

Investigating image quality achieved with different detector resolutions

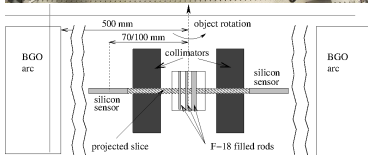
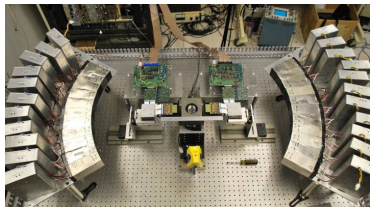
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September 12, 2013

Outline

- 1 Motivation
- 2 Extracting parameters
 - Extracting SNR
 - Extracting resolution
- 3 Results
 - Basic Ideas for Proofs/Implementation

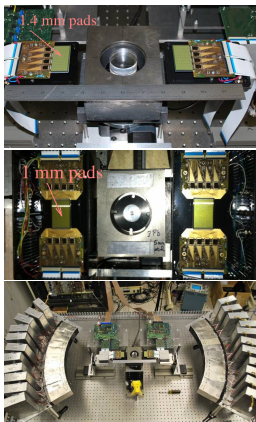
General setup description



Test setup at UofM:

- Dedicated BGO ring/
- New detectors inside the ring.
- Single slice collimation w/lead.
- Object rotation for full angular coverage.

List of setups



Setup list:

- Silicon w/ 1.4 mm pads (SetupID # 0).
- Silicon w/ 1 mm pads (SetupID # 2).
- Silicon remapped to 2.8 mm pads (SetupID # 100).
- Silicon remapped to 2 mm pads (SetupID # 102).

Possible combinations:

- Si + Si (0xf).
- Si + BGO (0xf0).
- BGO + BGO (0x100).

Goals

A lot of setups, a lot of combinations.

GOAL: To quantify improvements when using different setups.

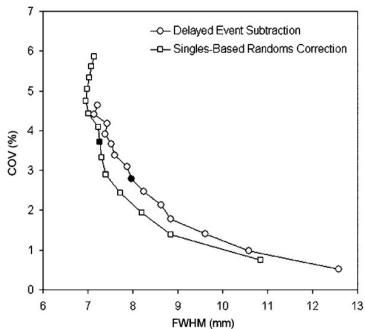
- Detectability (according to Cherry, Sorenson and Phelps):

$$CNR = |C_l| \cdot \sqrt{n_l} \cdot SNR \quad \text{and} \quad CNR \geq 4$$

CNR is contrast-to-noise ratio, C_l is lesion contrast, n_l number of pixels it spans, SNR is signal to noise ratio.

- SNR is a property of the readout, $|C_l|$ and $\sqrt{n_l}$ of the marker
- Trace SNR as a function of chosen setup, combination and reconstruction parameters.

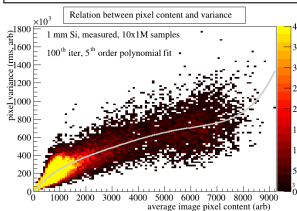
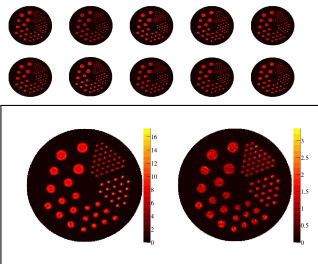
SNR and resolution are coupled



[Lodge, M. et al. Simultaneous measurement of noise and spatial resolution in PET phantom images. PMB 55(4) 2010: 1069–1081.]

- Noise/Covariance and resolution are coupled.
- For iterative method, iterations improve spatial resolution (and degrade noise).
- Relation is specific to a particular setup/combination
- **Wrong** to compare at fixed iteration, **correct** to compare at fixed resolution (or fixed covariance).

Estimating parameters: SNR



Estimating covariance:

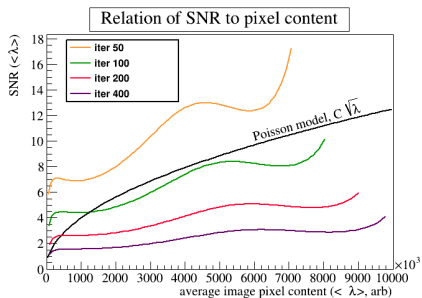
- Generate $N_s=10$ samples of $N_e=1M$ events from recorded/ simulated population sample.
- Produce average $\langle \lambda \rangle$ and covariance σ image

$$\langle \lambda \rangle_j = \frac{1}{N_s} \sum_{i=1}^{N_s} \lambda_j^i \quad \sigma_j^2 = \frac{1}{N_s} \sum_{i=1}^{N_s} (\lambda_j^i - \langle \lambda \rangle_j)^2$$

- Extract pixel-wise relation of σ to $\langle \lambda \rangle$.

$$SNR(\lambda) = \frac{\lambda}{\sigma(\lambda)}$$

Sidestep: SNR and Poisson

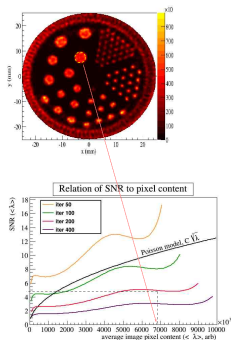


- For direct detection process

$$\text{SNR}(\lambda) = C\sqrt{\lambda}$$

C accounts for possible scaling of the image
- Pixels are coupled through Radon projection so SNR can be better or worse than pure Poisson process.
- For late iterations, SNR has little dependence on $\langle \lambda \rangle$.

Spatial variation of SNR.

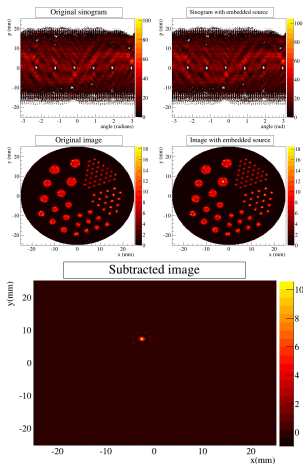


- Inscribe a circle with radius slightly smaller than rod radius.
- Determine average pixel content λ_r of the rod.
- SNR of that region is $\text{SNR}(\lambda_r)$.
- SNR will vary for different rod diameters (and in images in general as a function of the object shape).
- The same can be seen from Fischer information matrix and Cramer-Rao bound:

$$\sigma_j^2 \geq \mathbf{g}_j^T \mathbf{F}^{-1} \mathbf{g}_j \quad \mathbf{F} = \mathbf{M}^T \text{diag}[1/\lambda_j] \mathbf{M}$$

\mathbf{g}_j is mean bias gradient vector (similar to LIR), \mathbf{M} is the system matrix

Estimating resolution



- Possible through deconvolution of rod shapes (but not performed).
- Embed a (true) point source into data and reconstruct with the unperturbed data.

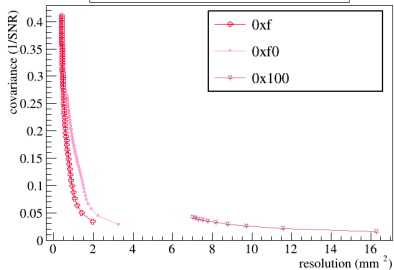
Point source is a minute perturbation of the data. Content of the source is 4 permil of the original data

- Subtract unperturbed image from the image with embedded source and perform fit to extract FWHM.
- FWHM area rather than diameter quoted (shape needn't be symmetric).

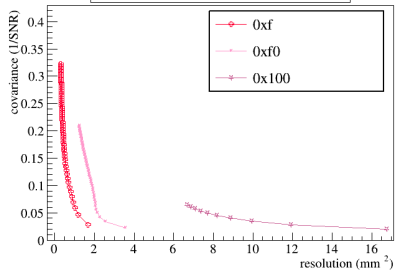
Measurements

For rod diameter 4.8 mm.

Covariance/resolution for setupID #0



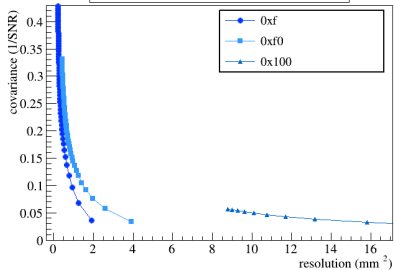
Covariance/resolution for setupID #2



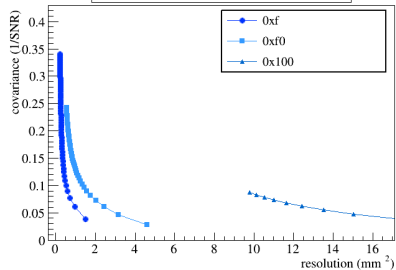
Measurements

For rod diameter 1.6 mm.

Covariance/resolution for setupID #0



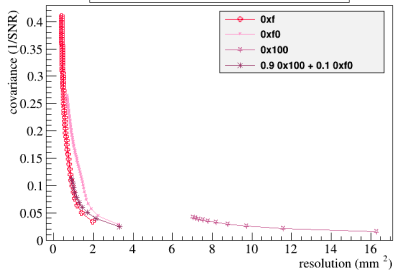
Covariance/resolution for setupID #2



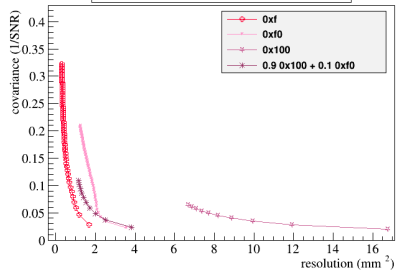
Measurements

For rod diameter 1.6 mm.

Covariance/resolution for setupID #0



Covariance/resolution for setupID #2



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Summary

- The **first main message** of your talk in one or two lines.
 - The **second main message** of your talk in one or two lines.
 - Perhaps a **third message**, but not more than that.
-
- Outlook
 - Something you haven't solved.
 - Something else you haven't solved.

For Further Reading I

-  A. Author.
Handbook of Everything.
Some Press, 1990.
-  S. Someone.
On this and that.
Journal of This and That, 2(1):50–100, 2000.