

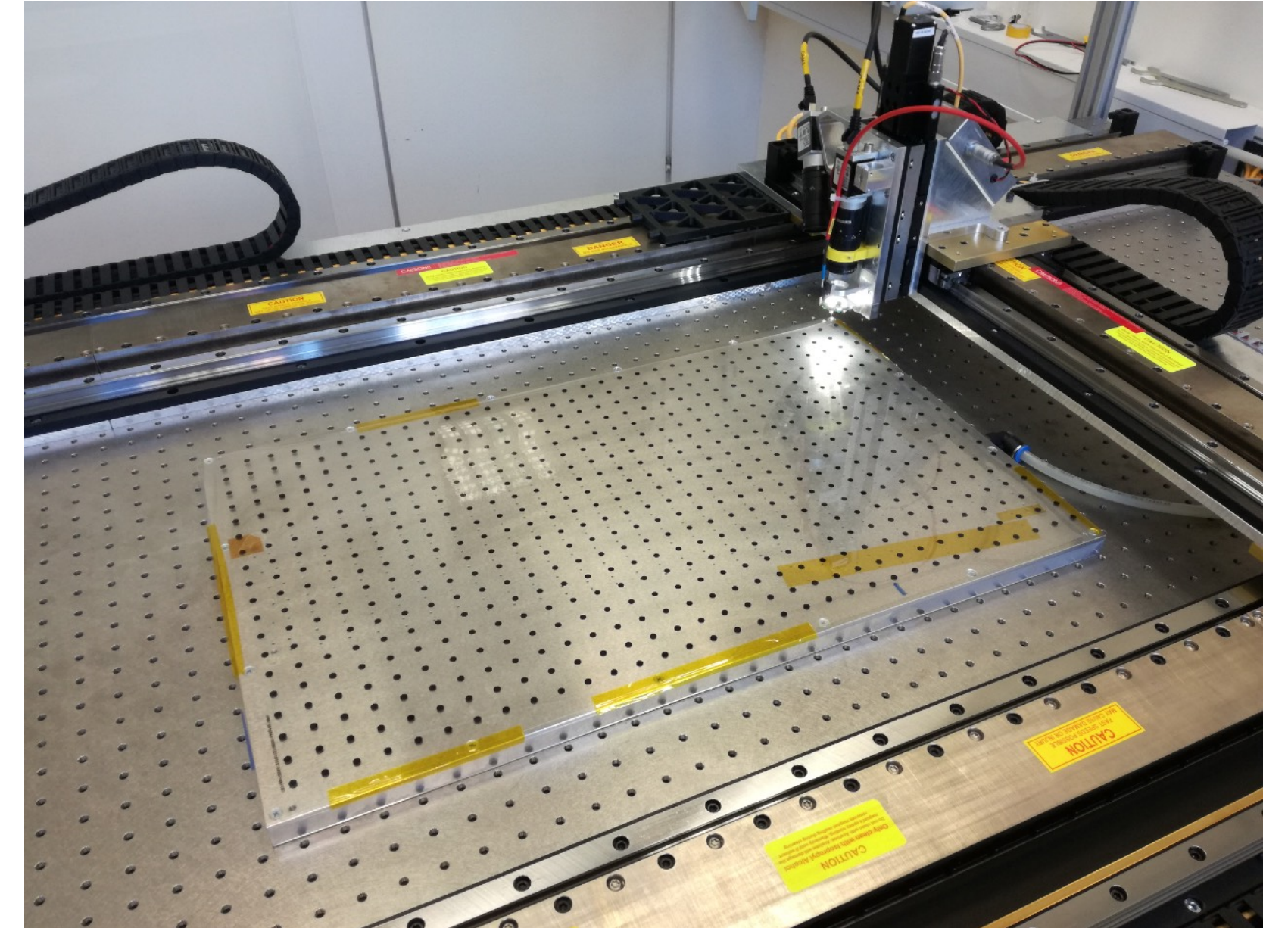
BTTR robot update

F9 SIC LAB WEEKLY

JSI - DESY robot cross-calibration

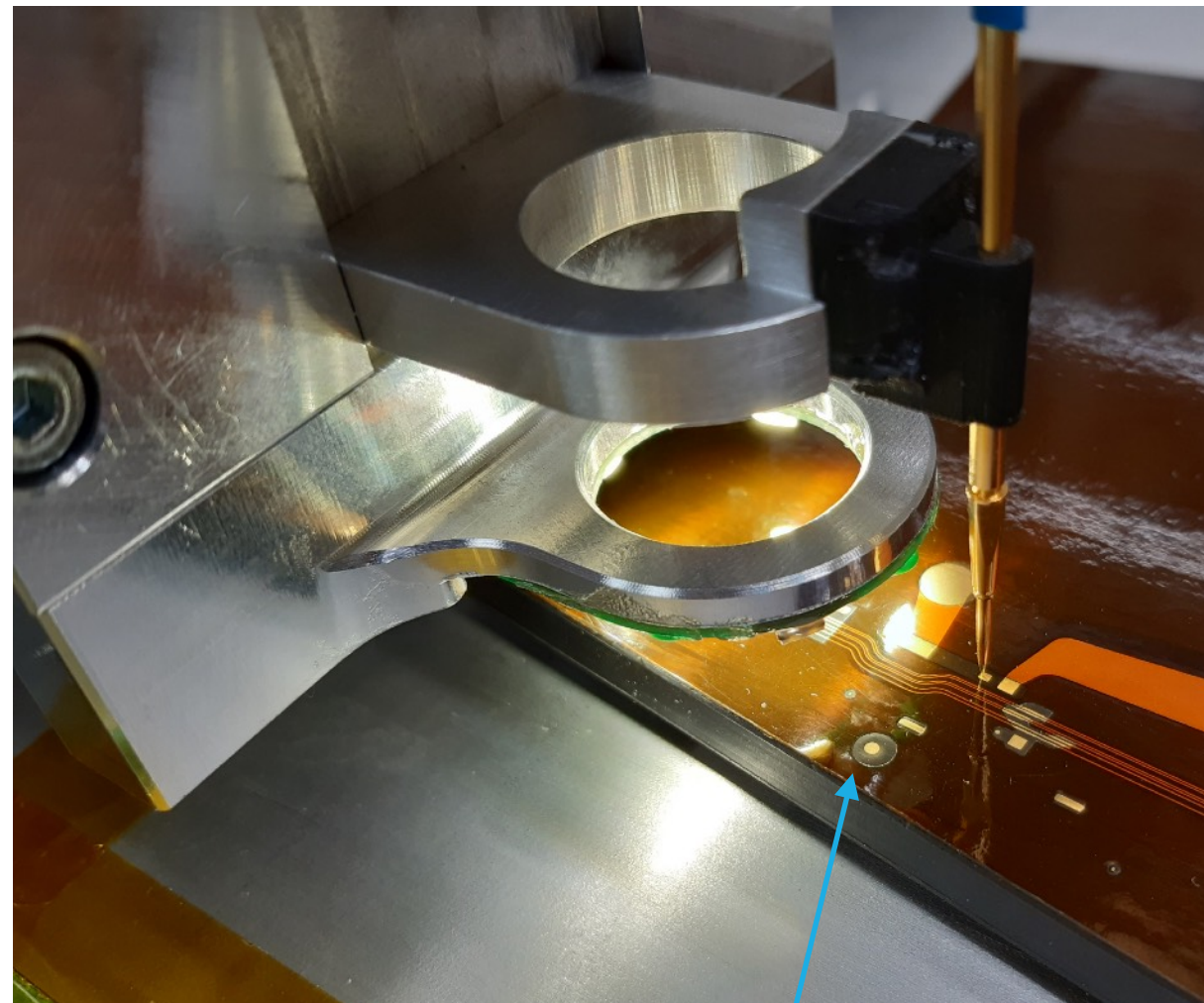
- Main factor is the dotted foil calibration. Foil with known spacing between points is used to calibrate any bending etc. of the robot stages.
- This calibration needs to be done only once (or if the robot stages are reassembled).
- Co-cured (Skin) tapes are used to measure differences between the robots.

- Measurements compared:
 - DESY: ➔ Smartscope corrected DESY cal. foil
 - JSI:
 - ➔ JSI cal. foil assuming equidistant points
 - ➔ Smartscope corrected JSI cal. foil
 - ➔ Smartscope corrected DESY cal. foil

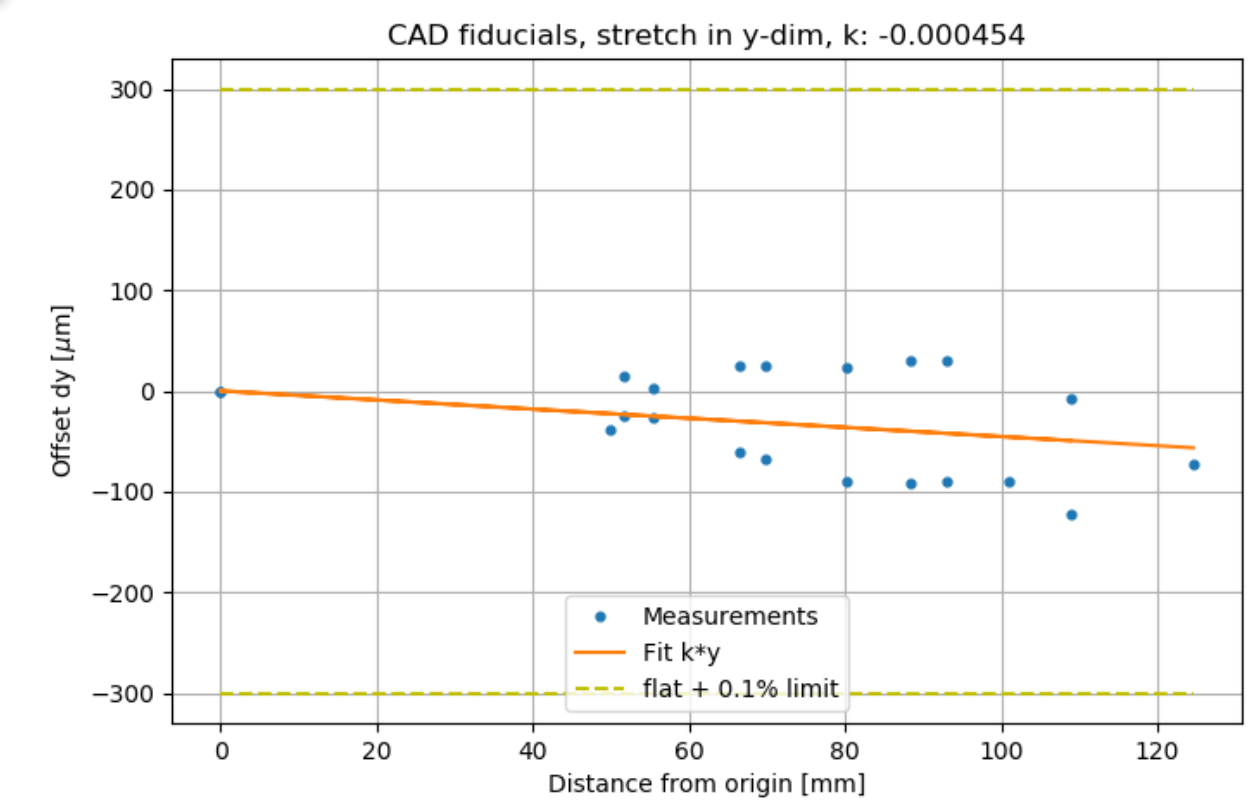
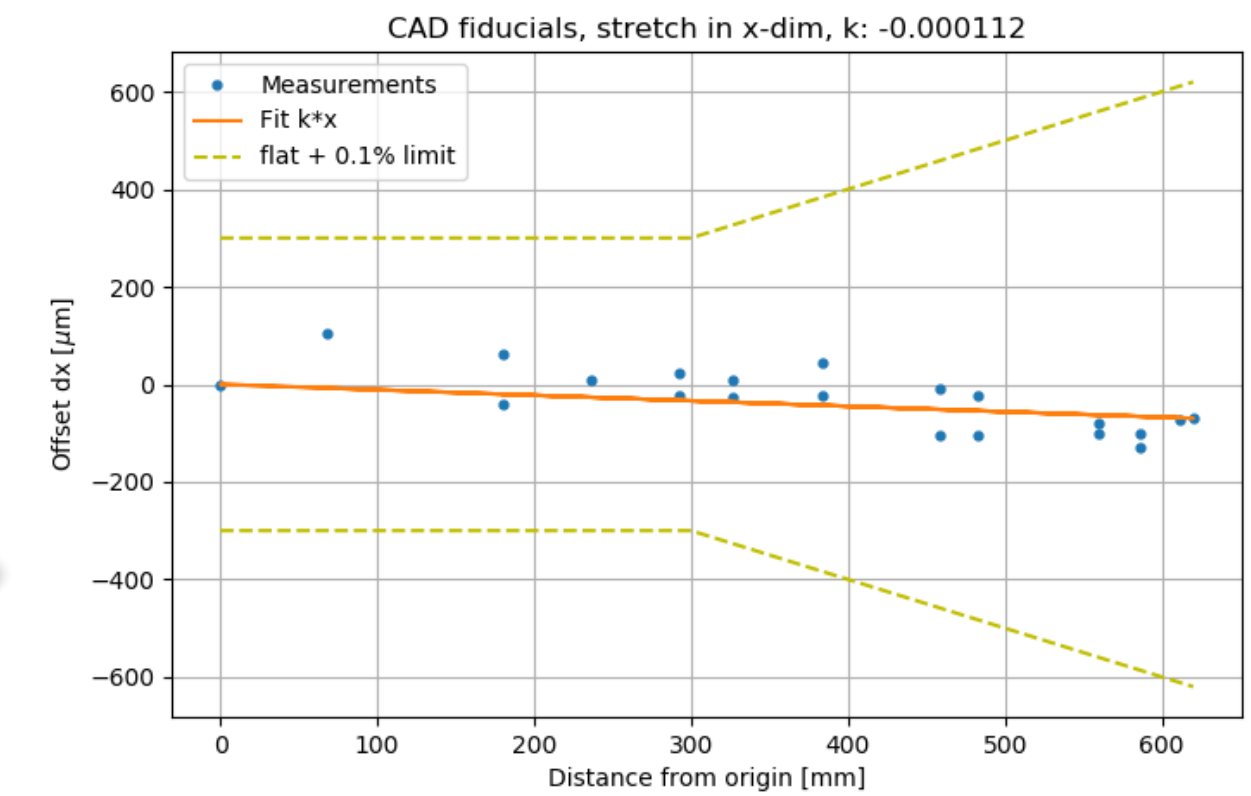
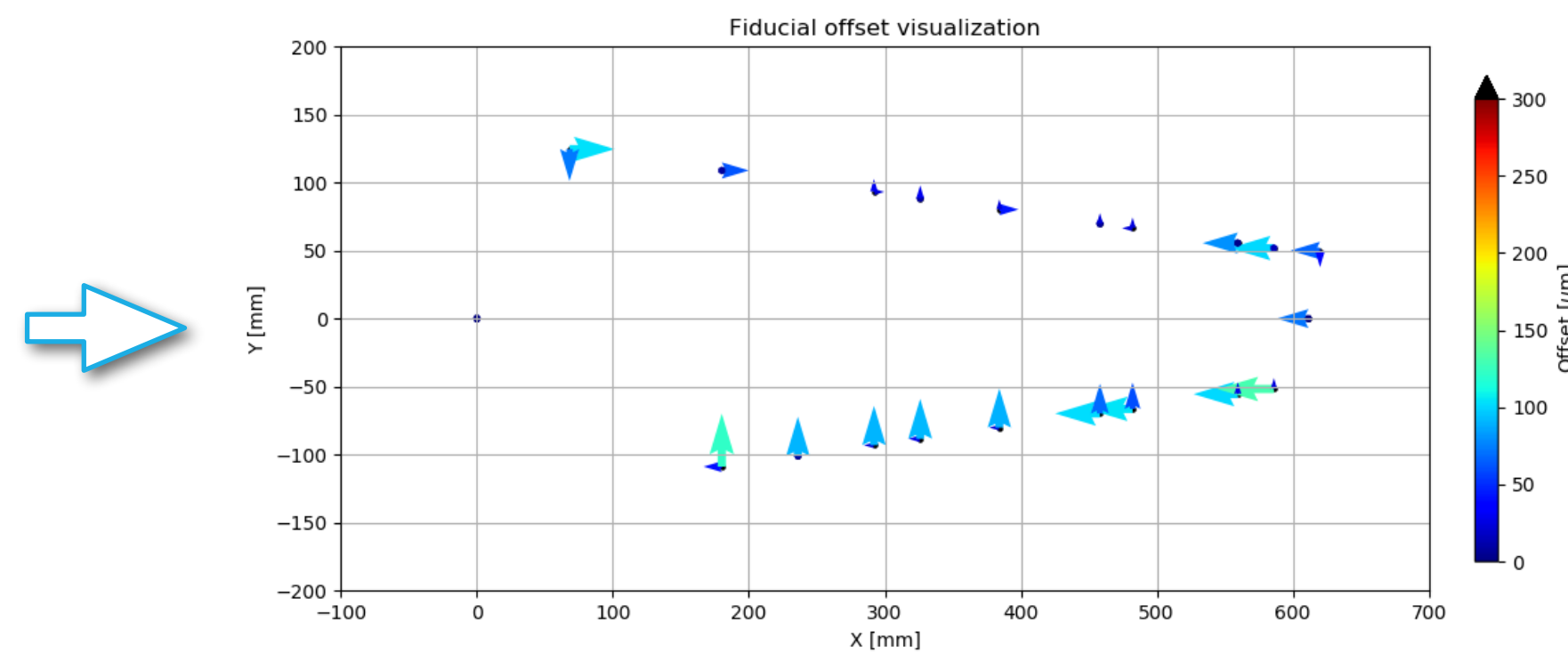


Tape stretch measurement

- Measure global fiducials with vertical camera mounted on Stage1.
- Compare measured positions with nominal.
- Linear **stretch coefficient** for stretch in X and stretch in Y direction.

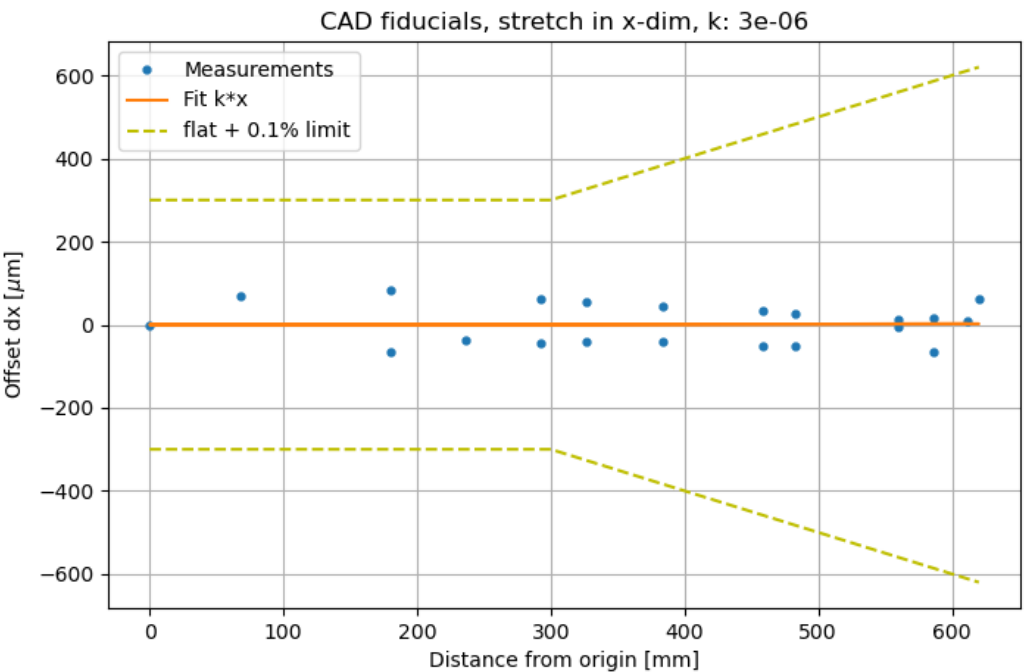


Global fiducial

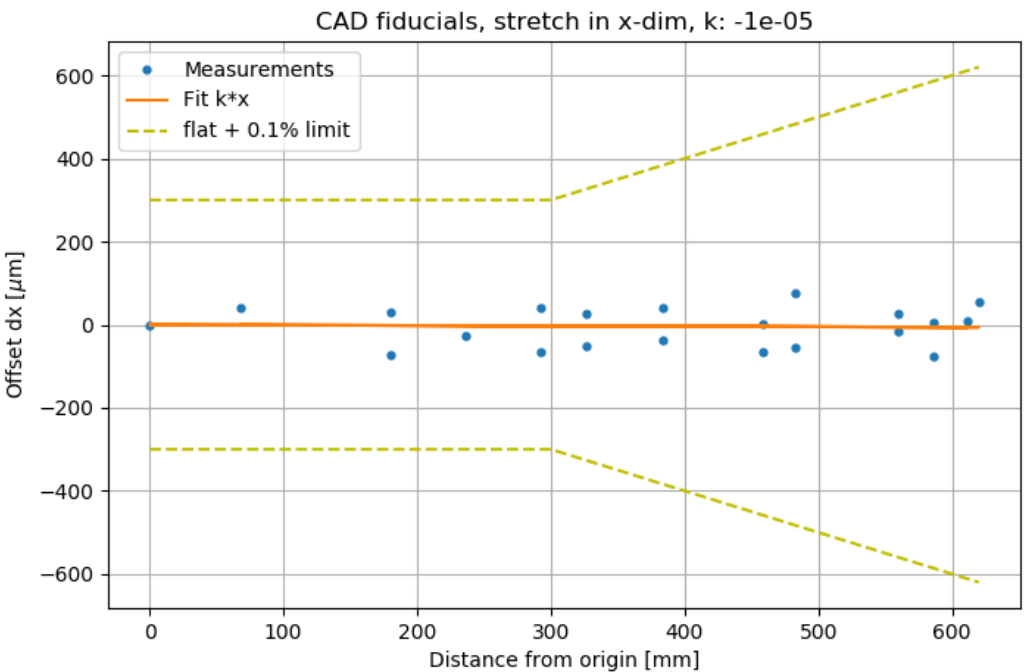


Example: tape 20USEBT2000011

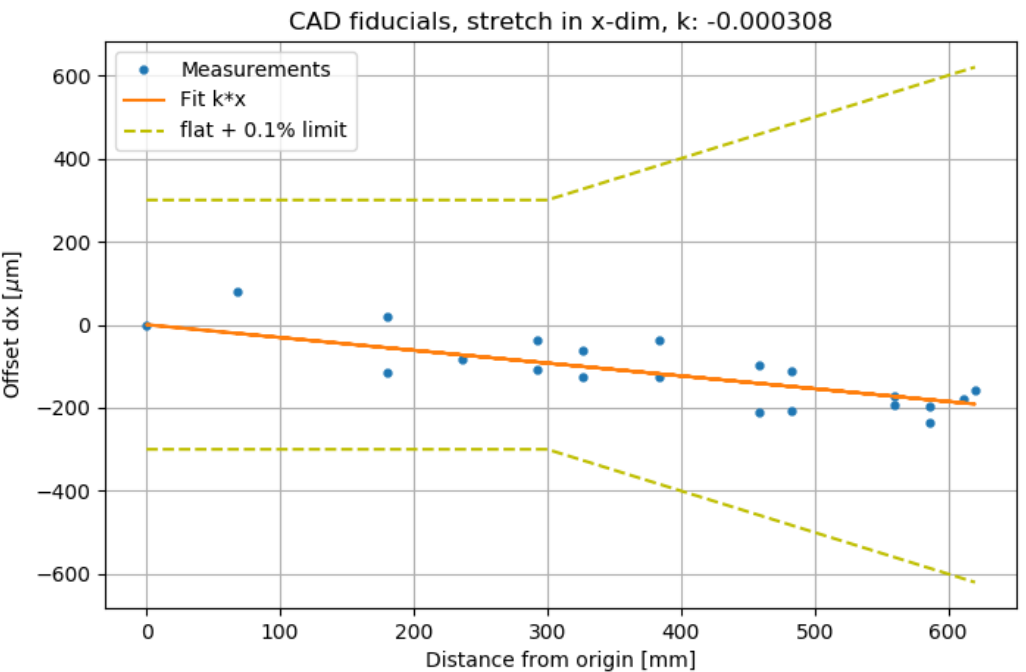
DESY, smartscope calibrated:



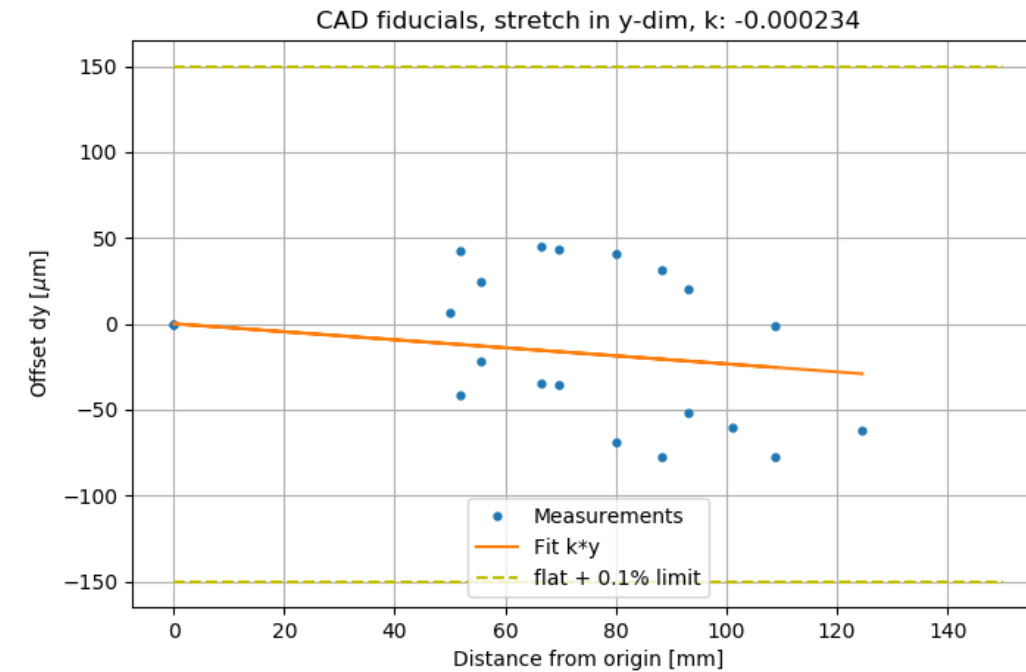
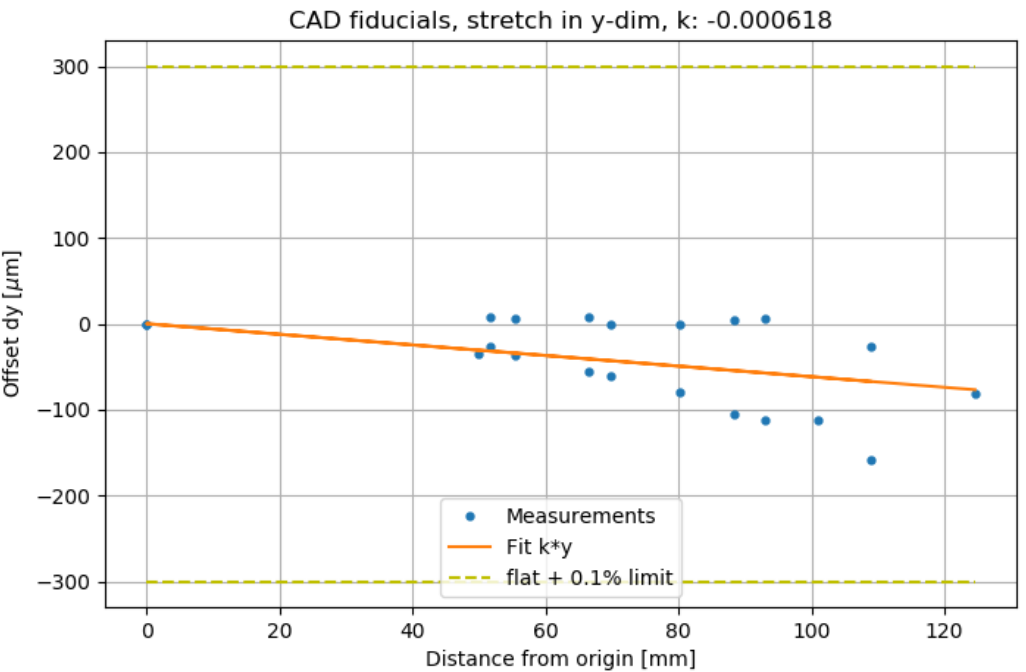
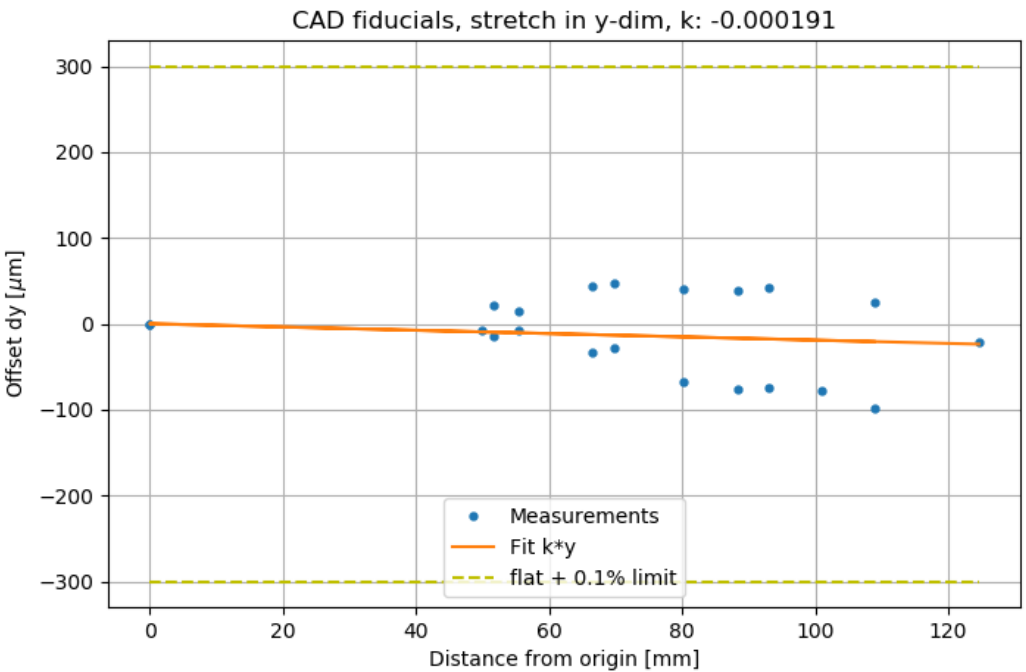
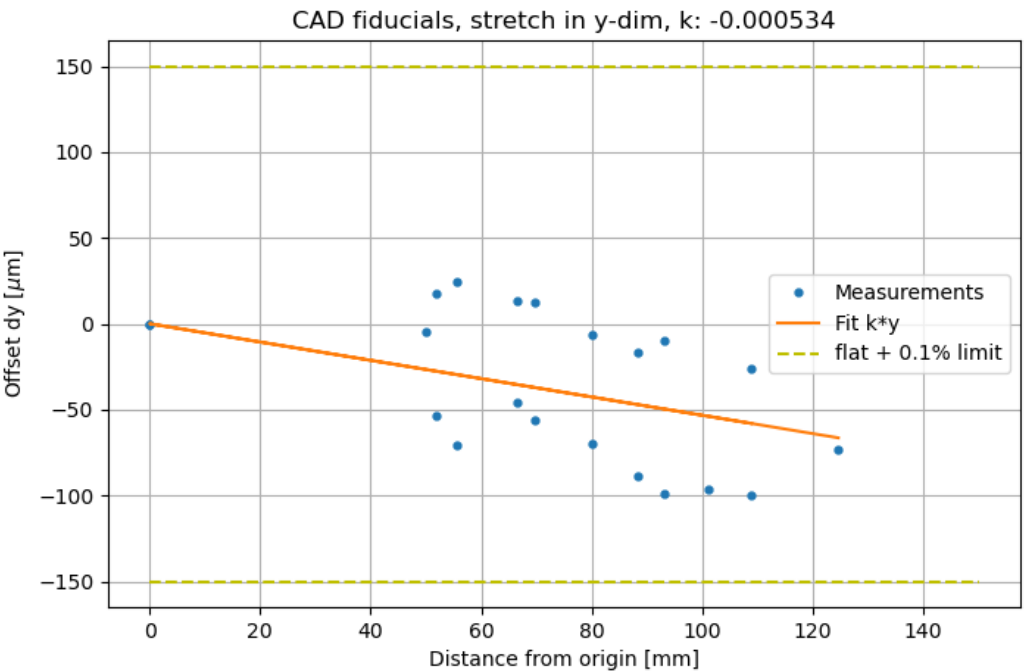
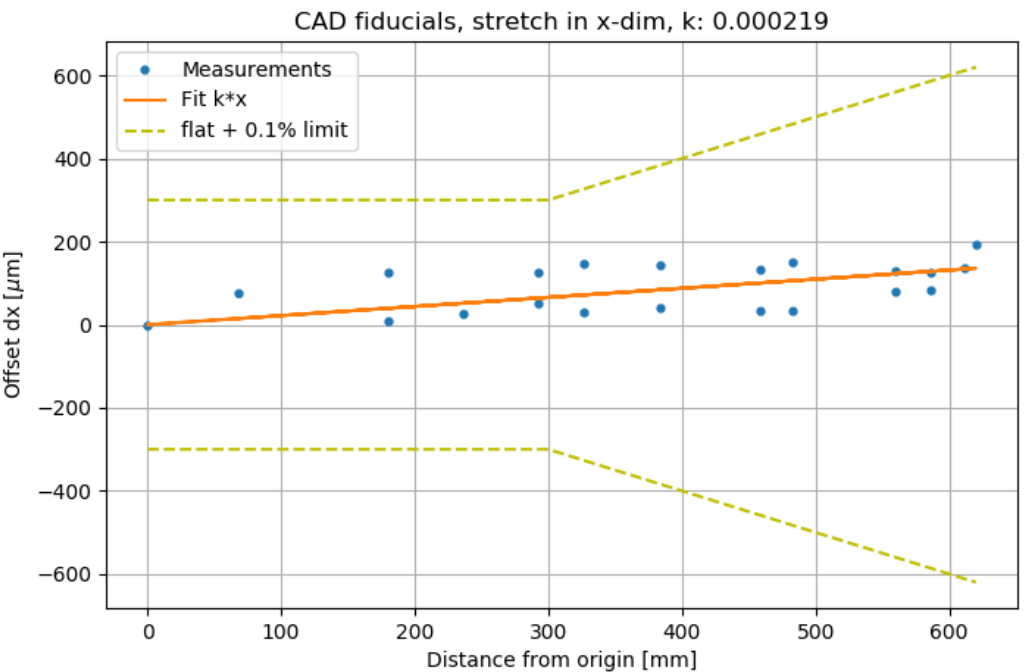
JSI, smartscope DESY cal. foil:



JSI, smartscope JSI cal. foil:

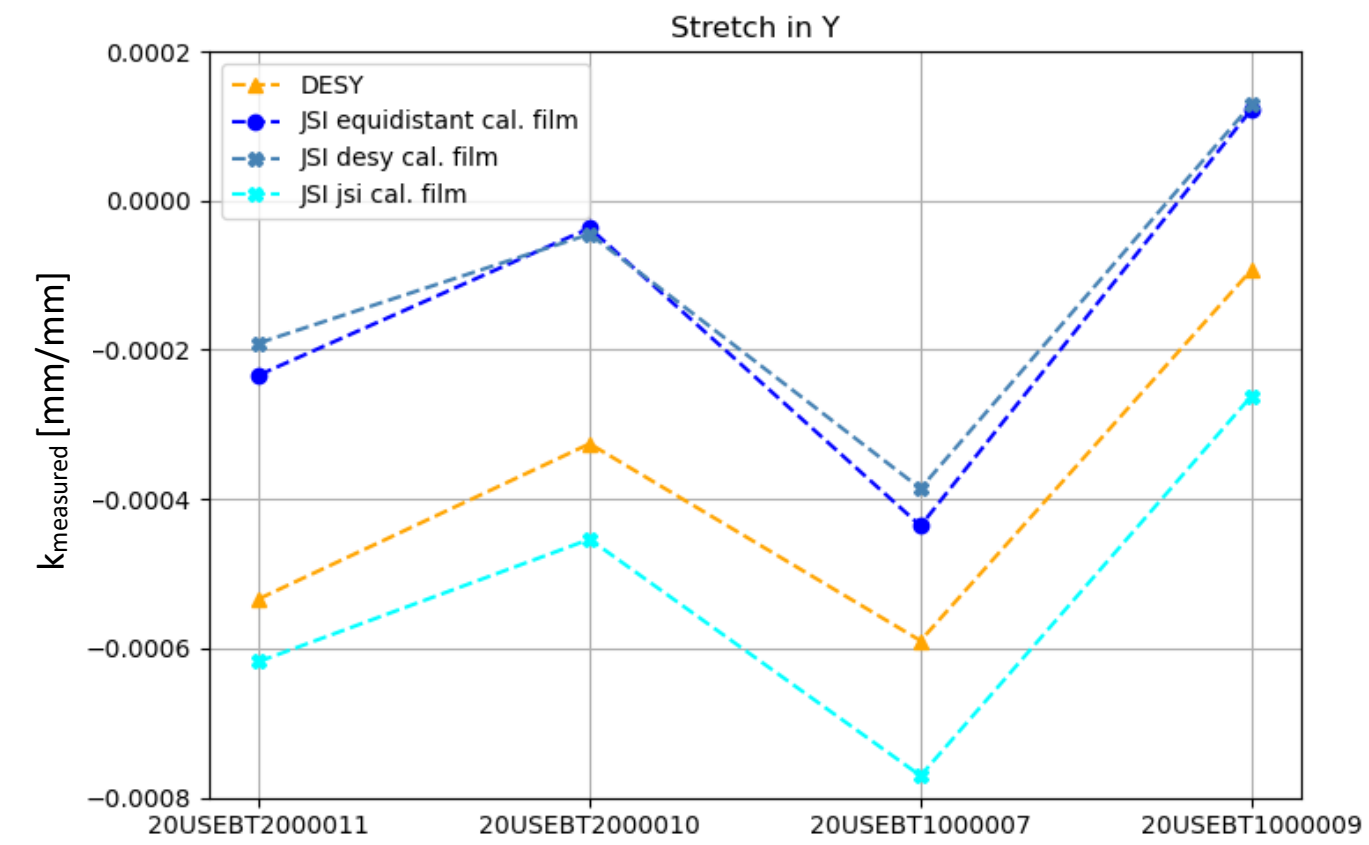
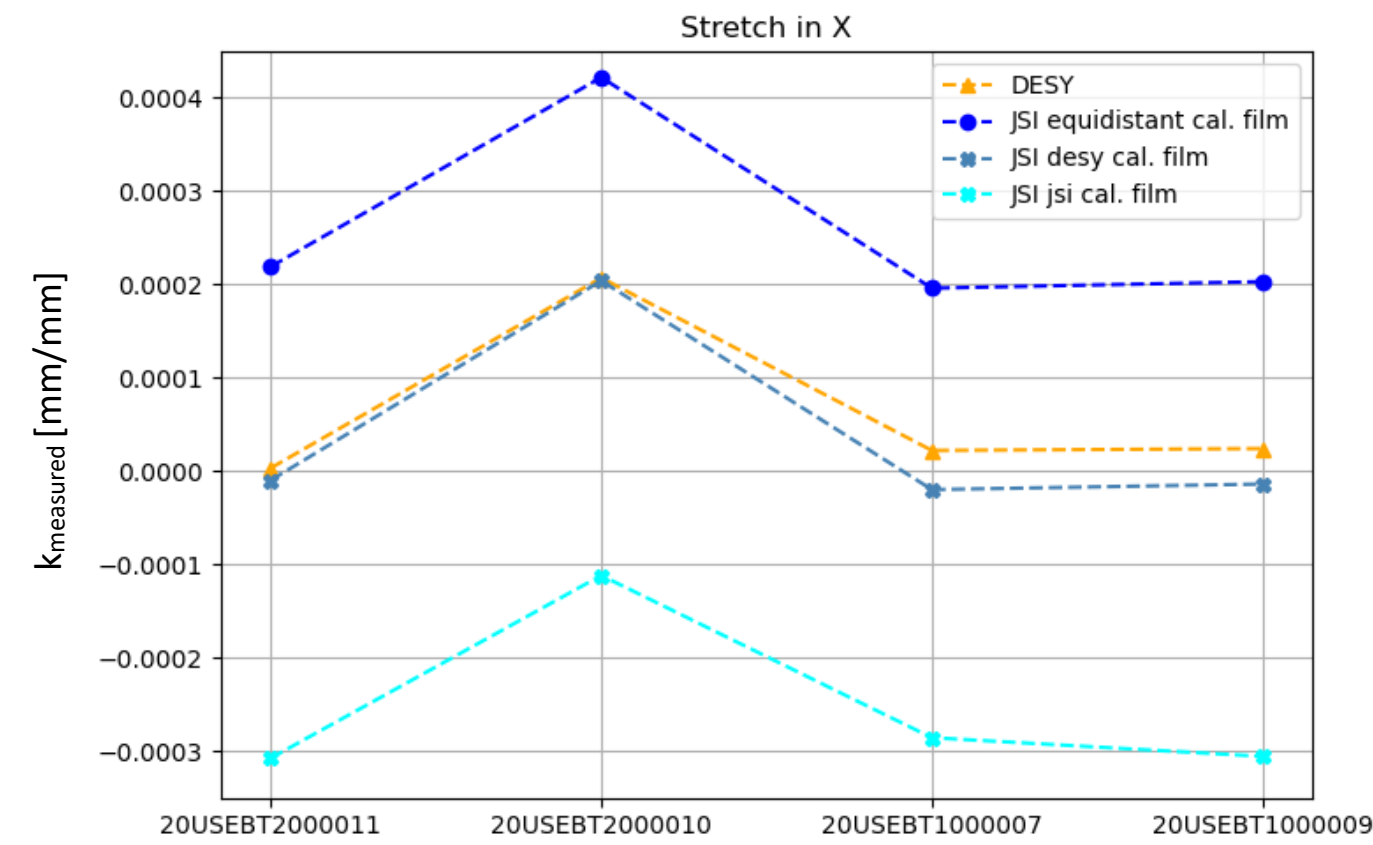


JSI, JSI equidistant foil:

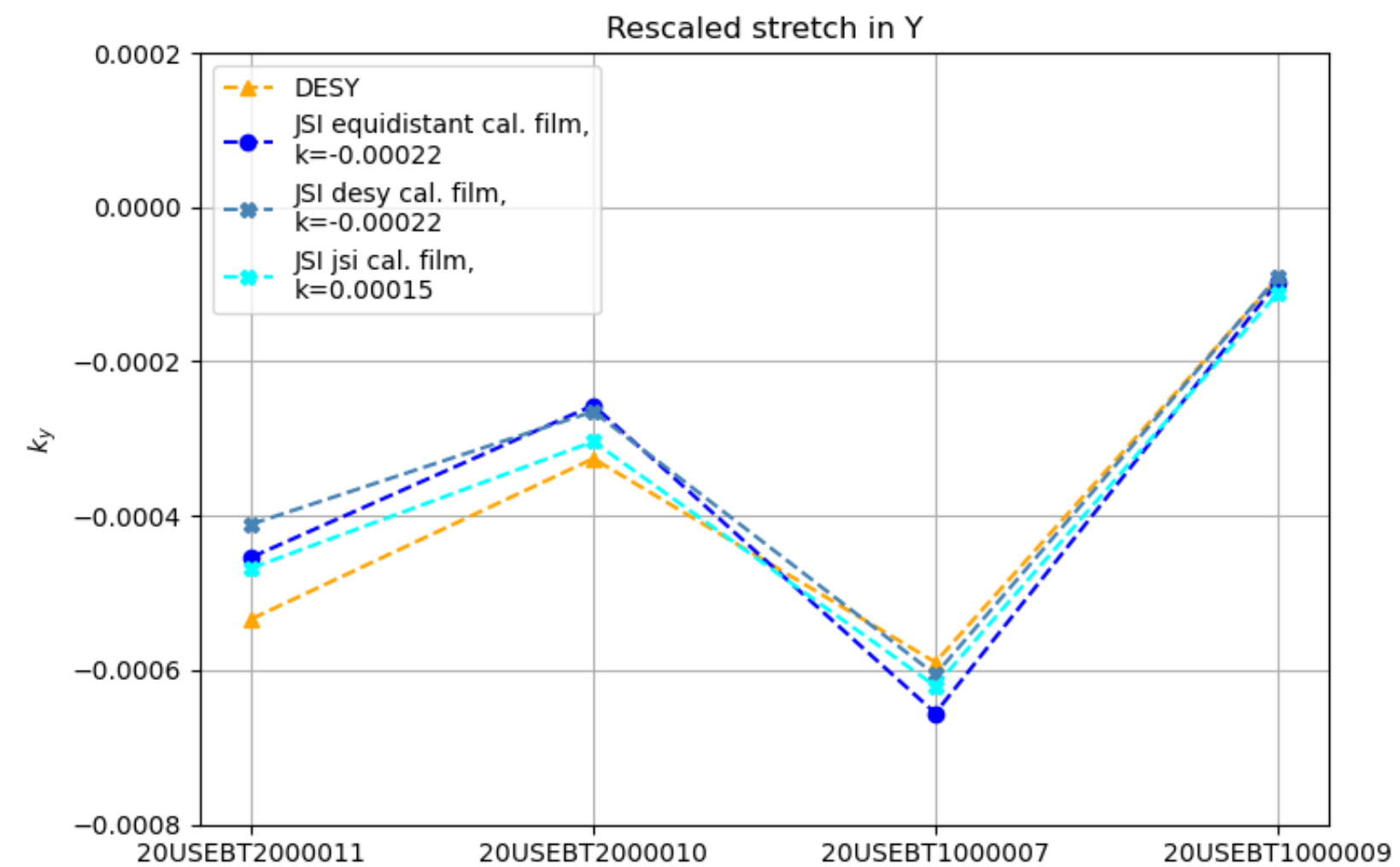
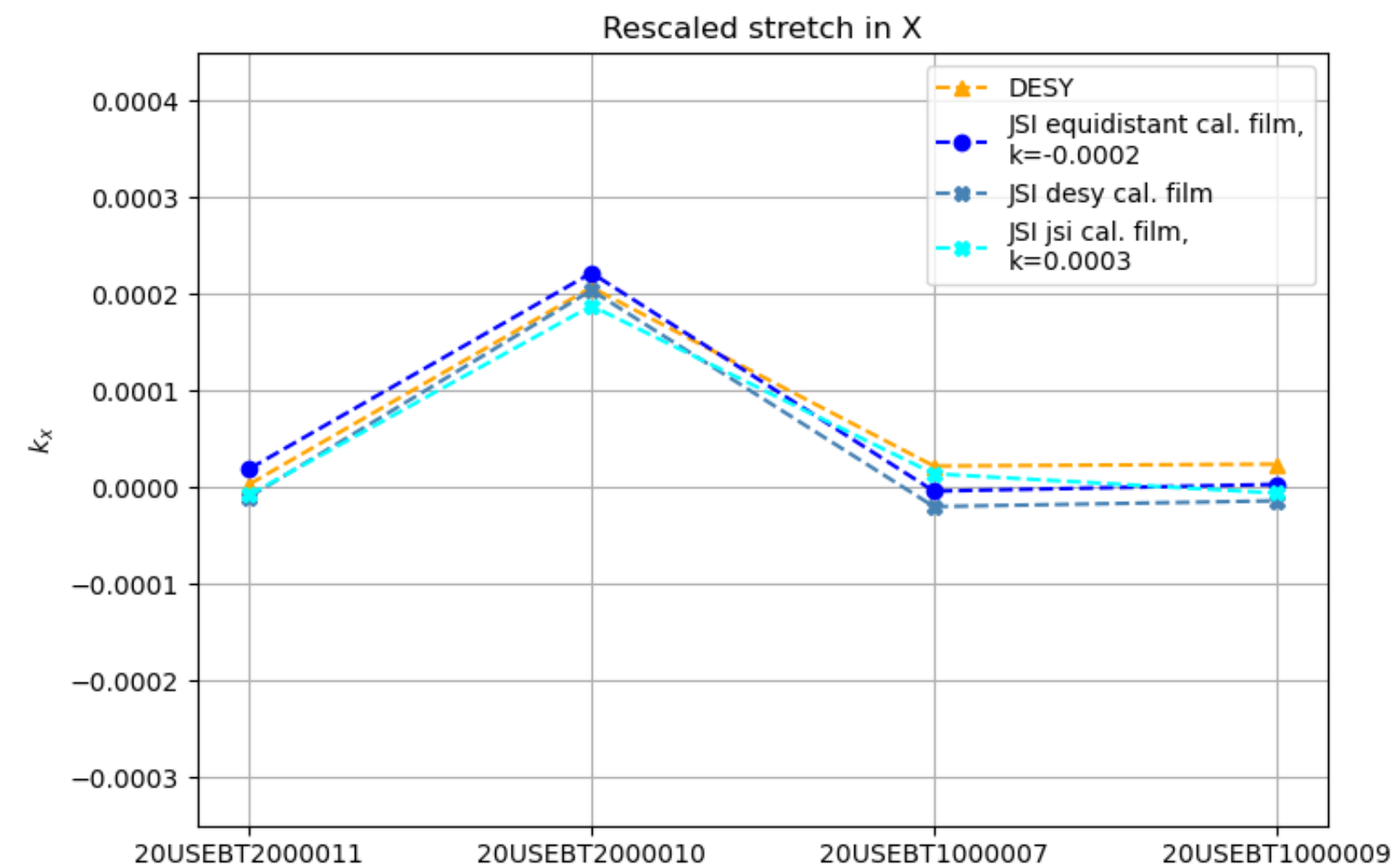


Four co-cured tapes

- Each calibration has a constant difference between stretch coefficients for all measured tapes.



- Excellent match after adding a correction coefficient for each calibration. With this we rescale our measurements to the smartscope. $k_x = (k_{\text{measured}} + k_{\text{correction}})$



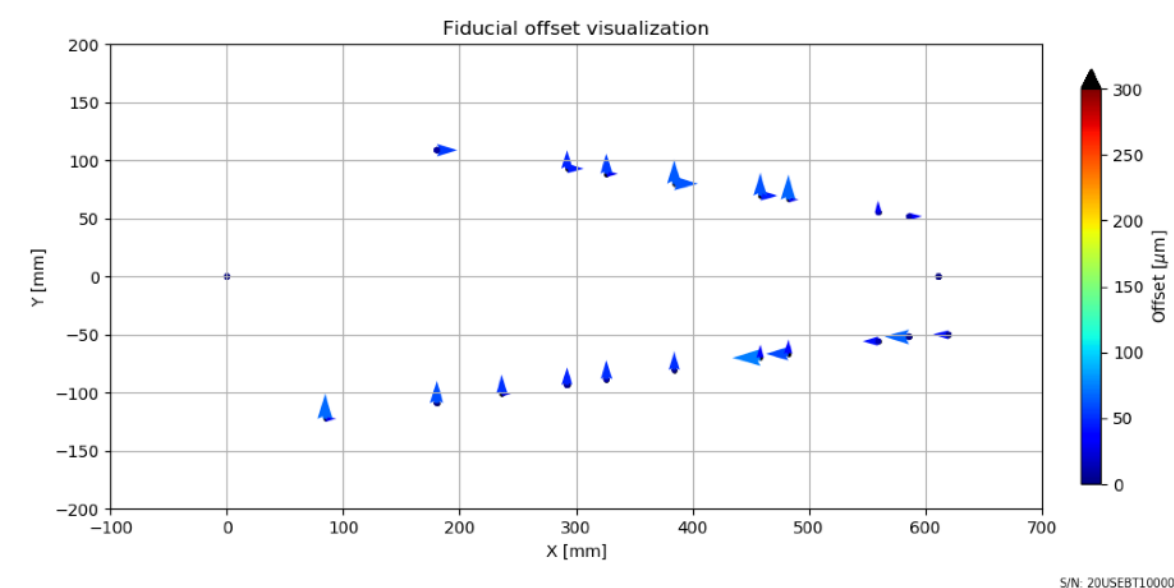
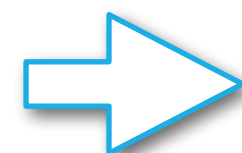
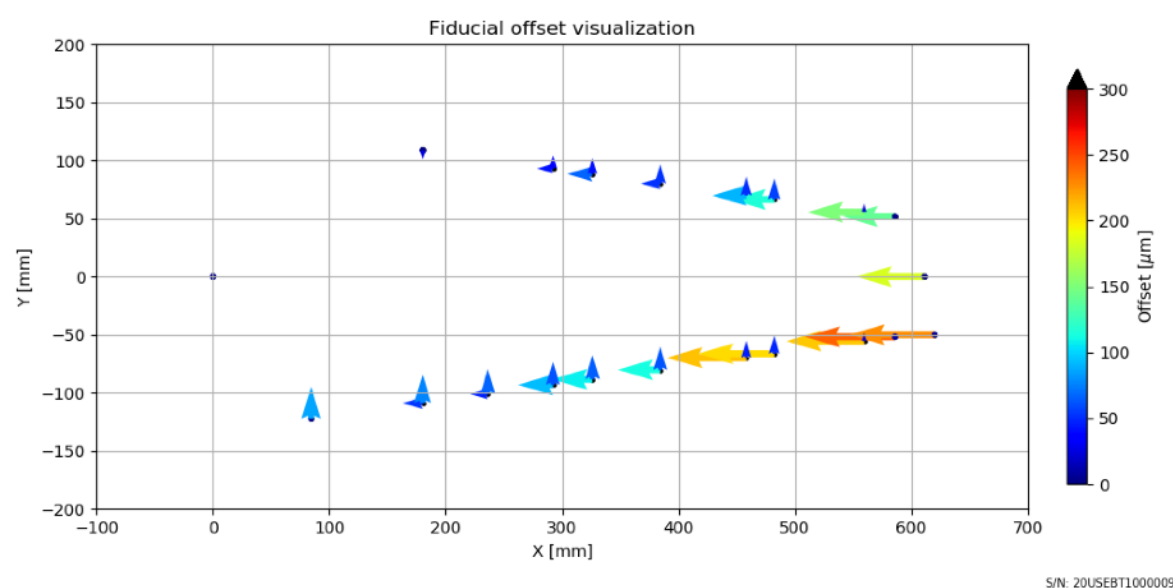
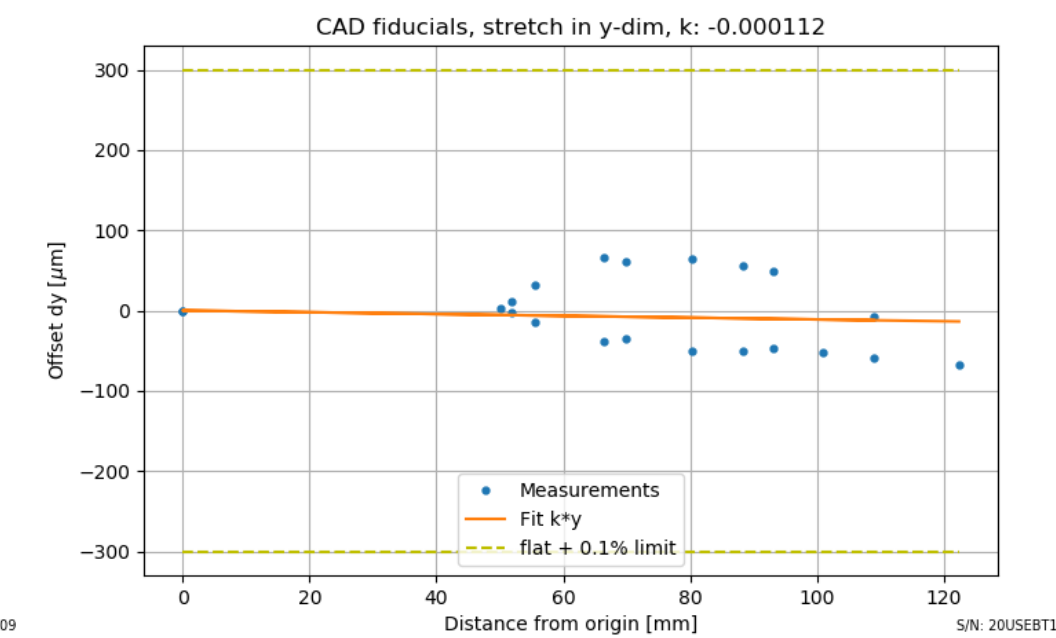
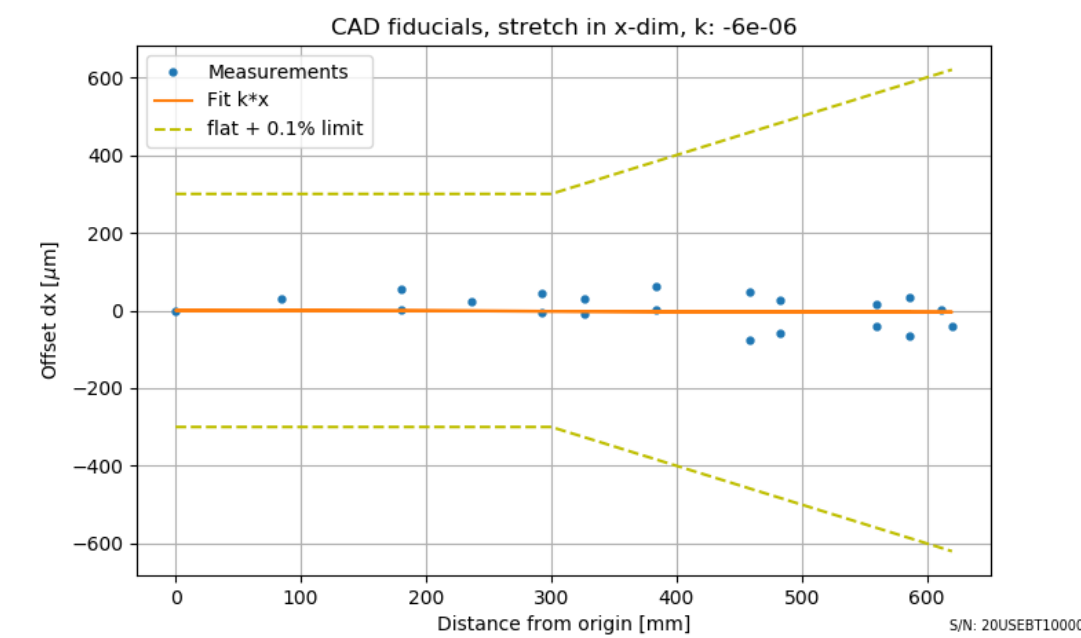
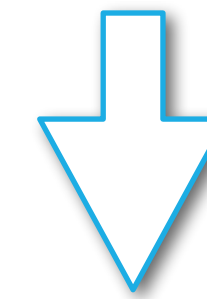
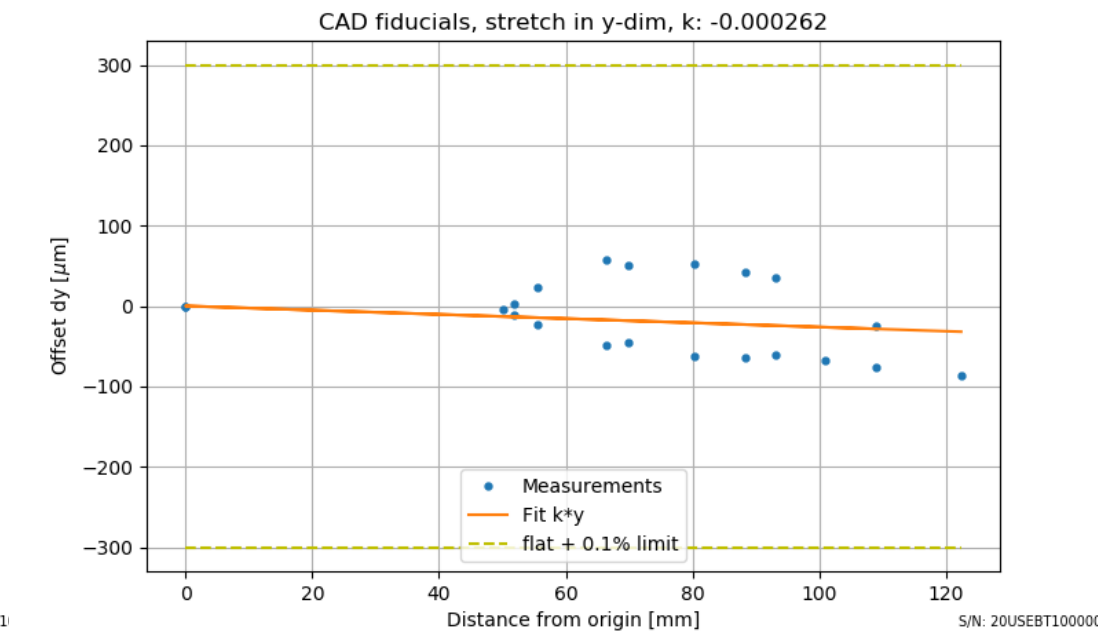
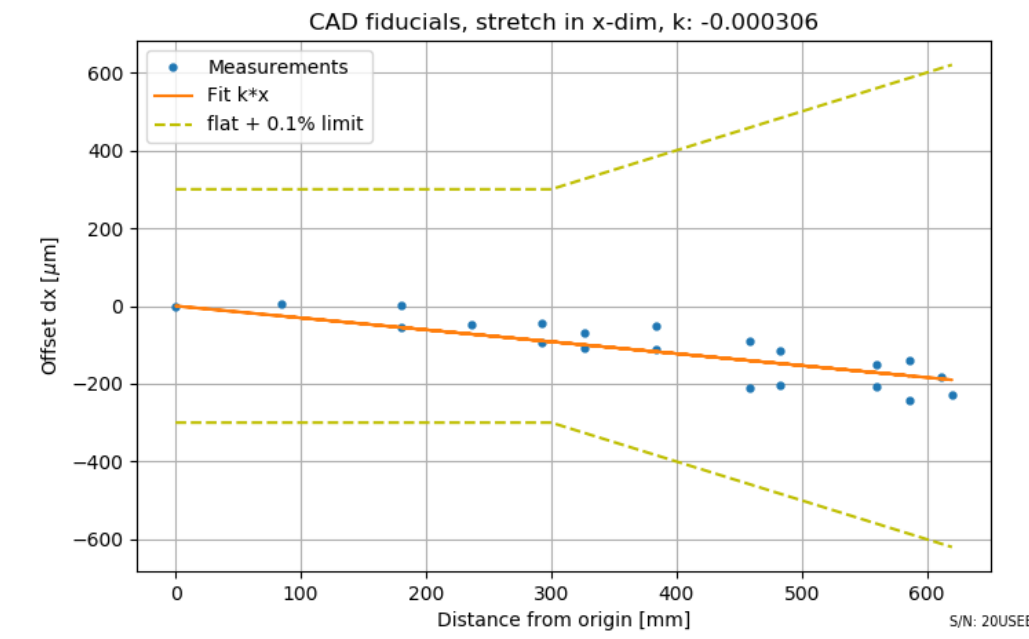
Correction coefficient

- Corrections added to the analysis procedure. They are recorded in the report:

Production Stage = Skin

Analysis	Status
Stretch in X	PASS
Stretch in Y	PASS
Shorts check	PASS
Resistance measurements	PASS
1000V HV	PASS

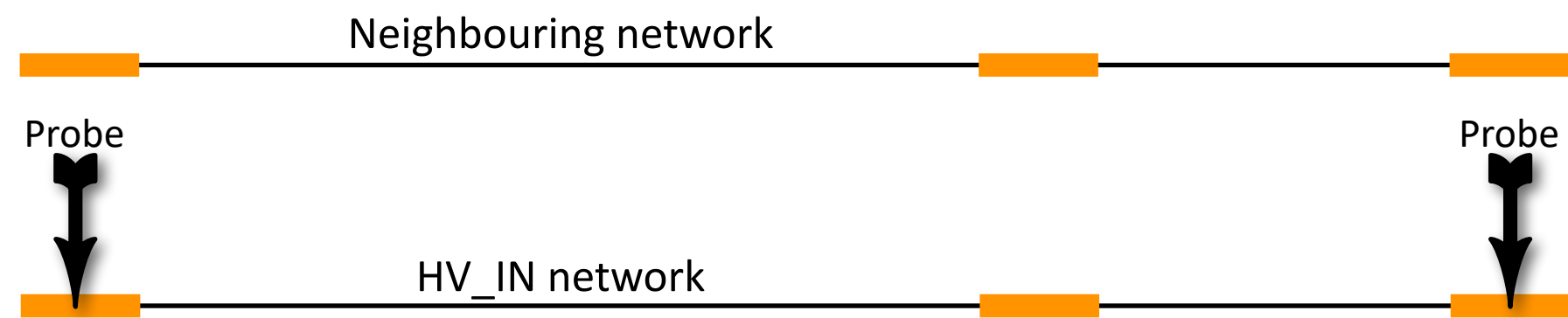
Offset based on CAD fiducial distance from origin was used as stretch criteria.
 Correction coefficient for rescaling X-axis: $0.3 \mu\text{/mm}$.
 Correction coefficient for rescaling Y-axis: $0.15 \mu\text{/mm}$.



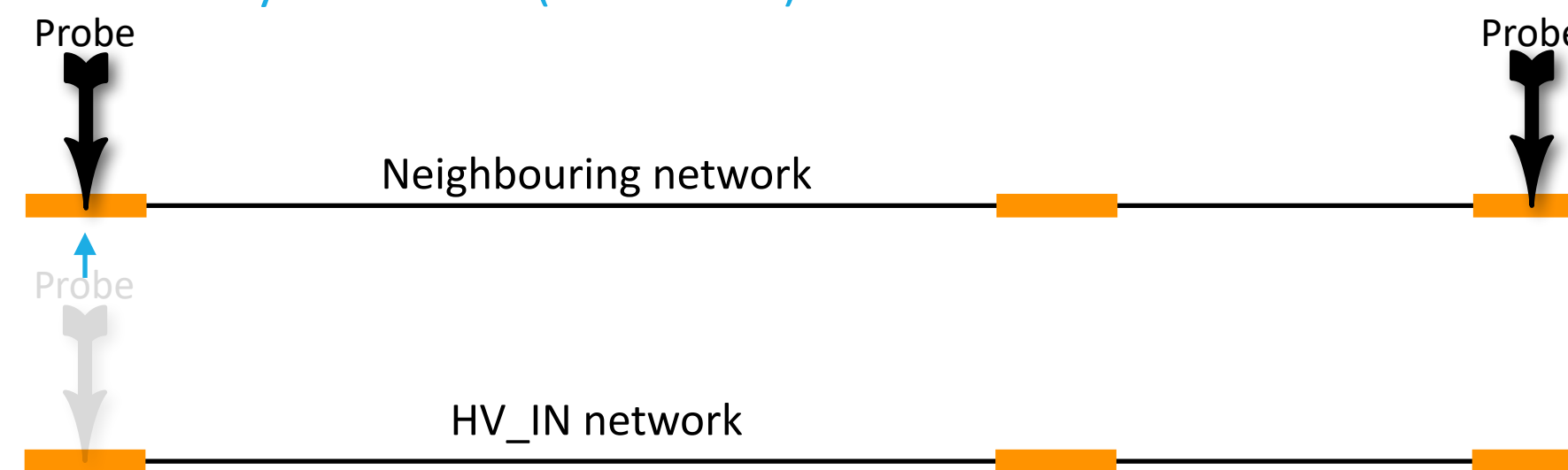
HV line checks implementation

- Before HV leakage measurement, probe contacts with both pads are checked.
- Requires two additional resistance measurements (few seconds each), but is the only way to make sure we correctly probe.

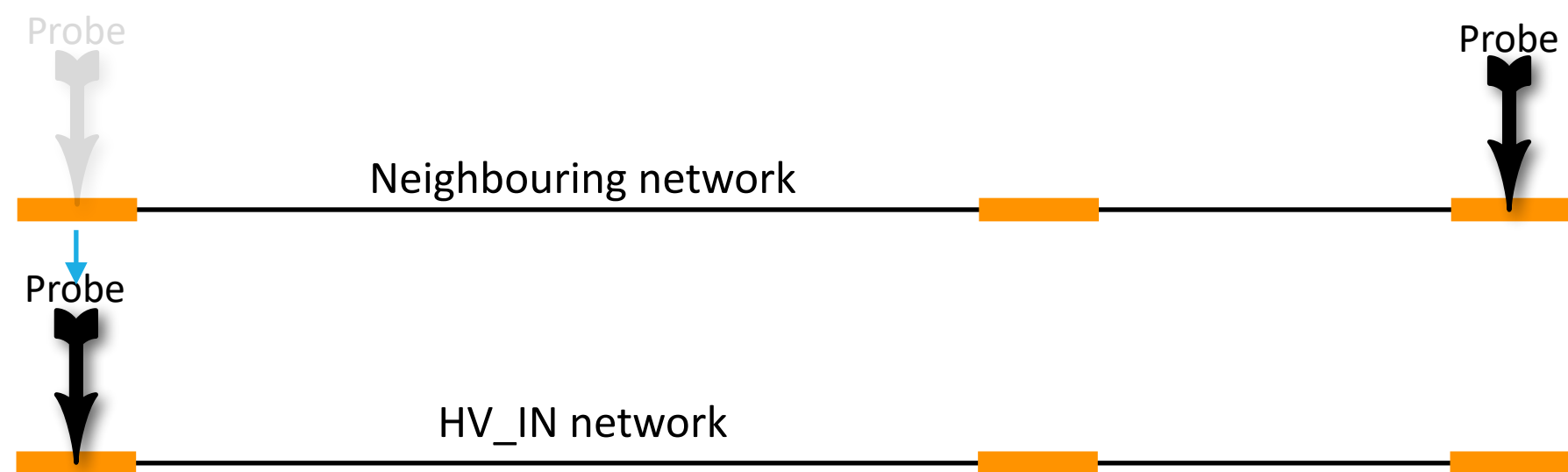
Primary line check (resistance)



Secondary line check (resistance)



HV measurement



Final configuration files for bare & co-cured tapes

- **Bare tapes:**

- 86 checks for short circuits
- 23 HV leakage tests
- 138/140 resistance measurements

Test time:

1 hour = 10 min loading & fiducial measurements + 50 min electrical tests

- **Co-cured (Skin) tapes:**

- 86 checks for short circuits
- 39 HV leakage tests
- 138/140 resistance measurements

Test time:

1 hour 15 minutes = 10 min loading & fiducial measurements + 1 hour 5 minutes electrical tests