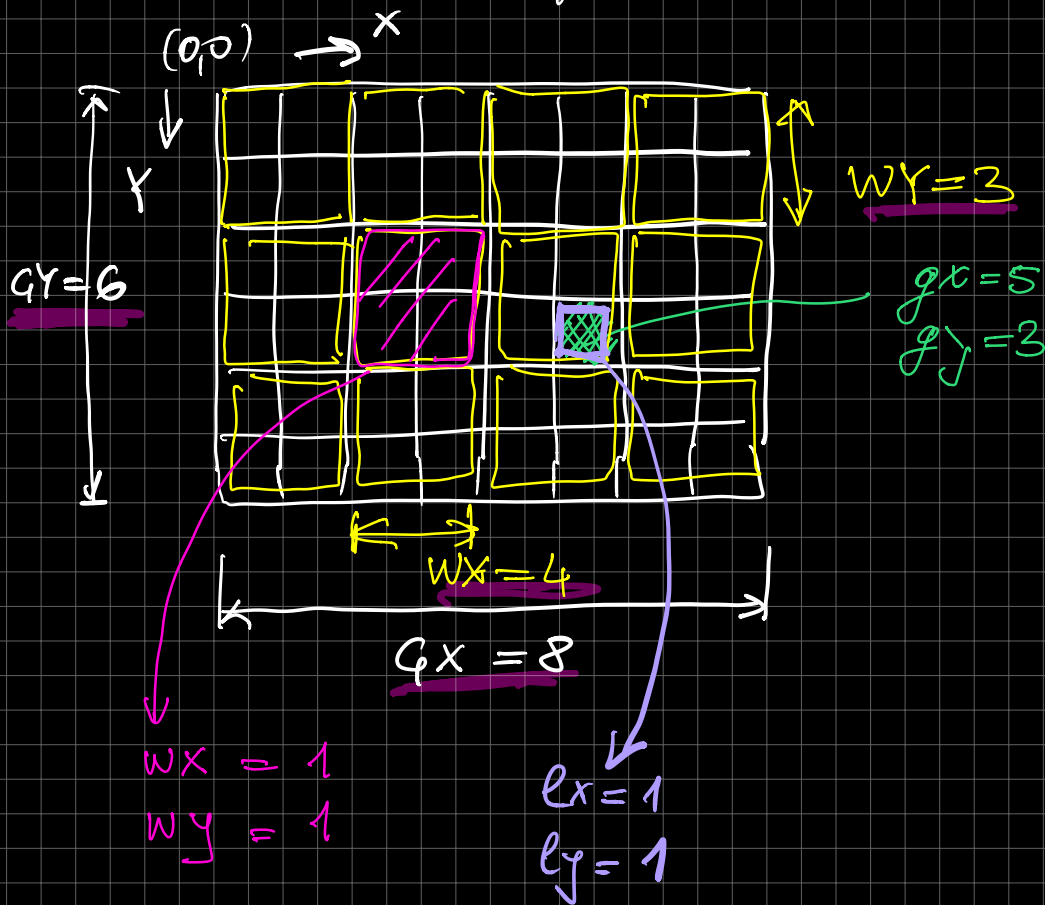
21.4.2021



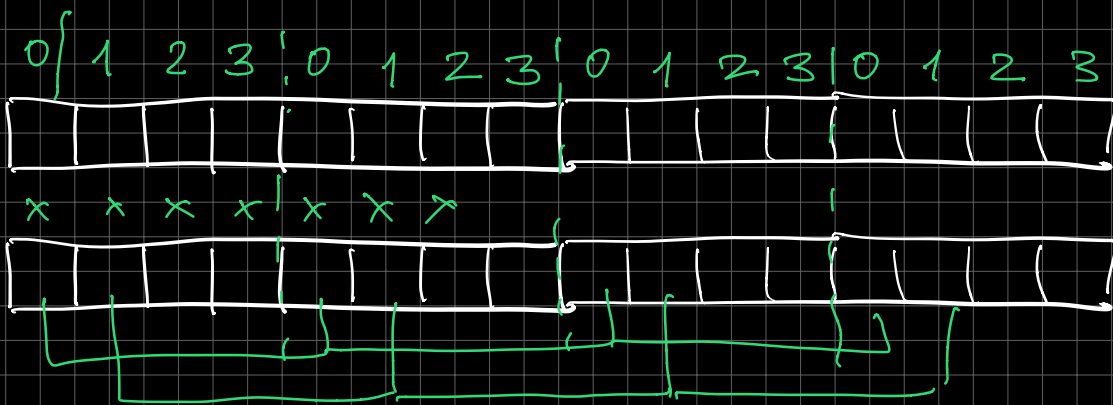
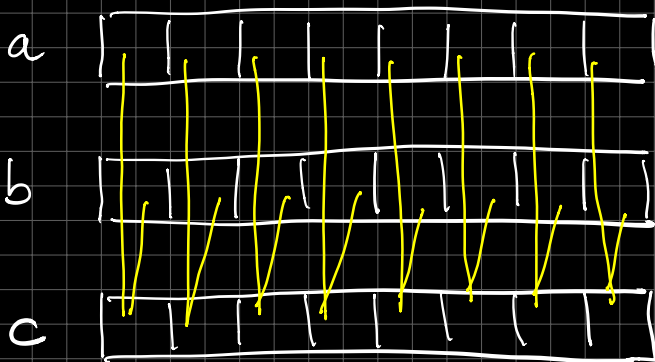
* NDRange

- dobcā stavba in organizacija po skupinah
- dobcā prostorsko organizacija
int. \rightarrow 1D, 2D, 3D

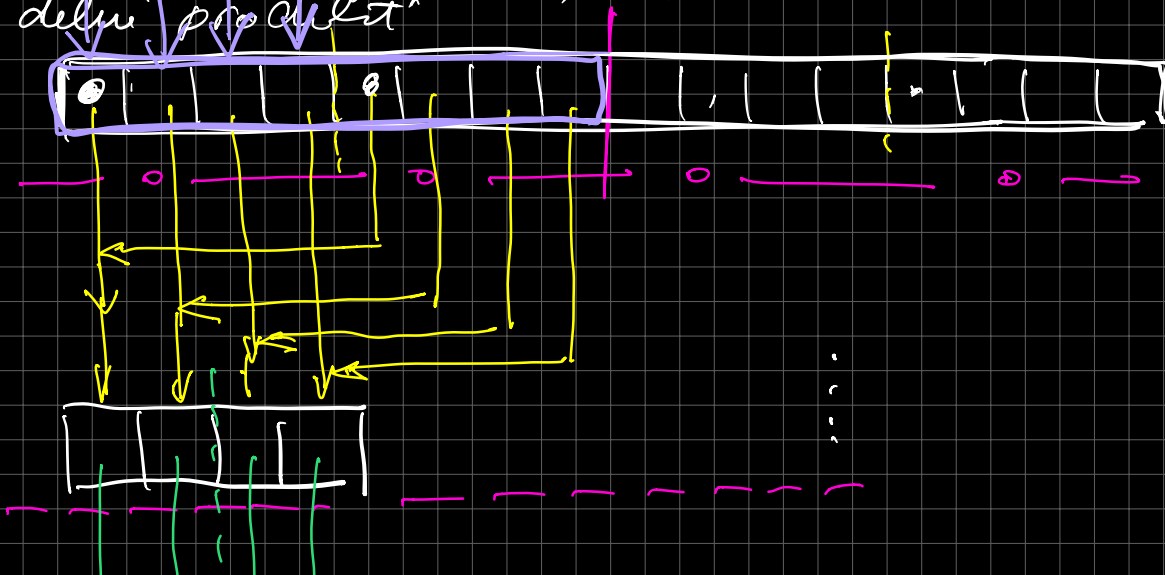
→ vsaka nit ima svoj evolutivni dočlen
index (10) v prostoru NDBoje

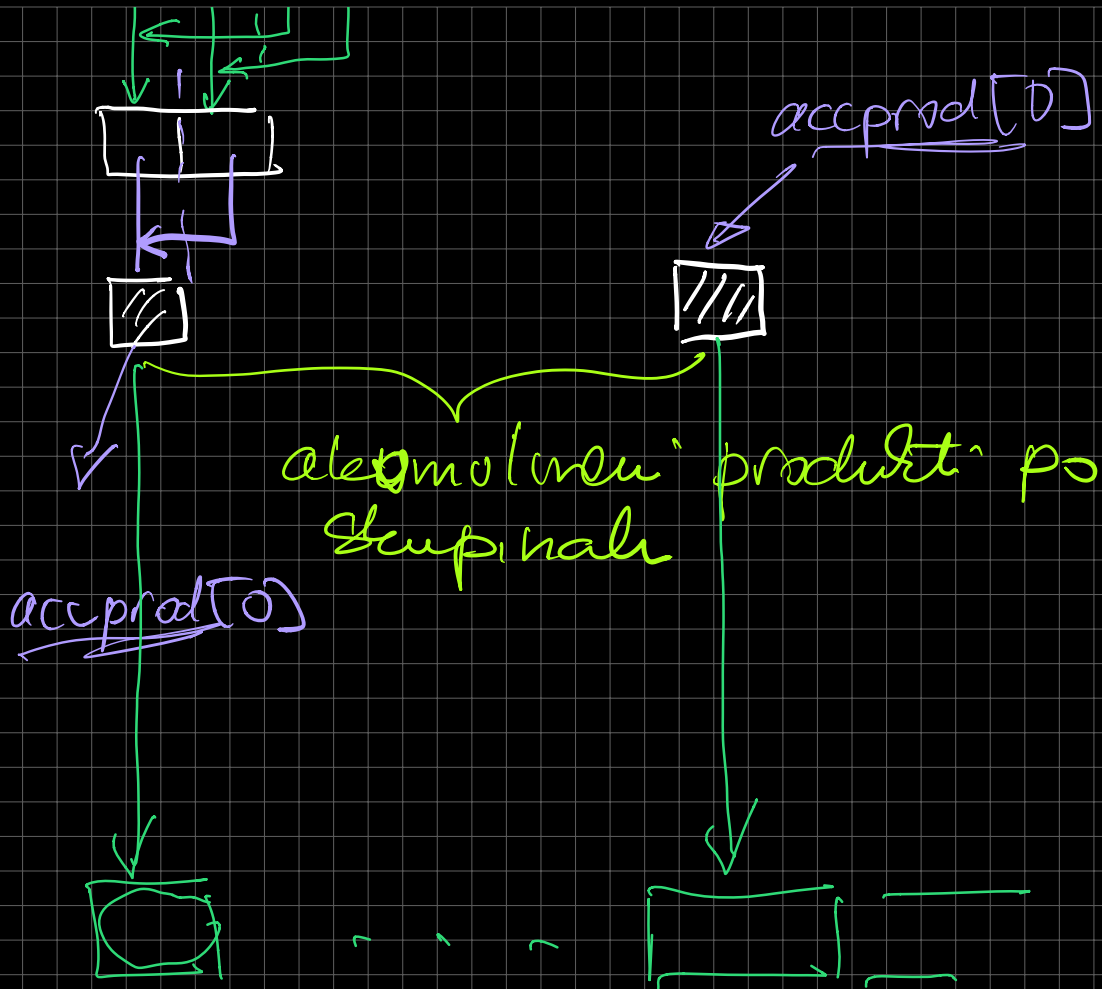


Predele razlozimo sicer, moreno
definirati: $\{G_x, G_y\}$ in $\{w_x, w_y\}$



Здесь: манус фазы делит прдуктер,
 делит прдуктер, 2^2 фазы инти, npr 16





22.04.2021

Razvrščanje niti

→ CPE ne razvrščajo posameznih niti
↓
CU

→ CU razvrščajo t.i. SNOPE NITI
(WARPS)

def. matrica 32 niti, delno
indeksi so zaporedni

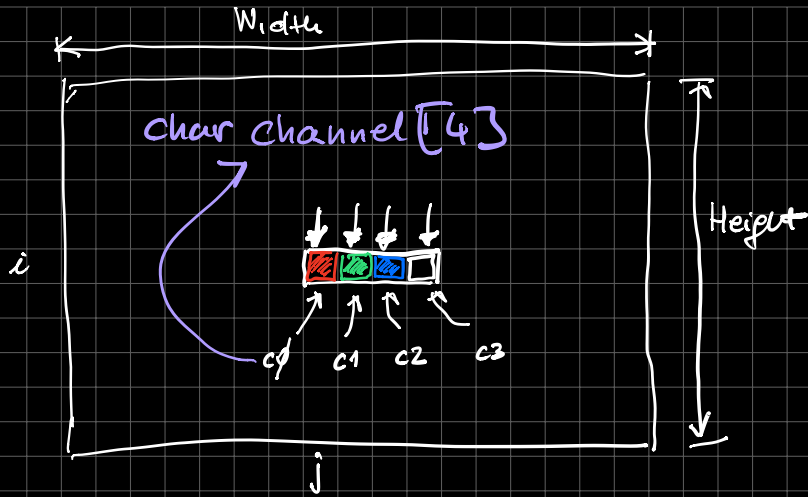
Snope: 0-31

Snope1: 32-63

⋮

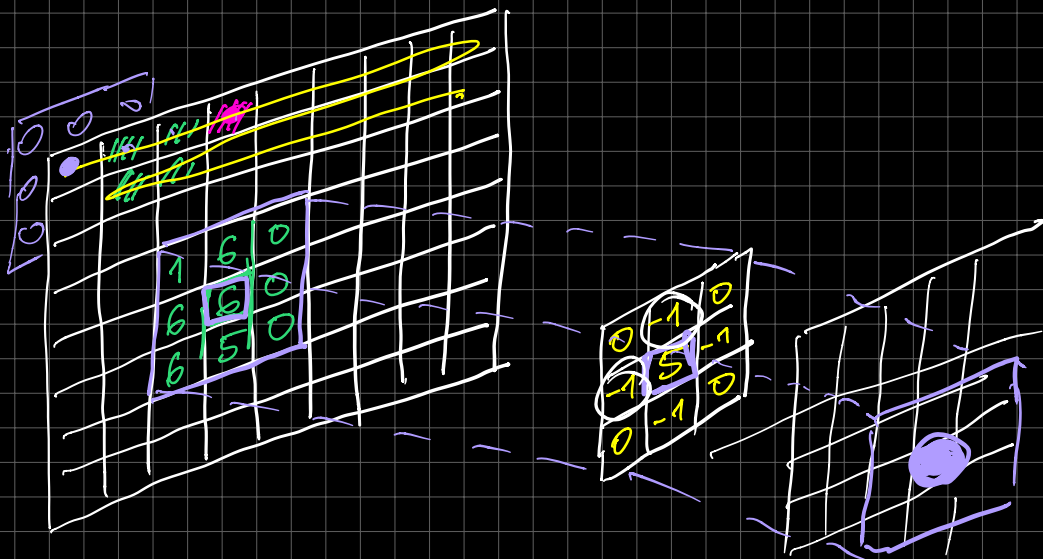
→ Na snope je vreten dostop
do globalnega pomnilnika

↓
V globalni pomnilnik se v rebrne
trunkle gre z naslovom, ži pa izstopajo
niti 12 istega snopa



$$pImage[(i * Width + j) * 4] + channel$$

Filtriranje: poudarjenje robov
(Edge Enhancement)

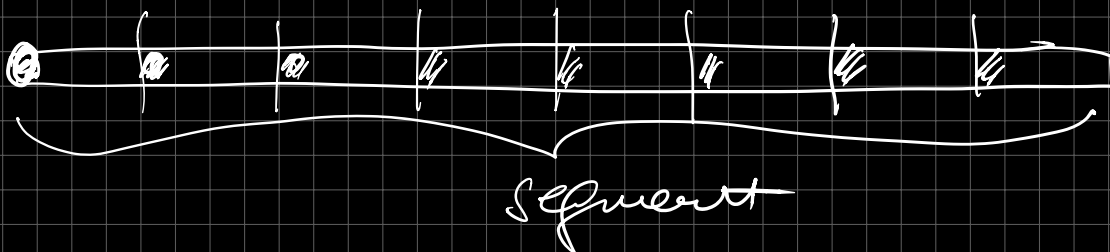
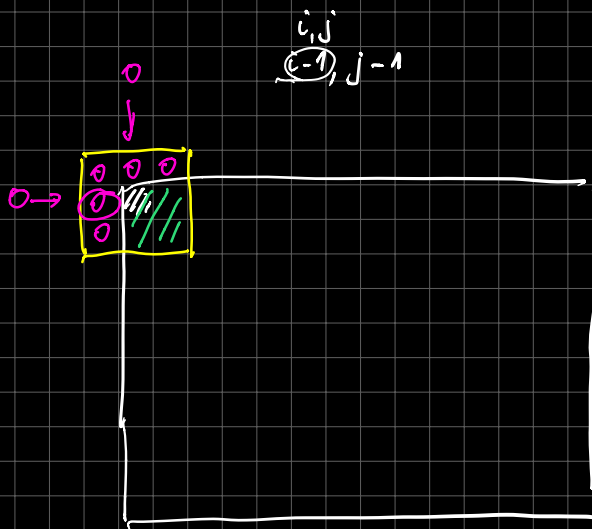


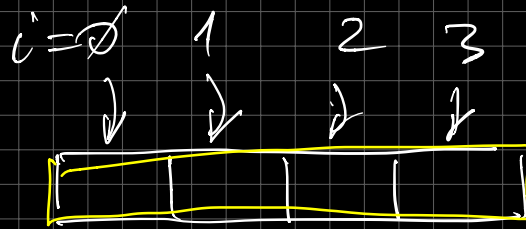
$$novi\ pixel = 1 \cdot 0 + 6 \cdot (-1) + 0 \cdot 0 + 6 \cdot (-1) + 6 \cdot (5) \dots$$

Saepec :

$$\text{mapOut}[i, j] = \text{mapIn}[i, j] * S$$

- $\text{mapIn}[i, j-1]$
- $\text{mapIn}[i-1, j]$
- $\text{mapIn}[i, j+1]$
- $\text{mapIn}[i+1, j]$





for ($i = 0 \dots 3$) {

- berit it p.k.
 - filtering

}



1. Preberi vse 4 kanale nalet (4 B)

2. ~~for ($0 \dots 3$) {~~

~~→ filtering vse prebrani boji posebej~~

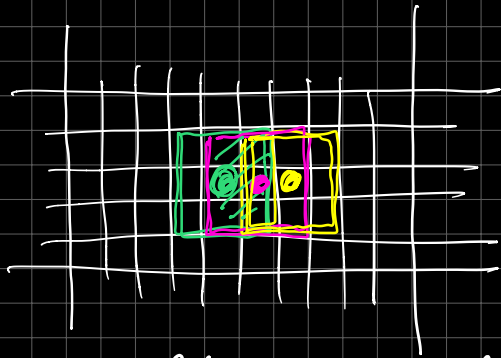
~~}~~

konst. bomo:

→ veljave pod. tip

i

→ veljave opravke



Operasi lokalnya sendiri:

